

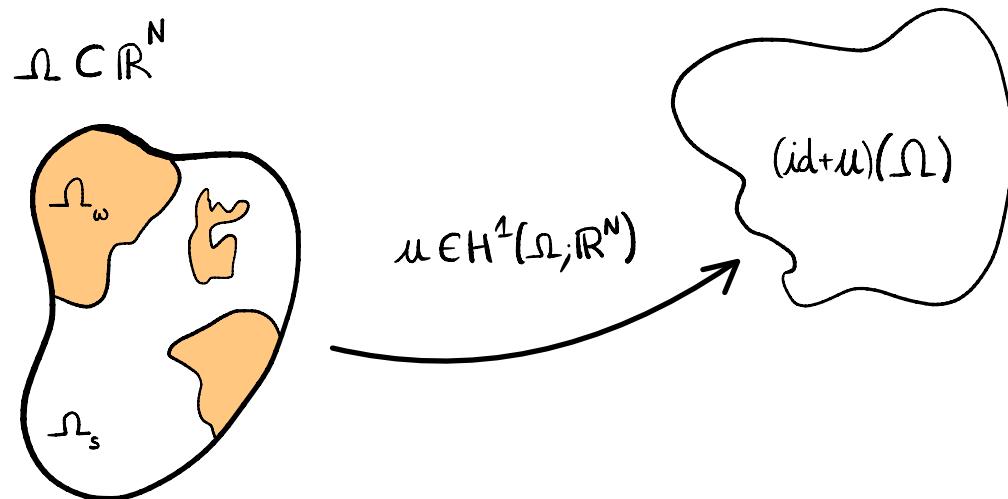
Can quasi-static evolutions of perfect plasticity be derived from brittle damage evolutions?

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General context of Brittle Damage



[Francfort-Marigo, 1993]

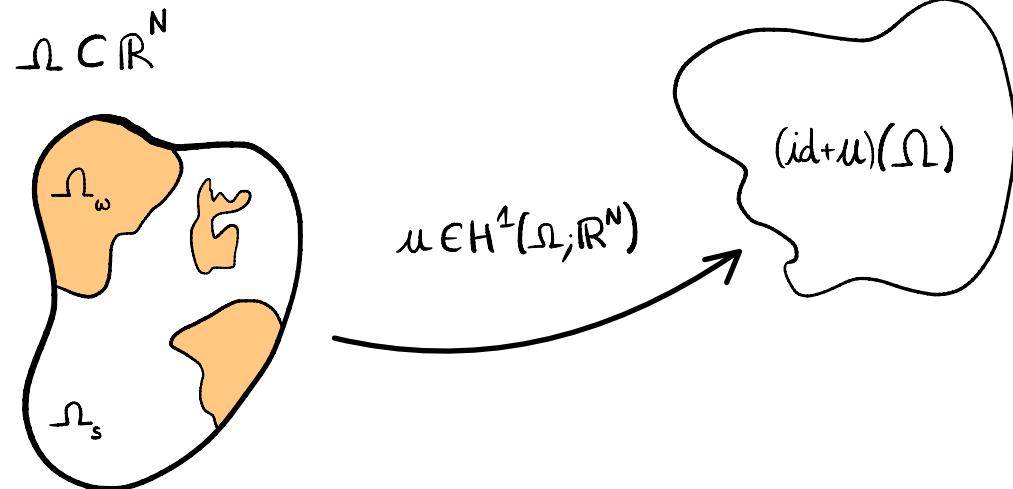
$$A_w \leq A_s$$

$$\chi = \frac{1}{\Omega} \int_{\Omega_w} \in L^\infty(\Omega; \{0, 1\})$$

$$A_\chi = \chi A_w + (1-\chi) A_s$$

$$\mathcal{E}(u, \chi) = \frac{1}{2} \int_{\Omega} A_\chi \epsilon u : \epsilon u \, dx + K \int_{\Omega} \chi \, dx$$

Concentration and elastic degeneracy of weak material



Scaling Law
[Babadjian-Iurlano-Rindler]

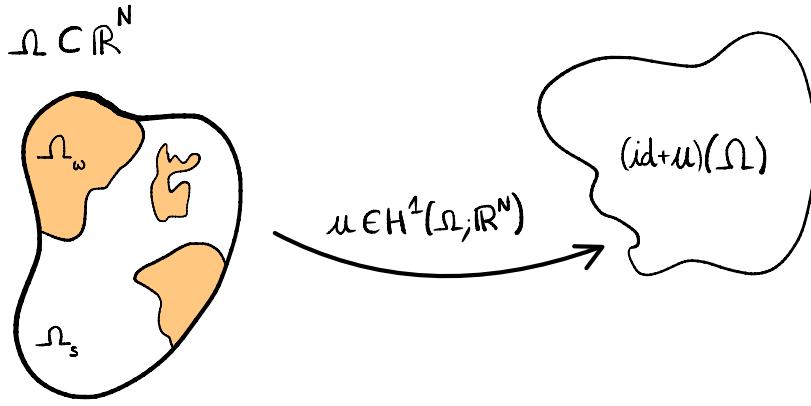
$$\varepsilon A_\omega \leq A_s$$

$$\chi = \frac{1}{\Omega_\omega} \in L^\infty(\Omega_\omega; \{0, 1\})$$

$$A_\chi^\varepsilon = \chi \varepsilon A_\omega + (1-\chi) A_s$$

$$\mathcal{E}_\varepsilon(u, \chi) = \frac{1}{2} \int_{\Omega} A_\chi^\varepsilon e u : e u \, dx + K \int_{\Omega} \chi \, dx$$

Concentration and elastic degeneracy of weak material



$$\chi = \frac{1}{\Omega_\omega} \in L^\infty(\Omega_\omega, \{0, 1\})$$

$$A_\chi^\varepsilon = \chi \varepsilon A_\omega + (1-\chi) A_s$$

Scaling Law
[Babadjian-Iurlano-Rindler]

$$\mathcal{E}_\varepsilon(u, \chi) = \frac{1}{2} \int_{\Omega} A_\chi^\varepsilon e u : e u \, dx + \frac{K}{\varepsilon} \int_{\Omega} \chi \, dx$$

$$\begin{matrix} \Gamma_{-CV} \\ L^1 \times L^1 \\ \varepsilon \downarrow 0 \end{matrix}$$

(Hencky)
perfect plasticity

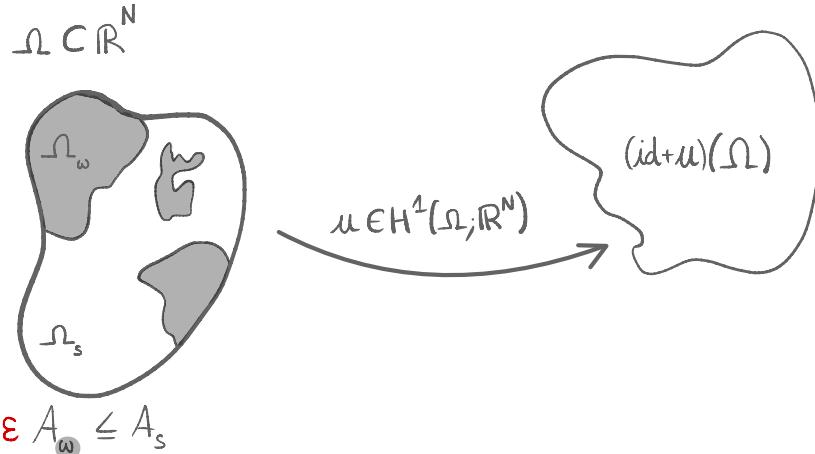
$$u \in BD(\Omega) \mapsto \int_{\Omega} \frac{1}{2} A_s e : e \, dx + \int_{\Omega} I_K^* \left(\frac{dp}{d|p|} \right) d|p| \quad \text{if } \chi = 0 \text{ a.e.}$$

where $E_u = e + p$
 elastic strain \rightarrow plastic (permanent) strain

closed convex set of plasticity

Concentration and elastic degeneracy of weak material

Scaling Law
[Babadjian-Iurlano-Rindler]



$$\chi = \frac{1}{\varepsilon} \int_{\omega} \epsilon \in L^\infty(\omega, \{0, 1\})$$

$$A_\chi^\varepsilon = \chi \varepsilon A_\omega + (1-\chi) A_s$$

(Hencky)
perfect plasticity

$$\begin{aligned} \mathcal{E}(u, \chi) &= \frac{1}{2} \int_{\Omega} A_\chi^\varepsilon e : e u \, dx + \frac{\kappa}{\varepsilon} \int_{\Omega} \chi \, dx \\ \text{P-cv} \quad \varepsilon \searrow 0 & \quad u \in BD(\Omega) \mapsto \int_{\Omega} \frac{1}{2} A_s e : e \, dx + \int_{\Omega} I_K^* \left(\frac{dp}{d|p|} \right) d|p| \quad \text{if } \chi = 0 \text{ a.e.} \end{aligned}$$

What about Evolution models?

