Robust hedging of American options in continuous time

Ivan Guo

School of Mathematics Centre for Quantitative Finance and Investment Strategies Monash University

BIRS Workshop — Stochastic Mass Transports March 2022

Joint work with Gregoire Loeper and Jan Obłój

Image: A math the second se

Section 1

Path-dependent optimal transport

Image: A math a math

Semimartingale optimal transport in continuous time

(Tan & Touzi (2013); Huesmann & Trevisan (2017); Backhoff-Veraguas, Beiglböck, Huesmann & Källblad (2017), etc.) Consider probability measures \mathbb{P} such that X is a semimartingale,

$$X_t = X_0 + \int_0^t \alpha_s^{\mathbb{P}} \, ds + M_t, \quad \langle X \rangle_t = \langle M \rangle_t = \int_0^t \beta_s^{\mathbb{P}} \, ds, \quad \mathbb{P}\text{-a.s.},$$

We say \mathbb{P} has *characterstics* $(\alpha^{\mathbb{P}}, \beta^{\mathbb{P}})$.

Semimartingale optimal transport problem

We want to minimise

$$V(\mu_0, \mu_1) = \inf_{\mathbb{P} \in \mathcal{P}(\mu_0, \mu_1)} \mathbb{E}^{\mathbb{P}} \int_0^1 H(\alpha^{\mathbb{P}}, \beta^{\mathbb{P}}) dt,$$

where $\mathcal{P}(\mu_0, \mu_1)$ contains probability measures satisfying

$$\mathbb{P} \circ X_0^{-1} = \mu_0, \quad \mathbb{P} \circ X_1^{-1} = \mu_1.$$

The cost function H is convex in (α, β) and may depend on (t, X) as well.

Path-dependent constraints

Instead of the marginal constraint $\mathbb{P} \circ X_1^{-1} = \mu_1$, how about other types of constraints? For example:

 $\mathbb{E}^{\mathbb{P}} X_1 = c, \quad \mathbb{E}^{\mathbb{P}} G(X) = c, \quad \mathbb{P} \circ G^{-1} = \rho, \quad \mathbb{P}(G(X) \leq 0) \leq c, \quad \text{etc.}$

æ

Path-dependent constraints

Instead of the marginal constraint $\mathbb{P} \circ X_1^{-1} = \mu_1$, how about other types of constraints? For example:

 $\mathbb{E}^{\mathbb{P}} X_1 = c, \quad \mathbb{E}^{\mathbb{P}} G(X) = c, \quad \mathbb{P} \circ G^{-1} = \rho, \quad \mathbb{P}(G(X) \leq 0) \leq c, \quad \text{etc.}$

General abstract constraints

Let $\mathcal{N} \subseteq \mathcal{P}$ be a convex subset that is closed with respect to the weak topology and define $F: C_b(\Omega) \to \mathbb{R} \cup \{+\infty\}$ by $F(\psi) := \sup_{\mu \in \mathcal{N}} \int_{\Omega} \psi \, d\mu$.

$$F^*(\mu) = \sup_{\psi \in C_b(\Omega)} \int_{\Omega} \psi \, d\mu - F(\psi) = \begin{cases} 0, & \mu \in \mathcal{N}, \\ +\infty, & \mu \notin \mathcal{N}. \end{cases}$$

This function penalises measures outside \mathcal{N} . Some examples:

$$\mathbb{E}^{\mathbb{P}}G(X) = c \implies F^*(\mu) = \sup_{\lambda \in \mathbb{R}^m} \lambda \cdot (c - \mathbb{E}^{\mu}(G(X))),$$
$$\mathbb{P} \circ G^{-1} = \rho \implies F^*(\mu) = \sup_{\lambda \in C_b(\mathbb{R}^m)} \int_{\mathbb{R}^m} \lambda(d\rho - d\mu).$$

Path-derivatives

Space of all paths: $\Omega = C([0, 1], \mathbb{R}^d)$, X is the canonical process. Space of all stopped paths: $\Lambda = \{(t, \omega_{\cdot \wedge t}) : t \in [0, 1], \omega \in \Omega\}$.

• • • • • • • • • • •

Path-derivatives

Space of all paths: $\Omega = C([0, 1], \mathbb{R}^d)$, X is the canonical process. Space of all stopped paths: $\Lambda = \{(t, \omega_{\cdot \wedge t}) : t \in [0, 1], \omega \in \Omega\}.$

Dupire (2009) introduced non-anticipative *path-derivatives* operating on functions $C^{1,2}(\Lambda)$. Also see Cont & Fournié (2013); Ekren, Touzi & Zhang. (2016).

• \mathcal{D}_t : a time derivative where we extend forward in time by dt while remaining constant in space.



• ∇_x, ∇_x^2 : space derivatives where we perturb the end point by dx.



Formally, we define the path-derivatives using the functional Itô formula.

Definition

We say $\phi \in C^{1,2}(\Lambda)$ if there exist functions $(\mathcal{D}_t \phi, \nabla_x \phi, \nabla_x^2 \phi) \in C(\Lambda; \mathbb{R} \times \mathbb{R}^d \times \mathbb{S}^d)$ such that, for any semimartingale measure \mathbb{P} , the following *functional Itô formula* holds:

$$\phi(t,X) - \phi(0,X) = \int_0^t \mathcal{D}_t \phi \, dt + \nabla_x \phi \cdot dX_t + \frac{1}{2} \nabla_x^2 \phi : d\langle X \rangle_t, \quad \mathbb{P}\text{-a.s.}$$

The functions $\mathcal{D}_t \phi$, $\nabla_x \phi$, $\nabla_x^2 \phi$ are known as the time derivative, first order space derivative and second order space derivative of ϕ , respectively.

Note that $A: B = tr(A^T B)$ for matrices A and B.

イロン イ団 とく ヨン イヨン

Lemma

Suppose that $\mu \in \mathcal{M}_+(\Omega)$ and $\nu \in \mathcal{M}_+(\Lambda)$. Then we have the equality

$$\int_{\Omega} \phi(1,\cdot) \, d\mu - \int_{\Omega_0} \phi(0,\cdot) \, d\rho_0 = \int_{\Lambda} \mathcal{D}_t \phi + \alpha \cdot \nabla_x \phi + \frac{1}{2}\beta : \nabla_x^2 \phi \, d\nu \qquad (1)$$

holds for all $\phi \in C^{1,2}(\Lambda)$ if and only if all of the following hold: (a) $d\mu \times dt = d\nu$, (b) $\mu \in \mathcal{P}(\rho_0)$ and (c) X is a μ -semimartingale with characteristics (α, β) .

Let us rewrite (1) using the shorthand $\mathcal{L}(\phi, \mu, \nu, \alpha, \beta) = 0$

イロト 不得 トイヨト イヨト

Path-dependent optimal transport

Our problem is

$$\begin{split} V &= \inf_{\mathbb{P}\in\mathcal{P}(\rho_0)} \int_{\Lambda} H(\alpha^{\mathbb{P}},\beta^{\mathbb{P}}) \, dt d\mathbb{P} \quad \text{s.t. } \mathbb{P}\in\mathcal{N}, \, X \text{ is a } \mathbb{P}\text{-semimartingale} \\ &= \inf_{\mathbb{P}\in\mathcal{P}(\rho_0)} F^*(\mathbb{P}) + \int_{\Lambda} H(\alpha^{\mathbb{P}},\beta^{\mathbb{P}}) \, dt d\mathbb{P} \quad \text{s.t. } X \text{ is a } \mathbb{P}\text{-semimartingale} \\ &= \inf_{\substack{\mu\in\mathcal{M}_+(\Omega), \\ \nu\in\mathcal{M}_+(\Lambda), \\ (\alpha,\beta)\in L^1(\Lambda,\nu)}} \sup_{\psi\in C_b(\Omega)} \int_{\Omega} \psi \, d\mu - F(\psi) + \int_{\Lambda} H(\alpha,\beta) \, d\nu - \mathcal{L}(\phi,\mu,\nu,\alpha,\beta) \end{split}$$

We want to swap the inf with the sup.

æ

(日) (同) (日) (日)

Path-dependent optimal transport

Our problem is

$$\begin{split} V &= \inf_{\mathbb{P}\in\mathcal{P}(\rho_0)} \int_{\Lambda} H(\alpha^{\mathbb{P}},\beta^{\mathbb{P}}) \, dt d\mathbb{P} \quad \text{s.t. } \mathbb{P}\in\mathcal{N}, \, X \text{ is a } \mathbb{P}\text{-semimartingale} \\ &= \inf_{\mathbb{P}\in\mathcal{P}(\rho_0)} F^*(\mathbb{P}) + \int_{\Lambda} H(\alpha^{\mathbb{P}},\beta^{\mathbb{P}}) \, dt d\mathbb{P} \quad \text{s.t. } X \text{ is a } \mathbb{P}\text{-semimartingale} \\ &= \inf_{\substack{\mu\in\mathcal{M}_+(\Omega), \\ \nu\in\mathcal{M}_+(\Lambda), \\ (\alpha,\beta)\in L^1(\Lambda,\nu)}} \sup_{\substack{\phi\in\bar{C}_0^{1,2}(\Lambda), \\ \psi\in C_b(\Omega)}} \int_{\Omega} \psi \, d\mu - F(\psi) + \int_{\Lambda} H(\alpha,\beta) \, d\nu - \mathcal{L}(\phi,\mu,\nu,\alpha,\beta) \end{split}$$

We want to swap the inf with the sup.

Use the Fenchel-Rockafellar duality theorem, operating on dual pairings of the form

$$(\mu, \nu, \bar{\nu}, \tilde{\nu})$$
 and $(\phi_1 + \psi, \mathcal{D}_t \phi, \nabla_x \phi, \nabla_x^2 \phi),$

where $d\bar{\nu} = \alpha d\nu$ and $d\tilde{\nu} = \beta d\nu$.

(日) (四) (日) (日) (日)

Fenchel-Rockafellar duality theorem

Let f be convex and g be concave. Let f^* and g_* be the respective convex and concave conjugates. Under some conditions,

$$\inf_{x \in \mathcal{X}} f(x) - g(x) = \sup_{x^* \in \mathcal{X}^*} g_*(x^*) - f^*(x^*),$$
$$\inf_{x \in \mathcal{X}} \sup_{x^* \in \mathcal{X}^*} f(x) + g_*(x^*) - \langle x, x^* \rangle = \sup_{x^* \in \mathcal{X}^*} \inf_{x \in \mathcal{X}} g_*(x^*) + f(x) - \langle x, x^* \rangle.$$



< □ > < 同 >

Main duality result

Theorem

イロト イヨト イヨト イヨト

э.

$$\begin{split} \inf_{\mathbb{P}\in\mathcal{P}(\rho_0)\cap\mathcal{N}} \int_{\Lambda} H(\alpha^{\mathbb{P}},\beta^{\mathbb{P}}) \, dt d\mathbb{P} &= \sup_{\psi\in C_b(\Omega), \phi\in C^{1,2}(\Lambda)} -F(\psi) - \int_{\Omega_0} \phi(0,\cdot) \, d\rho_0, \\ \text{s.t.} \quad \phi(1,\cdot) \geq -\psi \quad \text{and} \quad \mathcal{D}_t \phi + H^*\left(\nabla_x \phi, \frac{1}{2} \nabla_x^2 \phi\right) \leq 0. \end{split}$$

• The primal problem is attained, i.e., there exists an optimal $\tilde{\mathbb{P}}$ with characteristics $(\tilde{\alpha},\tilde{\beta}).$

• • • • • • • • • • •

$$\begin{split} \inf_{\mathbb{P}\in\mathcal{P}(\rho_0)\cap\mathcal{N}} \int_{\Lambda} H(\alpha^{\mathbb{P}},\beta^{\mathbb{P}}) \, dt d\mathbb{P} &= \sup_{\psi\in C_b(\Omega), \phi\in C^{1,2}(\Lambda)} -F(\psi) - \int_{\Omega_0} \phi(0,\cdot) \, d\rho_0, \\ \text{s.t.} \quad \phi(1,\cdot) \geq -\psi \quad \text{and} \quad \mathcal{D}_t \phi + H^*\left(\nabla_x \phi, \frac{1}{2} \nabla_x^2 \phi\right) \leq 0. \end{split}$$