Quasi-static Brittle Damage evolution
[Francfort-Garroni]

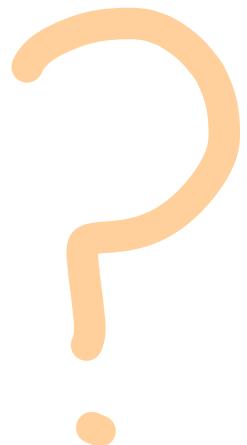
coupled with

Scaling Law
[BIR]

$$\varepsilon \searrow 0$$

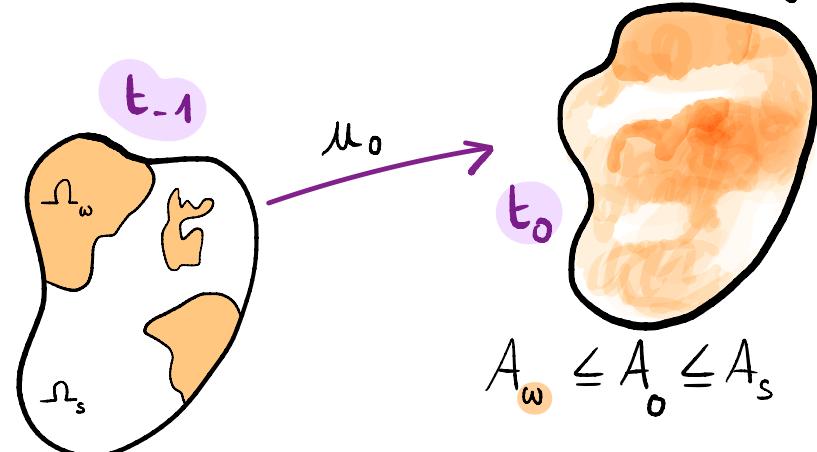
QS perfect plasticity evolution [Dal Maso-DeSimone-Mora]

$$(u, e, \mu, \sigma)$$



QS Brittle Damage Evolution [F-G]

$0 = t_0 \quad t_1 \quad \dots \quad t_i \quad \dots \quad t_m = T$



$$\mathcal{E}_0 = \inf_{u, X} \frac{1}{2} \int_{\Omega} A_X e_u : e_u \, dx + K \int_{\Omega} X \, dx \stackrel{\text{H-S}}{=} \min_{\substack{u, \Theta \\ A \in \mathcal{G}_{1-\Theta}(A_\omega, A_s)}} \int_{\Omega} \left(\frac{1}{2} A e_u : e_u + K(1-\Theta) \right) \, dx$$

$$A_\omega \leq A_s$$

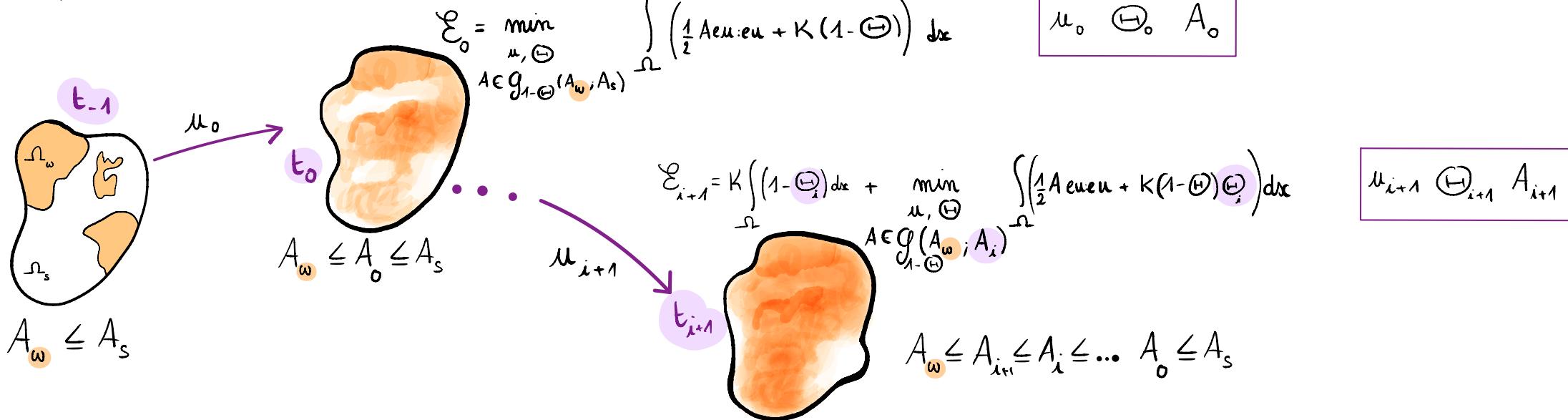
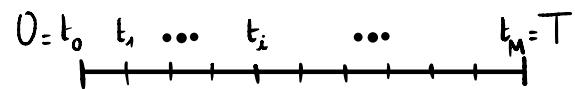
$$\mathcal{E}_{i+1} = K \int_{\Omega} (1-\Theta_i) \, dx + \inf_{u, X} \int_{\Omega} \left(\frac{1}{2} (X A_\omega + (1-X) A_i) e_u : e_u + K X \Theta_i \right) \, dx$$



$$\stackrel{\text{H-S}}{=} \min_{\substack{u, \Theta \\ A \in \mathcal{G}_{1-\Theta}(A_\omega, A_i)}} \int_{\Omega} \left(\frac{1}{2} A e_u : e_u + K(1-\Theta) \Theta_i \right) \, dx$$

$$A_\omega \leq A_{i+1} \leq A_i \leq \dots \leq A_0 \leq A_s$$

QS Brittle Damage Evolution [F-G]



Piecewise constant in time
interpolation

+

"Helly"

$$\sup_i |t_{i+1} - t_i| \xrightarrow[M]{} 0$$

$$u : [0, T] \rightarrow H^1(\Omega)$$

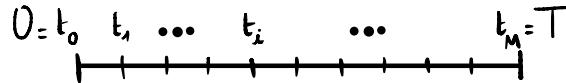
$$\Theta : [0, T] \rightarrow L^\infty(\Omega, [0, 1])$$

$$A : [0, T] \rightarrow L^\infty(\Omega)$$

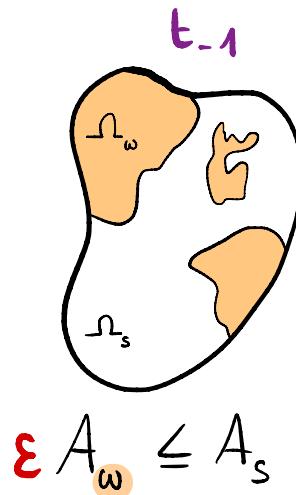
in time

$$\mathcal{E}(t) = \frac{1}{2} \int_{\Omega} A(t) \epsilon u(t) : \epsilon u(t) dx + K \int_{\Omega} (1 - \Theta(t)) dx$$

QS Brittle Damage Evolution [F-G] + Scaling Law [BIR]