- The primal problem is attained, i.e., there exists an optimal $\tilde{\mathbb{P}}$ with characteristics $(\tilde{\alpha},\tilde{\beta}).$
- $\bullet~{\rm If}~(\psi^n,\phi^n)$ is a maximising sequence of the dual problem, then

$$\begin{split} \phi^n + \psi^n \stackrel{d\tilde{\mathbb{P}}}{\to} 0, \quad \mathcal{D}_t \phi^n + H^* \left(\nabla_x \phi^n, \frac{1}{2} \nabla_x^2 \phi^n \right) \stackrel{d\tilde{\mathbb{P}} \times dt}{\to} 0, \\ \nabla H^* \left(\nabla_x \phi^n, \frac{1}{2} \nabla_x^2 \phi^n \right) \stackrel{d\tilde{\mathbb{P}} \times dt}{\to} (\tilde{\alpha}, \tilde{\beta}). \end{split}$$

$$\begin{split} \inf_{\mathbb{P}\in\mathcal{P}(\rho_0)\cap\mathcal{N}} \int_{\Lambda} H(\alpha^{\mathbb{P}},\beta^{\mathbb{P}}) \, dt d\mathbb{P} &= \sup_{\psi\in C_b(\Omega),\phi\in C^{1,2}(\Lambda)} -F(\psi) - \int_{\Omega_0} \phi(0,\cdot) \, d\rho_0, \\ \text{s.t.} \quad \phi(1,\cdot) \geq -\psi \quad \text{and} \quad \mathcal{D}_t \phi + H^*\left(\nabla_x \phi, \frac{1}{2}\nabla_x^2 \phi\right) \leq 0. \end{split}$$

- The primal problem is attained, i.e., there exists an optimal $\tilde{\mathbb{P}}$ with characteristics $(\tilde{\alpha}, \tilde{\beta})$.
- $\bullet~{\rm If}~(\psi^n,\phi^n)$ is a maximising sequence of the dual problem, then

$$\begin{split} \phi^n + \psi^n \stackrel{d\tilde{\mathbb{P}}}{\to} 0, \quad \mathcal{D}_t \phi^n + H^* \left(\nabla_x \phi^n, \frac{1}{2} \nabla_x^2 \phi^n \right) \stackrel{d\tilde{\mathbb{P}} \times dt}{\to} 0, \\ \nabla H^* \left(\nabla_x \phi^n, \frac{1}{2} \nabla_x^2 \phi^n \right) \stackrel{d\tilde{\mathbb{P}} \times dt}{\to} (\tilde{\alpha}, \tilde{\beta}). \end{split}$$

• Under some conditions, via partial comparison principles for PPDEs, we recover the HJB equation without using the dynamic programming principle.

1

Optimal transport for volatility calibration



Figure: Volatility $\sigma(t, x, y)$ (y is the running minimum) calibrated to European puts, down-and-out puts (all possible barriers) and lookback puts, at all strikes and four different maturities. The figure shows the t cross sections.

Section 2

Robust hedging in continuous time

I Guo (Monash CQFIS)

Robust hedging of American options

March 2022

・ロト ・日下・ ・ ヨト・

13/33

Robust hedging: model uncertainty

Consider a market with stocks X and some European claims g which WLOG have initial prices of 0. We are allowed to trade X dynamically and g statically.

Let $Q \subset P$ be the set of possible "models", i.e., X is martingale, g has zero expectation, etc.

イロト イボト イヨト イヨ

Robust hedging: model uncertainty

Consider a market with stocks X and some European claims g which WLOG have initial prices of 0. We are allowed to trade X dynamically and g statically.

Let $\mathcal{Q}\subset \mathcal{P}$ be the set of possible "models", i.e., X is martingale, g has zero expectation, etc.

Consider a European claim Z. Worst case model price:

$$\sup_{\mathbb{P}\in\mathcal{Q}}\mathbb{E}^{\mathbb{P}}Z.$$

Super-hedging price:

$$\pi(Z) := \inf\{x : \exists (q,h), \text{ s.t. } x + \int_0^1 q \cdot dX_t + h \cdot g \ge Z, \ \mathcal{Q}\text{-q.s.}\}.$$

(日) (四) (日) (日) (日)

Robust hedging: model uncertainty

Consider a market with stocks X and some European claims g which WLOG have initial prices of 0. We are allowed to trade X dynamically and g statically.

Let $\mathcal{Q}\subset \mathcal{P}$ be the set of possible "models", i.e., X is martingale, g has zero expectation, etc.

Consider a European claim Z. Worst case model price:

$$\sup_{\mathbb{P}\in\mathcal{Q}}\mathbb{E}^{\mathbb{P}}Z.$$

Super-hedging price:

$$\pi(Z) := \inf\{x : \exists (q,h), \text{ s.t. } x + \int_0^1 q \cdot dX_t + h \cdot g \ge Z, \ \mathcal{Q}\text{-q.s.}\}.$$

It is easy to check that

$$\pi(Z) \ge \sup_{\mathbb{P} \in \mathcal{Q}} \mathbb{E}^{\mathbb{P}} Z.$$

Duality (equality) results are obtained in various settings by Denis & Martini (2006); Soner, Touzi & Zhang (2013); Neufeld & Nutz (2013); and Possamaï, Royer & Touzi (2013); Hou & Obłój (2018) and many more.

I Guo (Monash CQFIS)

Theorem

Let $H : \Lambda \times \mathbb{S}^d \to \mathbb{R} \cup \{+\infty\}$ satisfy some assumptions and $H^*(t, \omega, \cdot)$ be the convex conjugate of $H(t, \omega, \cdot)$. Define

$$\begin{split} V &:= \sup_{\mathbb{P}} \inf_{h \in \mathbb{R}^m} \mathbb{E}^{\mathbb{P}}(-h \cdot g + Z) - \mathbb{E}^{\mathbb{P}} \int_0^1 H(\beta_t^{\mathbb{P}}) \, dt, \\ \mathcal{V} &:= \inf_{h \in \mathbb{R}^m, \phi \in C^{1,2}(\Lambda)} \phi(0, X_0), \\ \text{subject to} \quad \phi(1, \cdot) \geq Z - h \cdot g \quad \text{and} \quad \mathcal{D}_t \phi + H^* \left(\frac{1}{2} \nabla_x^2 \phi\right) \leq 0. \end{split}$$

Then $V = \mathcal{V}$. Moreover, if V is finite, then the supremum is attained.

Hedging duality via Path-dependent OT

Let $H(\beta)$ be 0 if $\beta \in D$ (volatility constraint), or ∞ otherwise. Then the dual is

$$\mathcal{V} = \inf_{h \in \mathbb{R}^m, \phi \in C^{1,2}(\Lambda)} \phi(0, X_0),$$

ubject to $\phi(1, \cdot) \ge Z - h \cdot g$ and $\mathcal{D}_t \phi + \sup_{\beta \in D} \frac{1}{2} \nabla_x^2 \phi : \beta \le 0.$ (2)

Each ϕ is actually a super-hedge. For every $\mathbb{P}\in\mathcal{Q}$

$$\begin{split} Z - h \cdot g - \phi(0, X_0) &\leq \phi(1, X) - \phi(0, X_0) \\ &= \int_0^1 (\mathcal{D}_t \phi + \frac{1}{2} \beta^{\mathbb{P}} : \nabla_x^2 \phi) dt + \nabla_x \phi \cdot dX_t, \quad \mathbb{P}\text{-a.s.} \\ &\leq \int_0^1 \nabla_x \phi \cdot dX_t. \end{split}$$

Hence $\phi(0, X_0) \ge \pi(Z)$. Since this works for all ϕ satisfying (2), it implies

$$\mathcal{V} = \inf_{\phi \in C_0^{1,2}(\Lambda), (2)} \phi(0, X_0) \ge \pi(Z) \ge \sup_{\mathbb{P} \in \mathcal{Q}} \mathbb{E}^{\mathbb{P}} Z = V = \mathcal{V},$$

S

Robust hedging American options

Let Z be an American-style claim. Worst case model price:

 $\sup_{\tau\in\mathcal{T},\mathbb{P}\in\mathcal{Q}}\mathbb{E}^{\mathbb{P}}Z(\tau,\cdot).$

Super-hedging price:

$$\begin{split} \pi^A(Z) &:= \inf\{x: \exists (p,q,h) \text{ s.t.} \\ x + \int_0^\tau p \cdot dX_t + \int_\tau^1 q^\tau \cdot dX_t + hg \geq Z_\tau, \mathcal{Q}^D\text{-q.s.}, \forall \tau \in \mathcal{T} \}. \end{split}$$

Again, it is easy to check $\pi^A(Z) \ge \sup_{\tau \in \mathcal{T}, \mathbb{P} \in \mathcal{Q}} \mathbb{E}^{\mathbb{P}} Z(\tau, \cdot).$

イロト イポト イヨト 一日

Robust hedging American options

Let ${\cal Z}$ be an American-style claim. Worst case model price:

 $\sup_{\tau\in\mathcal{T},\mathbb{P}\in\mathcal{Q}}\mathbb{E}^{\mathbb{P}}Z(\tau,\cdot).$

Super-hedging price:

$$\begin{aligned} \pi^A(Z) &:= \inf\{x : \exists (p,q,h) \text{ s.t.} \\ x + \int_0^\tau p \cdot dX_t + \int_\tau^1 q^\tau \cdot dX_t + hg \geq Z_\tau, \mathcal{Q}^D \text{-q.s.}, \forall \tau \in \mathcal{T} \}. \end{aligned}$$

Again, it is easy to check $\pi^A(Z) \ge \sup_{\tau \in \mathcal{T}, \mathbb{P} \in \mathcal{Q}} \mathbb{E}^{\mathbb{P}} Z(\tau, \cdot).$

When the set of statically traded European options is non-empty, there may be a duality gap, which can be eliminated by enlarging the probability space.

In discrete time, various duality results for American options are obtained by Dolinsky (2014); Hobson & Neuberger (2017); Bayraktar & Zhou (2017); Aksamit, Deng, Obłój & Tan (2019); and more. Some relevant works in continuous time include Herrmann & Stebegg (2017); Tiplea (2019); Grigorova, Quenez & Sulem (2021) etc.

I Guo (Monash CQFIS)

Overview

The main idea of Aksamit et al. (2019) is to enlarge the space Ω with the stopping decisions to obtain $\overline{\Omega}$. Then the American option can be seen as a European option under the enlarged space.

イロト イヨト イヨト イヨト

Overview

The main idea of Aksamit et al. (2019) is to enlarge the space Ω with the stopping decisions to obtain $\overline{\Omega}$. Then the American option can be seen as a European option under the enlarged space.

In the case where there is no statically traded European options g.

$$\bar{\pi}(Z) = \pi^A(Z) \ge \sup_{\bar{\mathbb{P}} \in \bar{\mathcal{Q}}} \mathbb{E}^{\bar{\mathbb{P}}} Z = \bar{\pi}(Z),$$
$$\sup_{\bar{\mathbb{P}} \in \bar{\mathcal{Q}}} \mathbb{E}^{\bar{\mathbb{P}}} Z = \sup_{\tau \in \mathcal{T}, \mathbb{P} \in \mathcal{Q}} \mathbb{E}^{\mathbb{P}} Z(\tau, \cdot).$$

(日) (四) (日) (日) (日)

Overview

The main idea of Aksamit et al. (2019) is to enlarge the space Ω with the stopping decisions to obtain $\overline{\Omega}$. Then the American option can be seen as a European option under the enlarged space.