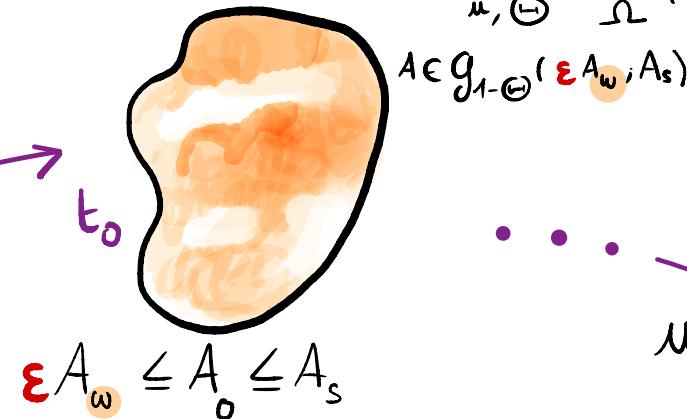


$\varepsilon > 0$



$$\mathcal{E}_0^\varepsilon = \min_{u, \Theta} \int_{\Omega} \left(\frac{1}{2} A e u \cdot e u + \frac{K(1-\Theta)}{\varepsilon} \right) dx$$

u_0^ε	Θ_0^ε	A_0^ε
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...

$$\varepsilon A_w \leq A_{t_{i+1}}^\varepsilon \leq A_i^\varepsilon \leq \dots A_0^\varepsilon \leq A_s$$



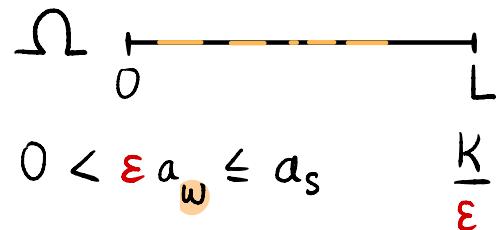
$$\mathcal{E}_{i+1}^\varepsilon = \frac{K}{\varepsilon} \int_{\Omega} (1 - \Theta_i^\varepsilon) dx + \min_{u, \Theta} \int_{\Omega} \left(\frac{1}{2} A e u \cdot e u + \frac{K(1-\Theta)}{\varepsilon} \Theta_i^\varepsilon \right) dx$$

$$A \in g_{1-\Theta_i^\varepsilon}(\varepsilon A_w, A_i^\varepsilon)$$

u_{i+1}^ε	Θ_{i+1}^ε	A_{i+1}^ε
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$T > 0$

QS Brittle Damage Evolution [F-G] + Scaling Law [BIR] in 1D



Dirichlet boundary condition:

$$\omega \in AC([0, T]; H^1(\mathbb{R}))$$

$$\begin{aligned}
 & [F-G] \quad u_\varepsilon : [0, T] \rightarrow H^1((0, L)) \\
 & \rightarrow \quad \Theta_\varepsilon : [0, T] \rightarrow L^\infty((0, L); [0, 1]) \\
 & a_\varepsilon = \left(\frac{1 - \Theta_\varepsilon}{\varepsilon a_\omega} + \frac{\Theta_\varepsilon}{a_s} \right)^{-1} : [0, T] \rightarrow L^\infty((0, L))
 \end{aligned}
 \quad \left. \begin{array}{l} \text{in time} \\ \downarrow \end{array} \right\}$$

Dirichlet boundary condition:

$$u_\varepsilon^{(t)}|_{\{0, L\}} = \omega^{(t)}|_{\{0, L\}}$$

One-sided minimality: $\forall v \in \omega(t) + H'_o((0, L)), \forall \theta \in L^\infty((0, L); [0, 1]),$

$$\frac{1}{2} \int_0^L a_\varepsilon(t) |u'_\varepsilon(t)|^2 dx \leq \frac{1}{2} \int_0^L \left(\frac{1 - \theta}{a_\varepsilon(t)} + \frac{\theta}{\varepsilon a_\omega} \right)^{-1} |v'|^2 dx + \frac{K}{\varepsilon} \int_0^L \theta \Theta_\varepsilon(t) dx$$

$$\text{Energy balance: } \mathcal{E}_\varepsilon(t) := \frac{1}{2} \int_0^L a_\varepsilon(t) |u'_\varepsilon(t)|^2 dx + \frac{K}{\varepsilon} \int_0^L (1 - \Theta_\varepsilon(t)) dx = \mathcal{E}_\varepsilon(0) + \int_0^t \int_0^L a_\varepsilon(s) u'_\varepsilon(s) (\dot{\omega})'(s) dx ds$$

? Quid when $\varepsilon \downarrow 0$?

$T > 0$

QS Brittle Damage Evolution [F-G] + Scaling Law [BIR] in 1D

$$\Omega \quad 0 \quad L$$

$0 < \varepsilon a_\omega \leq a_s \quad \frac{K}{\varepsilon}$

Dirichlet boundary condition:
 $\omega \in AC([0, T]; H^1(\mathbb{R}))$

[F-G]

$$u_\varepsilon : [0, T] \rightarrow H^1((0, L))$$

$$\rightarrow \Theta_\varepsilon : [0, T] \rightarrow L^\infty((0, L); [0, 1])$$

$$a_\varepsilon = \left(\frac{1 - \Theta_\varepsilon}{\varepsilon a_\omega} + \frac{\Theta_\varepsilon}{a_s} \right)^{-1} : [0, T] \rightarrow L^\infty((0, L)) \quad \text{in time}$$

Dirichlet boundary condition:

$$u_\varepsilon(t)|_{\{0, L\}} = \omega(t)|_{\{0, L\}}$$

One-sided minimality: $\forall v \in \omega(t) + H_0^1((0, L))$, $\frac{1}{2} \int_0^L a_\varepsilon(t) |u'_\varepsilon(t)|^2 dx \leq \frac{1}{2} \int_0^L a_\varepsilon(t) |v'|^2 dx$

$\rightsquigarrow \zeta_\varepsilon := a_\varepsilon u'_\varepsilon : [0, T] \rightarrow \mathbb{R}$ homogeneous in space $(\zeta_\varepsilon(t)' = 0 \text{ in } H^1((0, L)), \forall t \in [0, T])$

$$u'_\varepsilon = \zeta_\varepsilon \left(\frac{1 - \Theta_\varepsilon}{\varepsilon a_\omega} + \frac{\Theta_\varepsilon}{a_s} \right)$$

$$\zeta_\varepsilon = \frac{e_\varepsilon}{a_s} \Theta_\varepsilon$$

$$P_\varepsilon = \frac{\zeta_\varepsilon}{a_\omega} \frac{1 - \Theta_\varepsilon}{\varepsilon}$$

Energy balance: $\mathcal{E}_\varepsilon(t) := \frac{1}{2} \int_0^L a_\varepsilon(t) |u'_\varepsilon(t)|^2 dx + \frac{K}{\varepsilon} \int_0^L (1 - \Theta_\varepsilon(t)) dx = \mathcal{E}_\varepsilon(0) + \iint_0^t \int_0^L a_\varepsilon(s) u'_\varepsilon(s) (\dot{\zeta}_\varepsilon)(s) dx ds$

$T > 0$

Dirichlet boundary condition:
 $\omega \in AC([0, T]; H^1(\mathbb{R}))$

QS Brittle Damage Evolution [F-G] + Scaling Law [BIR] in 1D

[F-G] $u_\varepsilon : [0, T] \rightarrow H^1((0, L))$
 $\rightarrow \Theta_\varepsilon : [0, T] \rightarrow L^\infty((0, L); [0, 1])$
 $a_\varepsilon = \left(\frac{1 - \Theta_\varepsilon}{\varepsilon a_w} + \frac{\Theta_\varepsilon}{a_s} \right)^{-1} : [0, T] \rightarrow L^\infty((0, L))$

$\Theta_\varepsilon(t) := \frac{1}{2} \int_0^L a_\varepsilon(t) |u'_\varepsilon(t)|^2 dx + \frac{K}{\varepsilon} \int_0^L (1 - \Theta_\varepsilon(t)) dx$

$g_\varepsilon := a_\varepsilon u'_\varepsilon : [0, T] \rightarrow \mathbb{R}$
 $u'_\varepsilon = g_\varepsilon \left(\frac{1 - \Theta_\varepsilon}{\varepsilon a_w} + \frac{\Theta_\varepsilon}{a_s} \right)$

↓ in time

One-sided minimality:

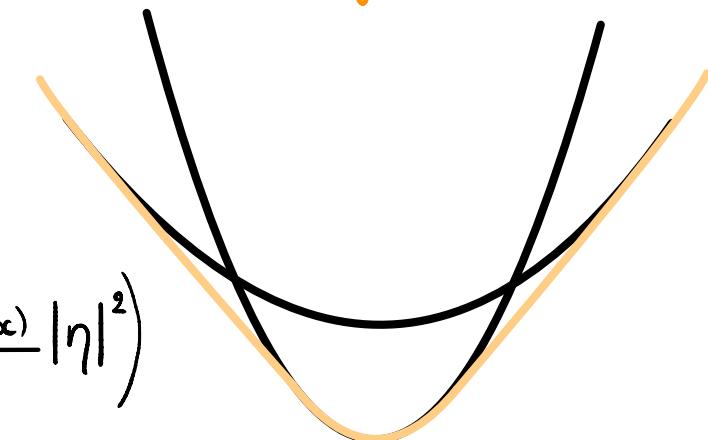
Aumann
Selection
Criterion

$$\frac{1}{2} a_\varepsilon(t) |u'_\varepsilon(t)|^2 \stackrel{\text{a.e. in } (0, L)}{=} \min_{\theta \in [0, 1]} \left\{ \frac{K \Theta_\varepsilon(t)}{\varepsilon} \theta + \frac{1}{2} \left(\frac{\theta}{\varepsilon a_w} + \frac{1 - \theta}{a_\varepsilon(t)} \right)^{-1} |u'_\varepsilon(t)|^2 \right\}$$

$$= \text{Convex } W_\varepsilon^t(x, u'_\varepsilon(t))$$

explicit formula

$$W_\varepsilon^t(x, \eta) := \min \left(\frac{K \Theta_\varepsilon(t, x)}{\varepsilon} + \frac{\varepsilon a_w}{2} |\eta|^2, \frac{a_\varepsilon(t, x)}{2} |\eta|^2 \right)$$



$T > 0$

Compactness

$$\Omega \xrightarrow[0]{\quad} \xleftarrow[L]{\quad}$$

$$0 < \varepsilon a_\omega \leq a_s \quad \frac{K}{\varepsilon}$$

Dirichlet boundary condition:
 $\omega \in AC([0, T]; H^1(\mathbb{R}))$

[F-G] $\begin{aligned} u_\varepsilon : [0, T] &\rightarrow H^1((0, L)) \\ \Theta_\varepsilon : [0, T] &\rightarrow L^\infty((0, L); [0, 1]) \\ a_\varepsilon = \left(\frac{1 - \Theta_\varepsilon}{\varepsilon a_\omega} + \frac{\Theta_\varepsilon}{a_s} \right)^{-1} : [0, T] &\rightarrow L^\infty((0, L)) \end{aligned}$

in time

$$\mathcal{E}_\varepsilon(t) := \frac{1}{2} \int_0^L a_\varepsilon(t) |u'_\varepsilon(t)|^2 dx + \frac{K}{\varepsilon} \int_0^L (1 - \Theta_\varepsilon(t)) dx$$

$$\delta_\varepsilon := a_\varepsilon u'_\varepsilon : [0, T] \rightarrow \mathbb{R}$$

$$u'_\varepsilon = \delta_\varepsilon \left(\frac{1 - \Theta_\varepsilon}{\varepsilon a_\omega} + \frac{\Theta_\varepsilon}{a_s} \right)$$

Uniform bounds:

$$\sup_{\substack{t \in [0, T] \\ \varepsilon > 0}} \mathcal{E}_\varepsilon(t) < +\infty$$

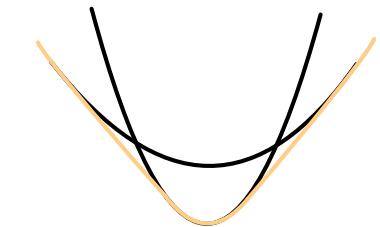
$$\Rightarrow \sup_{\substack{t \in [0, T] \\ \varepsilon > 0}} \left| \mu_\varepsilon(t) := \frac{1 - \Theta_\varepsilon(t)}{\varepsilon} \mathbb{1}_{(0, L)} \right| ([0, L]) < +\infty \Rightarrow \Theta_\varepsilon(t) \xrightarrow[\varepsilon \searrow 0]{L^1((0, L))} 1 \quad \forall t \in [0, T]$$

in time & Helly

$$\sup_{\varepsilon > 0} \| \delta_\varepsilon \|_{L^\infty([0, T])} < +\infty$$

$$\sup_{\substack{t \in [0, T] \\ \varepsilon > 0}} \| u_\varepsilon(t) \|_{BV((0, L))} < +\infty$$

& One-sided minimality: $\frac{1}{2} a_\varepsilon(t) |u'_\varepsilon(t)|^2 = \text{Conv}_W_\varepsilon^t(x, u'_\varepsilon(t))$



Compactness

$$\mathcal{E}_\varepsilon(t) := \frac{1}{2} \int_0^L a_\varepsilon(t) |u'_\varepsilon(t)|^2 dx + \frac{k}{\varepsilon} \int_0^L (1 - \Theta_\varepsilon(t)) dx$$

$$\sigma_\varepsilon := a_\varepsilon u'_\varepsilon : [0, T] \rightarrow \mathbb{R}$$

$$u'_\varepsilon = \sigma_\varepsilon \left(\frac{1 - \Theta_\varepsilon}{\varepsilon a_w} + \frac{\Theta_\varepsilon}{a_s} \right)$$

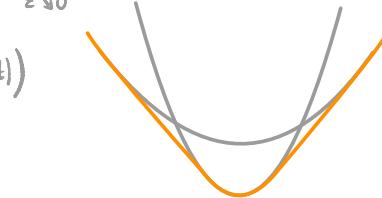
Uniform bounds:

$$\sup_{t, \varepsilon} \mathcal{E}_\varepsilon(t) < +\infty$$

↑ in time & Helly

$$\sup_{t, \varepsilon} \left| \mu_\varepsilon(t) := \frac{1 - \Theta_\varepsilon(t)}{\varepsilon} \mathbb{1}_{(0, L)} \right| ([0, L]) < +\infty \Rightarrow \Theta_\varepsilon(t) \xrightarrow[\varepsilon \searrow 0]{L^1((0, L))} 1 \quad \forall t \in [0, T]$$

& One-sided minimality: $\frac{1}{2} a_\varepsilon(t) |u'_\varepsilon(t)|^2 = \text{Conv} W_\varepsilon^t(x, u'_\varepsilon(t))$



Subsequence independent of time

⇒ ∀ t ∈ [0, T],

$$\sigma_\varepsilon(t) \xrightarrow[\varepsilon]{\mathbb{R}} \sigma(t) \in K := [-\sqrt{2 R a_0}, \sqrt{2 R a_0}]$$

$$\mu_\varepsilon(t) = \frac{1 - \Theta_\varepsilon(t)}{\varepsilon} \mathbb{1}_{(0, L)} \xrightarrow[\varepsilon]{\mathcal{J}_0^*([0, L])} \mu(t) \quad \text{↑ in time}$$

$$p_\varepsilon(t) = \frac{\sigma_\varepsilon(t)}{a_w} \mu_\varepsilon(t) \xrightarrow[\varepsilon]{\mathcal{J}_0^*([0, L])} p(t) = \frac{\sigma(t)}{a_w} \mu(t)$$

$$e_\varepsilon(t) = \frac{\sigma_\varepsilon(t)}{a_s} \Theta_\varepsilon(t) \xrightarrow[\varepsilon]{L^2((0, L))} e(t) = \frac{\sigma(t)}{a_s}$$

$$Du_\varepsilon(t) = e_\varepsilon(t) + p_\varepsilon(t) \mathbb{1}_{(0, L)} \xrightarrow[\varepsilon]{\mathcal{J}_0^*((0, L))} e(t) + p(t) \mathbb{1}_{(0, L)} = \sigma(t) \left(\frac{\mu(t)}{a_w} \mathbb{1}_{(0, L)} + \frac{L^1}{a_s} \mathbb{1}_{(0, L)} \right)$$

Compactness

$$\xi := a_\varepsilon \mu'_\varepsilon : [0, T] \rightarrow \mathbb{R}$$

$$\mu'_\varepsilon = \xi \left(\frac{1 - \Theta_\varepsilon}{\varepsilon a_w} + \frac{\Theta_\varepsilon}{a_s} \right)$$