In the case where there is no statically traded European options g.

$$\bar{\pi}(Z) = \pi^{A}(Z) \ge \sup_{\bar{\mathbb{P}} \in \bar{\mathcal{Q}}} \mathbb{E}^{\bar{\mathbb{P}}} Z = \bar{\pi}(Z),$$
$$\sup_{\bar{\mathbb{P}} \in \bar{\mathcal{Q}}} \mathbb{E}^{\bar{\mathbb{P}}} Z = \sup_{\tau \in \mathcal{T}, \mathbb{P} \in \mathcal{Q}} \mathbb{E}^{\mathbb{P}} Z(\tau, \cdot).$$

When g does exist, then we have to introduce a second enlarged space $\hat{\Omega}$ which includes the price process of g as another martingale.

$$\bar{\pi}_{g}(Z) = \pi_{g}^{A}(Z) \ge \hat{\pi}^{A}(Z) = \bar{\hat{\pi}}(Z) \ge \sup_{\bar{\mathbb{P}} \in \bar{\hat{\mathcal{Q}}}} \mathbb{E}^{\bar{\mathbb{P}}} Z \ge \sup_{\bar{\mathbb{P}} \in \bar{\hat{\mathcal{Q}}}_{g}} \mathbb{E}^{\bar{\mathbb{P}}} Z = \bar{\pi}_{g}(Z),$$
$$\sup_{\bar{\hat{\mathbb{P}}} \in \bar{\hat{\mathcal{Q}}}} \mathbb{E}^{\bar{\mathbb{P}}} Z = \sup_{\hat{\tau} \in \widehat{\mathcal{T}}, \bar{\mathbb{P}} \in \widehat{\mathcal{Q}}} \mathbb{E}^{\bar{\mathbb{P}}} Z(\hat{\tau}, \cdot).$$

We mostly focus on the case where there is no g.

æ

イロト イ団ト イヨト イヨト

We mostly focus on the case where there is no g.

Pricing hedging duality for European options is known in continuous time, and naturally extends to the enlarged space.

The equality $\bar{\pi}(Z) = \pi^A(Z)$ can also be argued in mostly the same way.

(日) (四) (日) (日) (日)

We mostly focus on the case where there is no g.

Pricing hedging duality for European options is known in continuous time, and naturally extends to the enlarged space.

The equality $\bar{\pi}(Z) = \pi^A(Z)$ can also be argued in mostly the same way.

However, the equality

$$\sup_{\mathbb{P}\in\bar{\mathcal{Q}}}\mathbb{E}^{\mathbb{P}}Z = \sup_{\tau\in\mathcal{T},\mathbb{P}\in\mathcal{Q}}\mathbb{E}^{\mathbb{P}}Z(\tau,\cdot),$$

creates difficulties in continuous time. Possible approaches include approximating with discrete time, Doob-Meyer type decomposition of non-linear Snell envelopes, reflected 2BSDEs, etc.

イロト 不得 トイヨト イヨト

Section 3

Duality for American options: Convexifying stopping times and martingale measures

I Guo (Monash CQFIS)

Robust hedging of American options

March 2022

20 / 33

Enlarged space

The original space for our model is $\Omega := C([0,1]; \mathbb{R}^d)$ with canonical process X. We enlarge it to $\overline{\Omega} := \Theta \times \Omega$ where

 $\Theta:=\{\vartheta\in C([0,1],\mathbb{R}): \vartheta_t=\theta\wedge t, \text{ for some } \theta\in [0,1]\}.$

 Θ is isometric to [0,1].

< ロ > < 同 > < 三 > < 三 > 、

Enlarged space

The original space for our model is $\Omega := C([0,1]; \mathbb{R}^d)$ with canonical process X. We enlarge it to $\overline{\Omega} := \Theta \times \Omega$ where

 $\Theta := \{ \vartheta \in C([0,1],\mathbb{R}) : \vartheta_t = \theta \wedge t, \text{ for some } \theta \in [0,1] \}.$

 Θ is isometric to [0,1].



Enlarged space

The original space for our model is $\Omega := C([0,1]; \mathbb{R}^d)$ with canonical process X. We enlarge it to $\overline{\Omega} := \Theta \times \Omega$ where

 $\Theta := \{ \vartheta \in C([0,1],\mathbb{R}) : \vartheta_t = \theta \wedge t, \text{ for some } \theta \in [0,1] \}.$

 Θ is isometric to [0,1].



Most aspects of Ω can be naturally extended to $\overline{\Omega}$, include semimartingale measures (since ϑ semimartingale with characteristics $(\mathbb{1}(t \leq \theta), 0)$). E.g., we define \overline{Q} to be the set of measures under which X is a martingale.

Path-dependent optimal transport on $\bar{\Omega}$

Also define the "stopped paths" of $\bar{\Omega}$, by

$$\bar{\Lambda} := \{ (t, \bar{\omega}_{\cdot \wedge t}) : t \in [0, 1], \bar{\omega} \in \bar{\Omega} \}.$$

So elements of $\overline{\Lambda}$ are $(t, \overline{\omega}_{.\wedge t}) = (t, \vartheta_{.\wedge t}, \omega_{.\wedge t}) = (t, \theta \wedge t, \omega_{.\wedge t})$. Functional Itô calculus and PPDEs can be extended in the same way.

The path-dependent optimal transport duality results (Guo and Loeper (2021)) can be applied here.