Subsequence
independent
of time

$$\Rightarrow \forall t \in [0, T],$$

$$\xi_\varepsilon(t) \xrightarrow[\varepsilon]{\mathcal{R}} \xi(t) \in K := [-\sqrt{2K a_0}, \sqrt{2K a_0}]$$

$$p_\varepsilon(t) = \frac{1 - \Theta_\varepsilon(t)}{\varepsilon} \mathbb{1}_{(0, L)} \xrightarrow[\varepsilon]{\mathcal{J}_0^*([0, L])} p(t) \quad \nearrow \text{in time}$$

$$P_\varepsilon(t) = \frac{\xi_\varepsilon(t)}{a_w} p_\varepsilon(t) \xrightarrow[\varepsilon]{\mathcal{J}_0^*([0, L])} P(t) = \frac{\xi(t)}{a_w} p(t)$$

$$e_\varepsilon(t) = \frac{\xi_\varepsilon(t)}{a_s} \Theta_\varepsilon(t) \xrightarrow[\varepsilon]{\mathbb{L}^2([0, L])} e(t) = \frac{\xi(t)}{a_s}$$

$$Du_\varepsilon(t) = e_\varepsilon(t) + P_\varepsilon(t) \Big|_{(0, L)} \xrightarrow[\varepsilon]{\mathcal{J}_0^*([0, L])} e(t) + P(t) \Big|_{(0, L)}$$

&

$$\sup_{\substack{t \in [0, T] \\ \varepsilon > 0}} \| \mu_\varepsilon(t) \|_{BV([0, L])} < +\infty$$

Along the
same
subsequence

$$\Rightarrow \forall t \in [0, T], \quad \mu_\varepsilon(t) \xrightarrow[\varepsilon]{BV([0, L])} \mu(t)$$

Good candidates

Uniform bounds

&

O-S minimality

&

Helly

$$\sigma_\varepsilon(t)$$

$$e_\varepsilon(t)$$

$$\nu_\varepsilon(t)$$

$$p_\varepsilon(t)$$

$$u_\varepsilon(t)$$

Subsequence independent of time

$$\xrightarrow{\mathbb{R}}$$

$$\xrightarrow{L^2}$$

$$\xrightarrow{\mathcal{M}_b([0,L])}$$

$$\xrightarrow{\mathcal{M}_b([0,L])}$$

$$\xrightarrow{BV([0,L])}$$

$$\sigma(t)$$

$$e(t) = \frac{\sigma(t)}{a_s}$$

$$\nu(t)$$

$$p(t)$$

$$u(t)$$

Good candidates

$(u, e, p, \nu, \sigma) : [0, T] \rightarrow BV(0, L) \times \mathbb{R} \times \mathcal{M}([0, L]) \times \mathcal{M}([0, L]) \times K$ is absolutely continuous on $[0, T]$

Additive decomposition

$$Du(t) = e(t) \mathcal{L}_{[0, L]}^1 + p(t) \mathbf{1}_{[0, L]} \quad \text{in } \mathcal{M}((0, L))$$

Relaxed Dirichlet boundary condition

$$\nu(t)_{\{0, L\}} = (w(t) - u(t)) v \quad H_{[0, L]}^0 \quad \text{in } \mathcal{M}(\{0, L\})$$

Constitutive Equation

$$\sigma(t) = a_s e(t)$$

Equilibrium Equation

$$\sigma'(t) = 0 \quad \text{in } H^{-1}((0, L))$$

Stress constraint

$$\sigma(t) \in K, \text{ ie: } |\sigma(t)| \leq \sqrt{2 K a_w}$$

Energy Balance

$$\begin{aligned} & \text{?} \quad \frac{1}{2} a_s e(t)^2 + \sqrt{2 K a_w} \mathcal{V}(p; 0, t) \quad \text{?} \\ &= \frac{1}{2} a_s e(0)^2 + \int_0^t \int_0^L \sigma(s) (\dot{w})'(s) \, dx \, ds \\ & \mathcal{V}(p; 0, t) = \sup \left\{ \sum_{i=1}^m |p(t_i) - p(t_{i-1})| ([0, L]), \quad 0 = t_0 < \dots < t_m = t, \quad m \in \mathbb{N}^* \right\} \end{aligned}$$

Good candidates

Uniform bounds

O-S minimality

$$\sigma_\varepsilon(t) \quad e_\varepsilon(t) \quad p_\varepsilon(t) \quad \mu_\varepsilon(t) \quad u_\varepsilon(t)$$

Helly

Subsequence independent of time

$$\varepsilon \downarrow 0$$

Good candidates

$$\sigma(t) \quad e(t) = \frac{\sigma(t)}{a_s} \quad p(t) \quad \mu(t) \quad u(t)$$

$(u, e, p, \mu, \sigma) : [0, T] \rightarrow BV(0, L) \times \mathbb{R} \times \mathcal{M}([0, L]) \times \mathcal{M}([0, L]) \times K$ is absolutely continuous on $[0, T]$

Additive decomposition

$$Du(t) = e(t) \mathcal{L}_{[0, L]}^1 + p(t) \mathbf{1}_{[0, L]} \quad \text{in } \mathcal{M}((0, L))$$

Relaxed Dirichlet boundary condition

$$p(t)_{|_{\{0, L\}}} = (w(t) - u(t)) v \quad H_{[0, L]}^0 \quad \text{in } \mathcal{M}(\{0, L\})$$

Constitutive Equation

$$\sigma(t) = a_s e(t)$$

Equilibrium Equation

$$\sigma'(t) = 0 \quad \text{in } H^{-1}((0, L))$$

Stress constraint

$$\sigma(t) \in K, \text{ i.e.: } |\sigma(t)| \leq \sqrt{2 K a_w}$$

Energy Balance

?

$$\frac{L}{2} a_s e(t)^2 + \sqrt{2 K a_w} \mathcal{V}(p; 0, t) \geq \frac{L}{2} a_s e(0)^2 + \int_0^t \int_0^L \sigma(s) (\dot{\omega})'(s) dx ds$$

$$\mathcal{V}(p; 0, t) = \sup \left\{ \sum_{i=1}^n |p(t_i) - p(t_{i-1})| ([0, L]), \quad 0 = t_0 < \dots < t_n = t, \quad n \in \mathbb{N}^* \right\}$$

Energy Balance?

Uniform bounds
O-S minimality
Helly

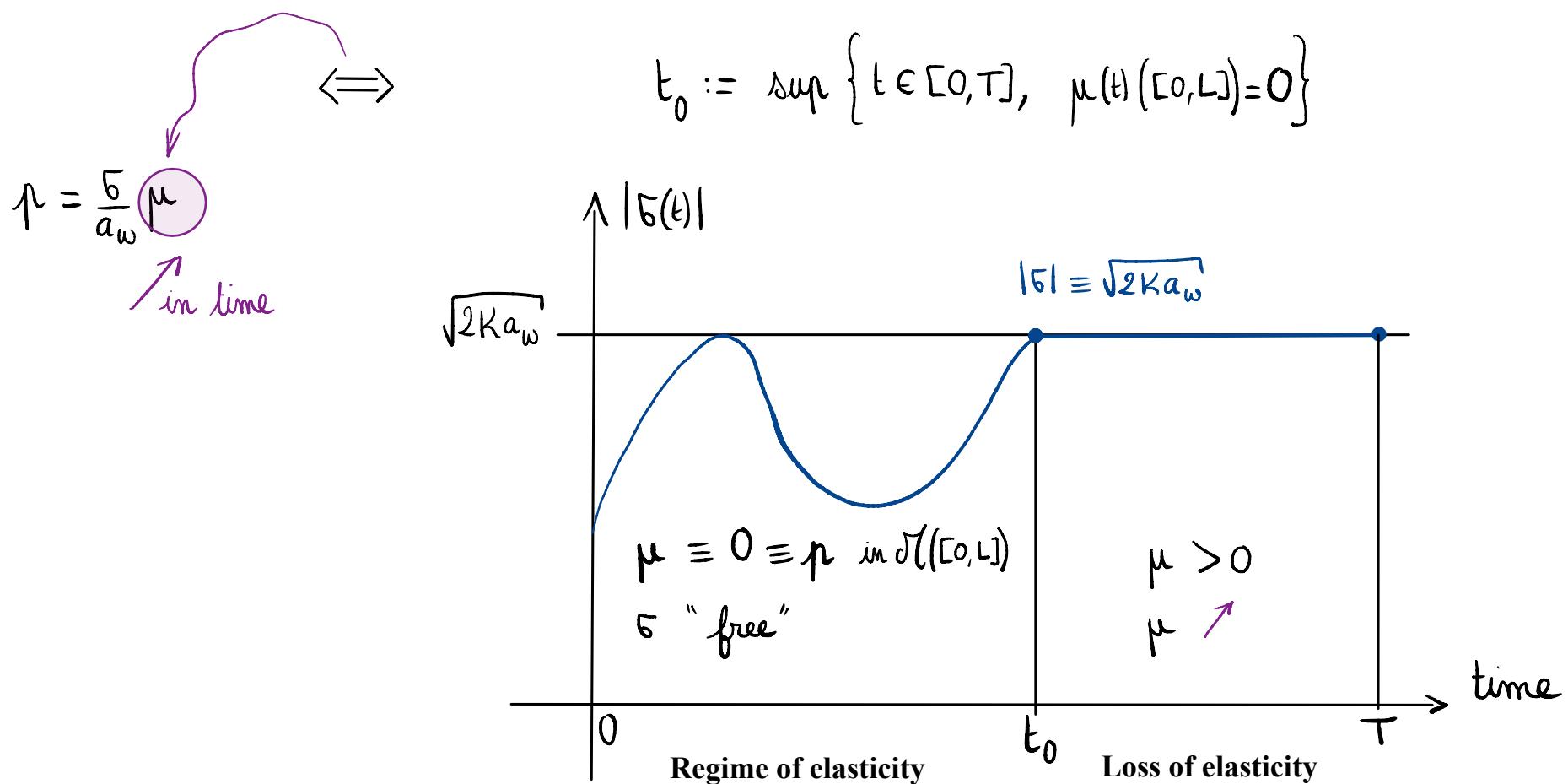
Subsequence
independent
of time
 $\varepsilon \downarrow 0$

Good candidates
 $\sigma(t)$ $e(t) = \frac{\sigma(t)}{a_s}$ $\mu(t)$ $p(t)$ $u(t)$

$(u, e, p, \sigma) : [0, T] \rightarrow BV(0, L) \times \mathbb{R} \times \mathcal{G}([0, L]) \times K$
 absolutely continuous
on $[0, T]$

Additive decomposition
Relaxed Dirichlet boundary condition
Constitutive Equation
Equilibrium Equation
Stress constraint

Energy Balance \iff **Flow Rule:** $\sigma(t) \dot{p}(t)([0, L]) = \sqrt{2K\omega} |\dot{p}(t)|([0, L])$ for \mathcal{L}^1 -a.e. $t \in [0, T]$



Uniform bounds
O-S minimality

Subsequence
independent
of time
 $\varepsilon \downarrow 0$

Helly

Good candidates
 $\sigma(t), e(t), p(t), \rho(t), u(t)$

Energy Balance?

$$(u, e, p, \sigma) : [0, T] \rightarrow BV(0, L) \times \mathbb{R} \times \mathcal{D}([0, L]) \times K$$

absolutely continuous
on $[0, T]$

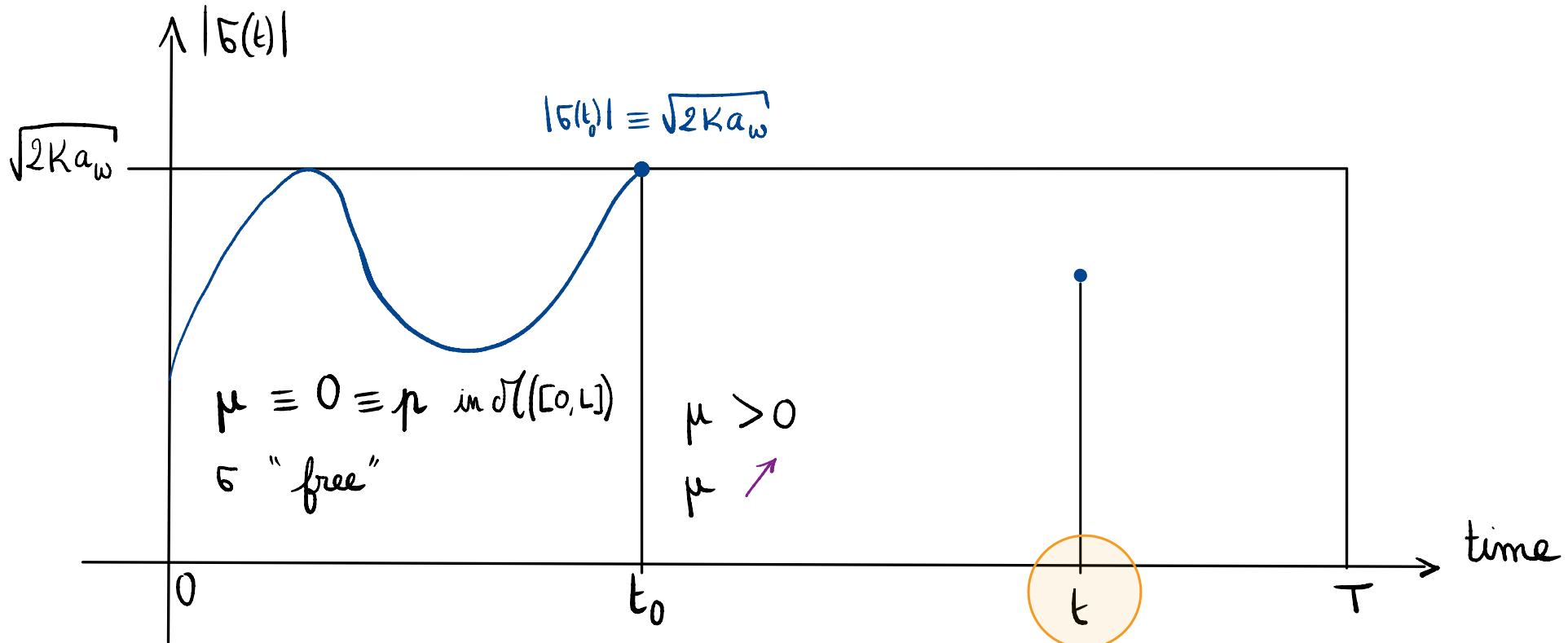
- ✓
Additive decomposition
Relaxed Dirichlet boundary condition
Constitutive Equation
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Stress constraint

$$\rho = \frac{5}{a_w} \mu$$

$$t_0 := \sup \left\{ t \in [0, T], \mu(t)([0, L]) = 0 \right\}$$

Assume

$$\exists t > t_0, |\sigma(t)| < \sqrt{2K a_w}$$



Uniform bounds
O-S minimality

Subsequence
independent
of time
 $\varepsilon \downarrow 0$

Good candidates

$$\sigma(t) \quad e(t) \quad p(t) \quad \mu(t) \quad u(t)$$

Energy Balance?

$$(\mu, e, p, \dot{\sigma}): [0, T] \rightarrow BV(0, L) \times \mathbb{R} \times \mathcal{D}([0, L]) \times K$$