Theorem

$$\begin{split} \sup_{\bar{\mathbb{P}}\in\bar{\mathcal{Q}}^D} \mathbb{E}^{\bar{\mathbb{P}}}f &= \inf_{\phi\in C_0^{1,1,2}(\bar{\Lambda})} \phi(0,0,X_0), \\ \text{subject to} \quad \phi(1,\cdot,\cdot) \geq f \quad \text{and} \quad \mathcal{D}_t \phi + \mathbbm{1}(t \leq \theta) \nabla_\theta \phi + \sup_{\beta \in D} \frac{1}{2}\beta : \nabla_x^2 \phi \leq 0. \end{split}$$

Image: A math the second se

European duality on the enlarged space

Theorem

sι

$$\sup_{\bar{\mathbb{P}}\in\bar{\mathcal{Q}}^D} \mathbb{E}^{\bar{\mathbb{P}}} f = \inf_{\phi\in C_0^{1,1,2}(\bar{\Lambda})} \phi(0,0,X_0),$$

which to $\phi(1,\cdot,\cdot) \ge f$ and $\mathcal{D}_t \phi + \mathbb{1}(t \le \theta) \nabla_\theta \phi + \sup_{\beta\in D} \frac{1}{2}\beta : \nabla_x^2 \phi \le 0.$

By the functional Itô formula, for each ϕ and $\overline{\mathbb{P}} \in \overline{Q}^D$, the following holds $\overline{\mathbb{P}}$ -a.s.

$$\begin{aligned} f - \phi(0, 0, X_0) &\leq \phi(1, \cdot, \cdot) - \phi(0, 0, X_0) \\ &= \int_0^1 (\mathcal{D}_t \phi + \mathbbm{1}(t \leq \theta) \nabla_\theta \phi + \frac{1}{2} \beta^{\mathbb{P}} : \nabla_x^2 \phi) dt + \nabla_x \phi \cdot dX_t \\ &\leq \int_0^1 \nabla_x \phi \cdot dX_t. \end{aligned}$$

Hence $\phi(0,0,X_0) \ge \bar{\pi}(f)$. Since this holds for all ϕ , it implies

$$\sup_{\bar{\mathbb{P}}\in\bar{\mathcal{Q}}^D}\mathbb{E}^{\bar{\mathbb{P}}}f\geq\bar{\pi}(f).$$

(日) (四) (日) (日) (日)

3/33

Convexifying measures and stopping times

We still need to address $\sup_{\bar{\mathbb{P}}\in\bar{\mathcal{Q}}}\mathbb{E}^{\bar{\mathbb{P}}}Z = \sup_{\tau\in\mathcal{T},\mathbb{P}\in\mathcal{Q}}\mathbb{E}^{\mathbb{P}}Z(\tau,\cdot).$

Given a pair $(\tau, \mathbb{P}) \in \mathcal{T} \times \mathcal{P}(\Omega)$, we can associate it with $\overline{\mathbb{P}} \in \mathcal{P}(\overline{\Omega})$ so that $\mathbb{E}^{\mathbb{P}}Z(\tau, \cdot) = \mathbb{E}^{\mathbb{P}}Z$. So $\mathcal{P}(\overline{\Omega})$ contains the "convex hull" of $\mathcal{T} \times \mathcal{P}(\Omega)$.

• • • • • • • • • • • •

Convexifying measures and stopping times

We still need to address $\sup_{\overline{\mathbb{P}}\in \bar{\mathcal{Q}}} \mathbb{E}^{\overline{\mathbb{P}}} Z = \sup_{\tau\in\mathcal{T},\mathbb{P}\in\mathcal{Q}} \mathbb{E}^{\mathbb{P}} Z(\tau,\cdot).$

Given a pair $(\tau, \mathbb{P}) \in \mathcal{T} \times \mathcal{P}(\Omega)$, we can associate it with $\overline{\mathbb{P}} \in \mathcal{P}(\overline{\Omega})$ so that $\mathbb{E}^{\mathbb{P}}Z(\tau, \cdot) = \mathbb{E}^{\mathbb{P}}Z$. So $\mathcal{P}(\overline{\Omega})$ contains the "convex hull" of $\mathcal{T} \times \mathcal{P}(\Omega)$.

But $\bar{\mathbb{P}} \in \mathcal{P}(\bar{\Omega})$ in general may correspond to "proper" random times, not even randomised stopping times.



• • • • • • • • • • • • • •

Convexifying measures and stopping times

We still need to address
$$\sup_{\bar{\mathbb{P}}\in\bar{\mathcal{Q}}}\mathbb{E}^{\bar{\mathbb{P}}}Z = \sup_{\tau\in\mathcal{T},\mathbb{P}\in\mathcal{Q}}\mathbb{E}^{\mathbb{P}}Z(\tau,\cdot).$$

Given a pair $(\tau, \mathbb{P}) \in \mathcal{T} \times \mathcal{P}(\Omega)$, we can associate it with $\overline{\mathbb{P}} \in \mathcal{P}(\overline{\Omega})$ so that $\mathbb{E}^{\mathbb{P}}Z(\tau, \cdot) = \mathbb{E}^{\mathbb{P}}Z$. So $\mathcal{P}(\overline{\Omega})$ contains the "convex hull" of $\mathcal{T} \times \mathcal{P}(\Omega)$.

But $\overline{\mathbb{P}} \in \mathcal{P}(\overline{\Omega})$ in general may correspond to "proper" random times, not even randomised stopping times.



If we choose another measure carefully and *only test against non-anticipative functions*, we can recover randomised stopping times. We also want to preserve martingale properties which is tricky.

I Guo (Monash CQFIS)

Robust hedging of American options

A few concepts

Definition

Given a random time $\rho,$ let $R:=\mathbb{1}(\rho\leq t).$ Then the Azéma supermartingale is defined as

$$Y = 1 - {}^{o}R = \mathbb{P}(\rho > t \,|\, \mathcal{F}_t).$$

æ

イロト イヨト イヨト イヨト

A few concepts

Definition

Given a random time ρ , let $R := \mathbb{1}(\rho \leq t)$. Then the Azéma supermartingale is defined as

$$Y = 1 - {}^{o}R = \mathbb{P}(\rho > t \,|\, \mathcal{F}_t).$$

Theorem (Itô-Watanabe)

Let Y be a non-negative càdlàg supermartingale with $Y_0 > 0$. Then we have the decomposition

$$Y = M(1 - A)$$

where M is a positive local martingale, A is a right-continuous, increasing process with $A_0 = 0$. The decomposition is unique up to $\tau = \inf\{t : Y_t = 0\}$.