Additive decomposition

Relaxed Dirichlet boundary condition

Constitutive Equation

Equilibrium Equation

Stress constraint

$$t_0 := \sup \left\{ t \in [0, T], \mu(t)([0, L]) = 0 \right\}$$

$$\mu = \frac{5}{a_w} \mu$$

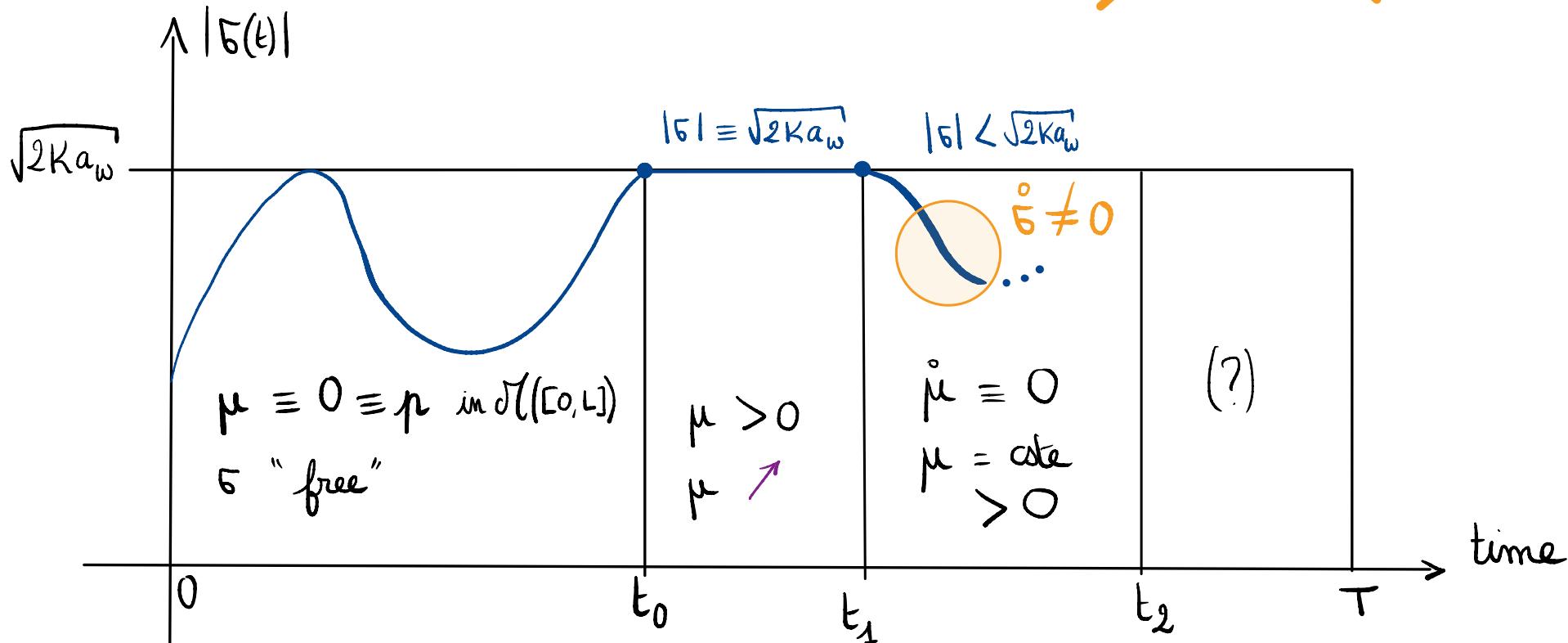
Assume

$$\exists t > t_0, |\sigma(t)| < \sqrt{2K a_w}$$



Flow Rule:

$$\sigma(t) \quad \dot{\mu}(t)([0, L]) = \sqrt{2K a_w} \quad |\dot{\mu}(t)|([0, L])$$



Uniform bounds
O-S minimality
Helly

Subsequence
independent
of time
 $\varepsilon \downarrow 0$

Good candidates

$$\sigma(t) \quad e(t) \quad \mu(t) \quad p(t) \quad u(t)$$

Energy Balance?

$$(u, e, \mu, \sigma) : [0, T] \rightarrow BV(0, L) \times \mathbb{R} \times \mathcal{D}([0, L]) \times K$$

Additive decomposition

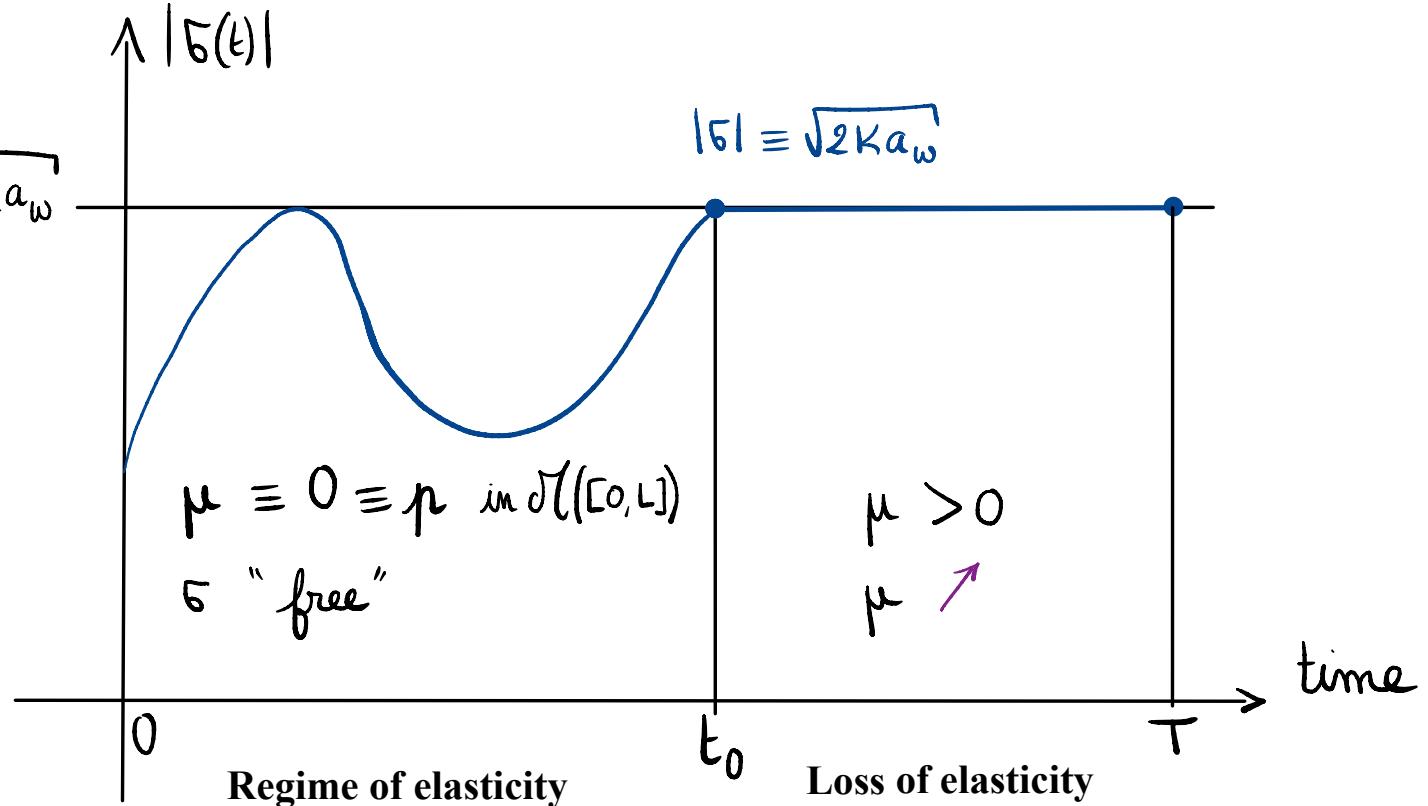
- Relaxed Dirichlet boundary condition
- Constitutive Equation
- Equilibrium Equation
- Stress constraint



$$p = \frac{\sigma}{a_w} \mu$$

\uparrow in time

Energy Balance $\iff \sqrt{2K a_w}$



$$t_0 := \sup \left\{ t \in [0, T], \mu(t)([0, L]) = 0 \right\}$$

Uniform bounds
O-S minimality

Subsequence
independent
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 $\varepsilon \downarrow 0$

Good candidates

$\sigma(t)$ $e(t)$ $\mu(t)$ $p(t)$ $u(t)$

Energy Balance?

$$(u, e, p, \sigma) : [0, T] \rightarrow BV(0, L) \times \mathbb{R} \times \mathcal{P}([0, L]) \times K$$