25/33

イロト イポト イヨト イヨト

A few concepts

Definition

Given a random time $\rho,$ let $R:=\mathbbm{1}(\rho\leq t).$ Then the Azéma supermartingale is defined as

$$Y = 1 - {}^{o}R = \mathbb{P}(\rho > t \,|\, \mathcal{F}_t).$$

Theorem (Itô-Watanabe)

Let Y be a non-negative càdlàg supermartingale with $Y_0 > 0$. Then we have the decomposition

$$Y = M(1 - A)$$

where M is a positive local martingale, A is a right-continuous, increasing process with $A_0 = 0$. The decomposition is unique up to $\tau = \inf\{t : Y_t = 0\}$.

Definition (Shmaya & Solan)

A randomised stopping time corresponds to an adapted, right-continuous, increasing process A with $A_0 = 0$ and $A_1 = 1$.

I Guo (Monash CQFIS)

イロト イ団ト イヨト イヨト

æ

From random times to stopping times

Lemma

(a) For every $\mu \in \mathcal{P}(\overline{\Omega})$, there exists an increasing and adapted A with $A_0 = 0$ and $A_1 = 1$, and $\mathbb{P} \in \mathcal{P}(\Omega)$ with $\mathbb{P} \ll \mu_{\Omega}$, such that for every (non-anticipative) $\psi \in L^{\infty}(\Lambda)$,

$$u(\psi(\theta,\omega_{\cdot\wedge\theta})) = \mathbb{E}^{\mathbb{P}} \int_0^1 \psi(t,\omega_{\cdot\wedge t}) \, dA_t.$$

(日) (四) (日) (日) (日)

From random times to stopping times

Lemma

(a) For every $\mu \in \mathcal{P}(\overline{\Omega})$, there exists an increasing and adapted A with $A_0 = 0$ and $A_1 = 1$, and $\mathbb{P} \in \mathcal{P}(\Omega)$ with $\mathbb{P} \ll \mu_{\Omega}$, such that for every (non-anticipative) $\psi \in L^{\infty}(\Lambda)$,

$$\iota(\psi(\theta,\omega_{\cdot\wedge\theta})) = \mathbb{E}^{\mathbb{P}} \int_{0}^{1} \psi(t,\omega_{\cdot\wedge t}) \, dA_{t}.$$

Proof outline: Define the raw IV process R from μ , for any $E \in \mathcal{F}_s$,

$$\int_{\bar{\Omega}} \mathbb{1}(\theta > s, \omega \in E) \, d\mu = \mathbb{E}^{\mu_{\Omega}} \big((1 - R_s) \mathbb{1}(\omega \in E) \big).$$

Then $1 - {}^{o}R$ is a non-negative μ_{Ω} -supermartingale (the Azéma supermartingale of the random time associated with μ). It has the (Itô-Watanabe) multiplicative decomposition $1 - {}^{o}R = M(1 - A)$, so

$$\mathbb{E}^{\mu_{\Omega}}((1-R_{s})\mathbb{1}(\omega\in E)) = \mathbb{E}^{\mu_{\Omega}}((1-{}^{o}R_{s})\mathbb{1}(\omega\in E))$$
$$= \mathbb{E}^{\mu_{\Omega}}(M_{s}(1-A_{s})\mathbb{1}(\omega\in E)) = \mathbb{E}^{\mathbb{P}}((1-A_{s})\mathbb{1}(\omega\in E)),$$

where $d\mathbb{P}/d\mu_{\Omega} = M_1$.

From random times to stopping times

Lemma

(a) For every $\mu \in \mathcal{P}(\overline{\Omega})$, there exists an increasing and adapted A with $A_0 = 0$ and $A_1 = 1$, and $\mathbb{P} \in \mathcal{P}(\Omega)$ with $\mathbb{P} \ll \mu_{\Omega}$, such that for every (non-anticipative) $\psi \in L^{\infty}(\Lambda)$,

$$\mu(\psi(\theta,\omega_{\cdot\wedge\theta})) = \mathbb{E}^{\mathbb{P}} \int_{0}^{1} \psi(t,\omega_{\cdot\wedge t}) \, dA_t.$$

(b) For every $\mu \in \mathcal{P}(\bar{\Omega})$, there exists a family of true stopping times τ_r and probability measures \mathbb{P}^r , indexed by $r \in [0,1]$, such that for every $\eta \in L^{\infty}(\bar{\Omega})$,

$$\mu(\eta(\theta,\omega)) = \int_0^1 \mathbb{E}^{\mathbb{P}^r} \eta(\theta = \tau_r, \omega) \, dr.$$

(c) For any $a \in [0,1]$ and any bounded and \mathcal{F}_{τ_a} -measurable function γ ,

$$\int_{a}^{1} \mathbb{E}^{\mathbb{P}^{r}} \gamma \, dr = (1-a) \mathbb{E}^{\mathbb{P}} \gamma.$$

Roughly speaking, we obtain r by disintegrating μ according to the value of A_{abs}



æ



イロト イヨト イヨト イヨト

28/33

æ



Image: A mathematical states and a mathem

Why not disintegrate via t?



.∋...>

イロト イヨト イヨト イ

Why not disintegrate via t? Or even just ω ?



• • • • • • • • • • •



I Guo (Monash CQFIS)

March 2022

29 / 33



9/33



Image: A math the second se



• • • • • • • • • •



29/33

Lemma

Suppose that X is a martingale under $\mu \in \mathcal{P}(\bar{\Omega})$ with characteristic $(0,\beta)$. Then there exists a family of true stopping times τ_r and probability measures $\mathbb{P}^r \in \mathcal{P}(\Omega)$, indexed by $r \in [0,1]$, such that for every $\eta \in L^{\infty}(\bar{\Omega})$,

$$\mu(\eta(\theta,\omega)) = \int_0^1 \mathbb{E}^{\mathbb{P}^r} \eta(\theta = \tau_r, \cdot) \, dr.$$

Moreover, each $\mathbb{P}^r \in \mathcal{P}(\Omega)$ is a martingale measure with characteristic $(0, \beta(t, t \land \tau_r(\omega), \omega_{.\land t})).$

Corollary

For any $Z \in L^{\infty}(\overline{\Omega})$, and any $E \subseteq \Omega$,

$$\sup_{\tau\in\mathcal{T},\mathbb{P}\in\mathcal{Q},\mathbb{P}(E)=1}\mathbb{E}^{\mathbb{P}}Z(\tau,\cdot)=\sup_{\bar{\mathbb{P}}\in\bar{\mathcal{Q}},\bar{\mathbb{P}}(\Theta\times E)=1}\mathbb{E}^{\bar{\mathbb{P}}}Z.$$

< ロ > < 同 > < 回 > < 回 >

Proof outline: For every $s, a \in [0, 1]$ and $E \in \mathcal{F}_s$, we show that

$$\int_{a}^{1} \mathbb{E}^{\mathbb{P}^{r}}(\mathbb{1}(E)(X_{1}-X_{s})) dr = 0.$$

2

Proof outline: For every $s, a \in [0, 1]$ and $E \in \mathcal{F}_s$, we show that

$$\int_{a}^{1} \mathbb{E}^{\mathbb{P}^{r}}(\mathbb{1}(E)(X_{1}-X_{s})) dr = 0.$$



This is done by breaking into two terms: before τ_r :

$$\mathbb{E}^{\mathbb{P}^r}(\mathbb{1}(E)\mathbb{1}(\tau_r > s)(X_{\tau_r} - X_s))$$

after τ_r :

$$\mathbb{E}^{\mathbb{P}^r}(\mathbb{1}(E)(X_1 - X_{s \vee \tau_r}))$$

イロト イ団ト イヨト イヨト

æ

Proof outline: For every $s, a \in [0, 1]$ and $E \in \mathcal{F}_s$, we show that

$$\int_{a}^{1} \mathbb{E}^{\mathbb{P}^{r}}(\mathbb{1}(E)(X_{1}-X_{s})) dr = 0.$$



This is done by breaking into two terms: before τ_r :

$$\mathbb{E}^{\mathbb{P}^r}(\mathbb{1}(E)\mathbb{1}(\tau_r > s)(X_{\tau_r} - X_s))$$

after τ_r :

$$\mathbb{E}^{\mathbb{P}^r}(\mathbb{1}(E)(X_1 - X_{s \vee \tau_r}))$$

イロト イボト イヨト イヨ

Then $\mathbb{E}^{\mathbb{P}^r}(X_1 | \mathcal{F}_s) = X_s$ holds for a countable dense set $s \in [0, 1]$, dr-a.e.. The continuity of X implies that it's a martingale.

The diffusion coefficient can be proven in the same way, replacing X by $X^2 - \int_0^{\cdot} \beta(t, t \wedge \tau_r(\omega), \omega_{\cdot \wedge t}) dt$.

Pricing hedging duality for American options

Combining all previous elements together, we have the main result.

Theorem

Suppose $Z \in C_b(\overline{\Omega})$, then

$$\pi^{A}(Z) = \bar{\pi}(Z) = \sup_{\bar{\mathbb{P}} \in \bar{\mathcal{Q}}} \mathbb{E}^{\bar{\mathbb{P}}} Z = \sup_{\tau \in \mathcal{T}, \mathbb{P} \in \mathcal{Q}} \mathbb{E}^{\mathbb{P}} Z(\tau, \cdot).$$

Similarly, in the case where the statically traded European options g are present,

$$\pi_g^A(Z) = \widehat{\pi}^A(Z) = \overline{\widehat{\pi}}(Z) = \sup_{\bar{\widehat{\mathbb{P}}} \in \widehat{\mathcal{Q}}} \mathbb{E}^{\widehat{\widehat{\mathbb{P}}}} Z = \sup_{\widehat{\tau} \in \widehat{\mathcal{T}}, \widehat{\mathbb{P}} \in \widehat{\mathcal{Q}}} \mathbb{E}^{\widehat{\mathbb{P}}} Z(\widehat{\tau}, \cdot).$$

(日) (四) (日) (日) (日)

Pricing hedging duality for American options

Combining all previous elements together, we have the main result.

Theorem

Suppose $Z \in C_b(\overline{\Omega})$, then

$$\pi^{A}(Z) = \bar{\pi}(Z) = \sup_{\bar{\mathbb{P}} \in \bar{\mathcal{Q}}} \mathbb{E}^{\bar{\mathbb{P}}} Z = \sup_{\tau \in \mathcal{T}, \mathbb{P} \in \mathcal{Q}} \mathbb{E}^{\mathbb{P}} Z(\tau, \cdot).$$

Similarly, in the case where the statically traded European options g are present,

$$\pi_g^A(Z) = \widehat{\pi}^A(Z) = \overline{\widehat{\pi}}(Z) = \sup_{\widehat{\mathbb{P}} \in \widehat{\mathcal{Q}}} \mathbb{E}^{\widehat{\mathbb{P}}} Z = \sup_{\widehat{\tau} \in \widehat{\mathcal{T}}, \widehat{\mathbb{P}} \in \widehat{\mathcal{Q}}} \mathbb{E}^{\widehat{\mathbb{P}}} Z(\widehat{\tau}, \cdot).$$

Further ongoing works include complexity reduction on the measurability of the robust price and optimal super-hedging strategies, hedging multiple American options and numerical implementations.

32/33

Some References:

- Aksamit, A., Deng, S., Obłój, J., & Tan, X. (2019). The robust pricing-hedging duality for American options in discrete time financial markets. *Mathematical Finance*, 29(3), 861–897.
- Guo, I., & Loeper, G. (2021). Path dependent optimal transport and model calibration on exotic derivatives. *The Annals of Applied Probability*, 31(3), 1232–1263.
- Herrmann, S., & Stebegg, F. (2019). Robust pricing and hedging around the globe. *The Annals of Applied Probability*, 29(6), 3348–3386.
- Hobson, D., & Neuberger, A. (2017). Model uncertainty and the pricing of American options. *Finance and Stochastics*, 21(1), 285–329.
- Tiplea, A. C. (2019). Super-replication of American Options in an Uncertain Volatility Model.

Thank you for listening!

< ロ > < 同 > < 三 > < 三 > 、