Additive decomposition

Relaxed Dirichlet boundary condition

Constitutive Equation

Equilibrium Equation

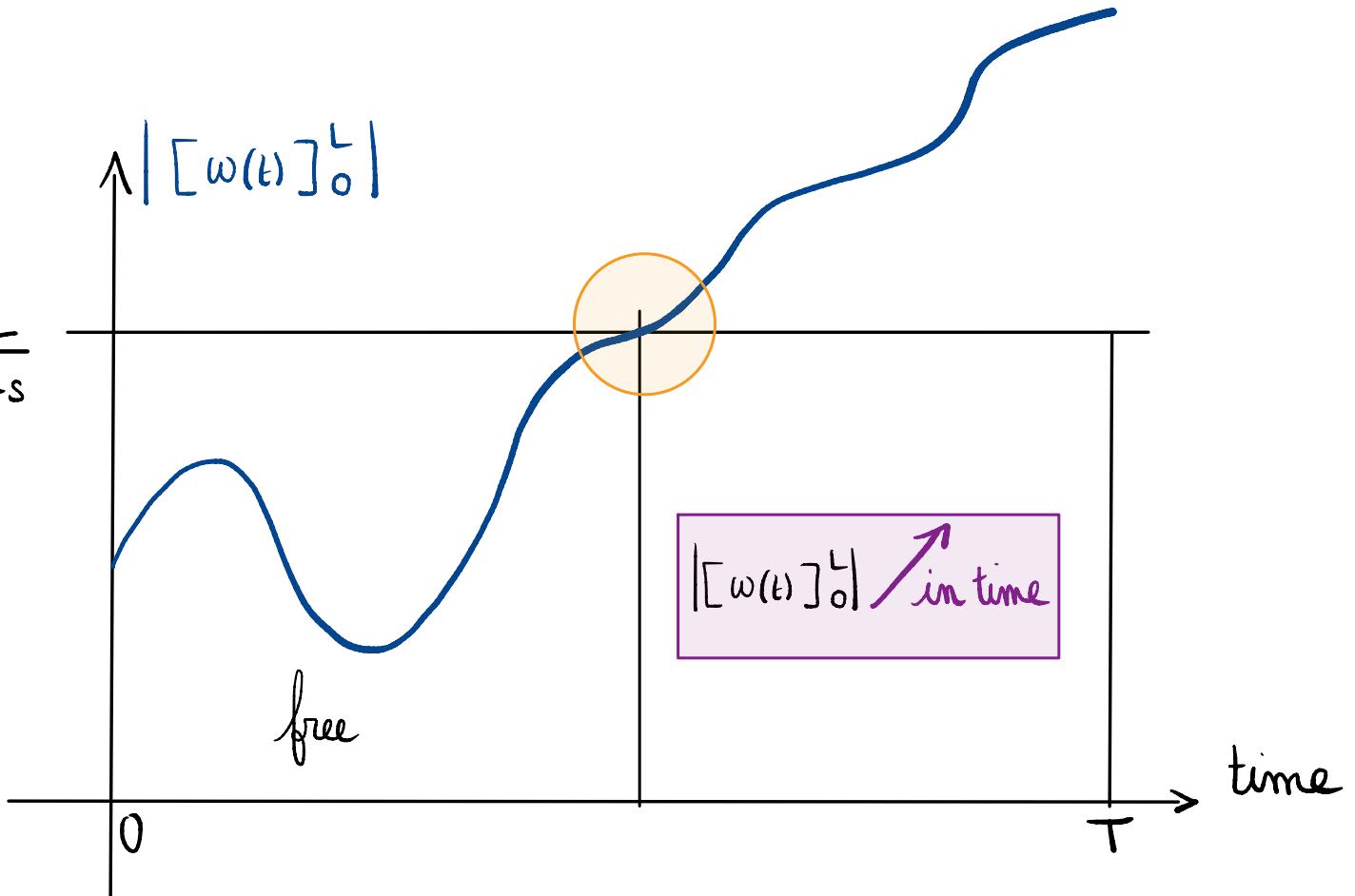
Stress constraint



$$p = \frac{\sigma}{a_w} \mu$$

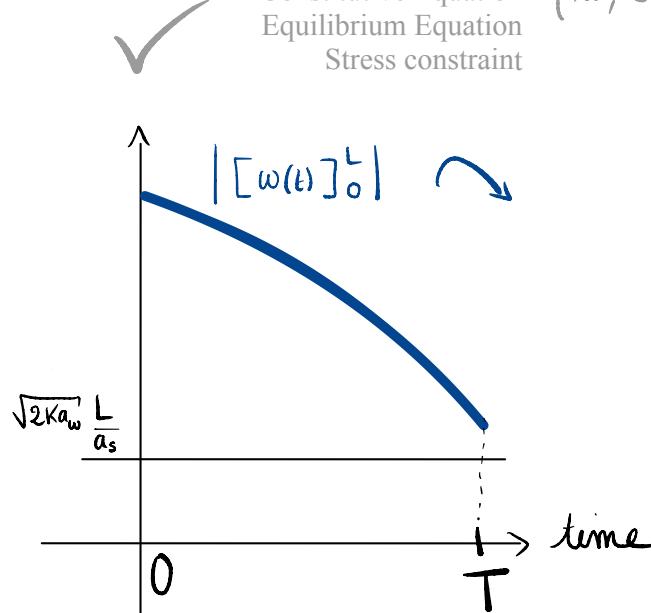
in time

$$\text{Energy Balance} \iff \sqrt{2K a_w} \frac{L}{a_s}$$



Conclusion

Additive decomposition
 Relaxed Dirichlet boundary condition
 Constitutive Equation
 Equilibrium Equation
 Stress constraint



$$(u, e, p, \sigma) : [0, T] \longrightarrow BV(0, L) \times \mathbb{R} \times \mathcal{G}([0, L]) \times K \quad \text{absolutely continuous on } [0, T]$$

$$\Rightarrow \frac{L}{2} a_s e(t)^2 + \sqrt{2K a_w} \mathcal{V}_{(p, 0, t)} > \frac{L}{2} a_s e(0)^2 + \int_0^t \int_0^L \sigma(\dot{\omega})' dx ds$$

QS Brittle Damage Evolution
 \Rightarrow $[F-G]$
 $+ \text{Scaling Law [BIR]}$

$\rightarrow \varepsilon \downarrow 0$ ~~QS perfect plasticity evolution~~

QS Damage Evolution

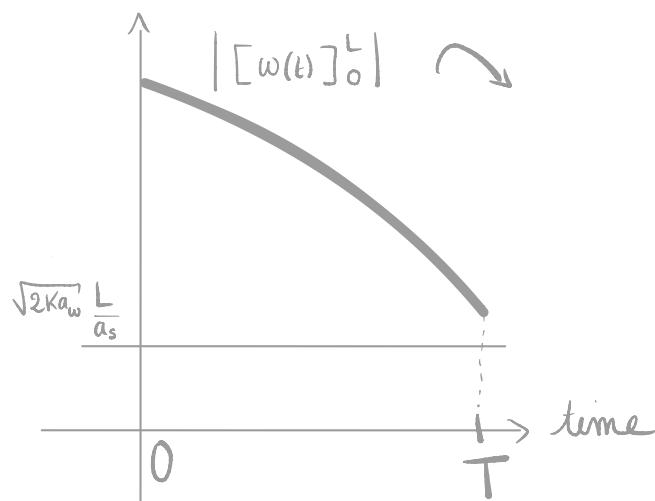
Constitutive Equation $Du(t) = \sigma(t) \left(\frac{\mu^{(t)} L_{(0,L)}}{a_w} + \frac{\mathcal{L}^1 L_{(0,L)}}{a_s} \right)$ in $\mathcal{G}([0, L])$

Griffith Evolution Law $\dot{a}(t) \left(2K a_w - \sigma(t)^2 \right) = 0$ in $\mathcal{G}([0, L])$

$\therefore a(t)$ "inverse" effective rigidity in time

Conclusion

Additive decomposition
 Relaxed Dirichlet boundary condition
 Constitutive Equation
 Equilibrium Equation
 Stress constraint



$$(u, e, p, \sigma) : [0, T] \longrightarrow BV(0, L) \times \mathbb{R} \times \mathcal{G}([0, L]) \times K \text{ absolutely continuous on } [0, T]$$

$$\Rightarrow \frac{L}{2} a_s e(t)^2 + \sqrt{2K a_w} \mathcal{D}_{(p, 0, t)} > \frac{L}{2} a_s e(0)^2 + \int_0^t \int_0^L \sigma(\dot{\omega})' d\omega ds$$

QS Brittle Damage Evolution
 \Rightarrow **[F-G]**
 $+ \text{Scaling Law [BIR]}$
 $\xrightarrow{\varepsilon \downarrow 0}$
~~QS perfect plasticity evolution~~

QS Damage Evolution

Constitutive Equation $Du(t) = \sigma(t) \left(\frac{\mu^{(t)} L_{(0,L)}}{a_w} + \frac{\mathcal{L}^1 L_{(0,L)}}{a_s} \right)$ in $\mathcal{G}([0, L])$

Griffith Evolution Law $\dot{a}(t) \left(2K a_w - \sigma(t)^2 \right) = 0$ in $\mathcal{G}([0, L])$

$a(t)$ "inverse" effective rigidity in time

Thank you for your attention!