



Cutting trees revisited

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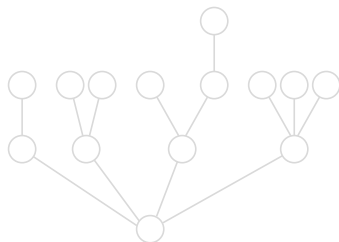
Workshop “Analytic and Probabilistic Combinatorics”,
BIRS, Banff, Canada, 17.11.2022

Cutting down procedure

- Meir & Moon [1970, 1974]:

Cutting down procedure for rooted trees

- 1 Take a rooted tree T
- 2 Choose edge e of T at random
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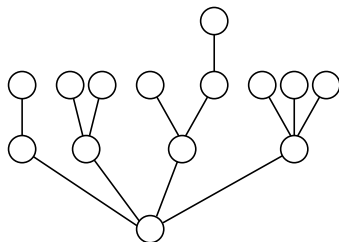


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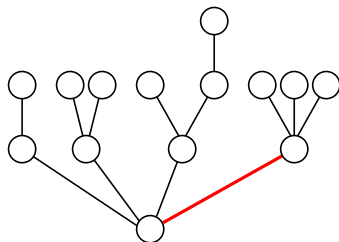


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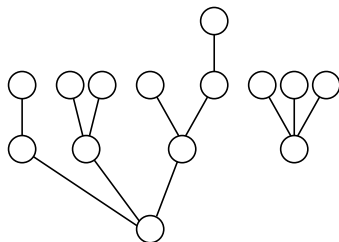


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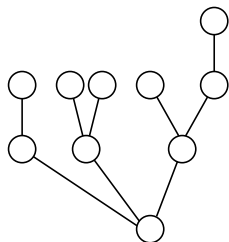


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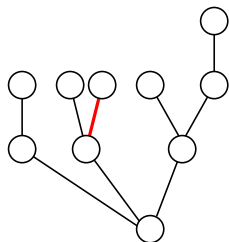


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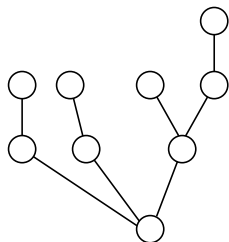


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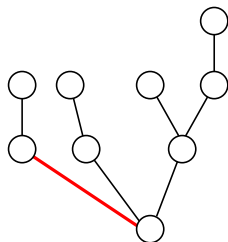


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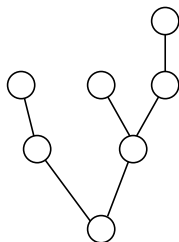


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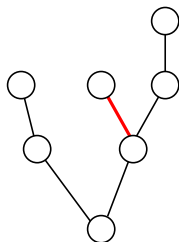


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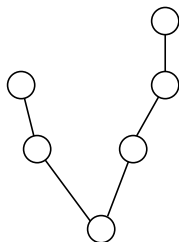


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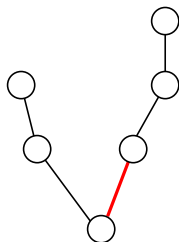


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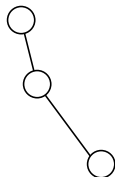


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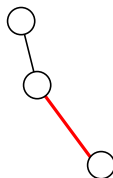


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Number of cuts to isolate root

Meir & Moon (1970, 1974): X_n , number of cuts of size- n tree for two random tree models:

- random Cayley-trees (= rooted labelled trees)
- random recursive trees (= increasingly labelled trees)

Start the cutting down procedure with random size- n tree
 → tree models behave quite different

Expectation/variance for Cayley-trees:

$$\mathbb{E}(X_n) \sim \sqrt{\frac{\pi n}{2}}, \quad \mathbb{V}(X_n) \sim \left(1 - \frac{\pi}{2}\right) \cdot n$$

Expectation/variance for recursive trees:

$$\mathbb{E}(X_n) \sim \frac{n}{\log n}, \quad \mathbb{E}(X_n^2) \sim \frac{n^2}{\log^2 n} \quad \Rightarrow \quad \mathbb{V}(X_n) = o\left(\frac{n^2}{\log^2 n}\right)$$

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Recursive approach

Used recursive description:

$$X_n \stackrel{(d)}{=} 1 + X_{S_n}, \quad S_n : \text{size of subtree containing root}$$

Size of remaining subtree:

$$\text{Cayley-trees: } \mathbb{P}\{S_n = m\} = \binom{n}{m} \frac{m^m (n-m)^{n-m-1}}{(n-1)n^{n-1}}$$

$$\text{Recursive trees: } \mathbb{P}\{S_n = m\} = \frac{n}{(n-1)(n-m)(n-m+1)}$$

G. f. **treatment of recurrences** for first moments yields results

Limitation of approach: only applicable (in direct way) if **randomness is preserved** for remaining tree

→ property only holds for few (important) random tree families

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Further studies via recursive approach

- Pan (2003, 2004, 2006):
 - **characterization of simply gen. tree families** (= cond. GW-trees) **satisfying randomness preservation property**
 - Cayley-trees
 - d -ary trees
 - generalized ordered trees
 - **Rayleigh limiting distribution of X_n**
for such “**very simple tree families**”

$$\frac{X_n}{\sqrt{n}} \xrightarrow{(d)} \text{Rayleigh}(\sigma), \quad \text{density } f_\sigma(x) = \frac{x}{\sigma^2} e^{-\frac{x^2}{2\sigma^2}}, \quad x \geq 0$$

- Cutting down non-crossing trees \rightarrow Rayleigh-limit law
- **Cutting down recursive trees**
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- Fill, Kapur & Pan (2006):

each cut costs a toll depending on size of the tree

→ study **total costs of one-sided and two-sided destruction** of “very simple trees”

→ **limiting distribution results via method of moments**

- Pan & Kuba (2007): application of two-sided destruction to **analysis of Union-Find-algorithms** (maintaining set partitions)

- Drmota, Iksanov, Möhle & Rösler (2009):

stable limit law of number of cuts X_n **for recursive trees**

$$\frac{X_n - \frac{n}{\log n} - \frac{n \log \log n}{\log^2 n}}{\frac{n}{\log^2 n}} \xrightarrow{(d)} Y \sim \text{Stable}(1),$$

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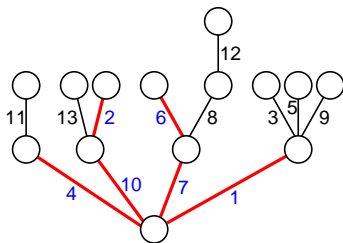
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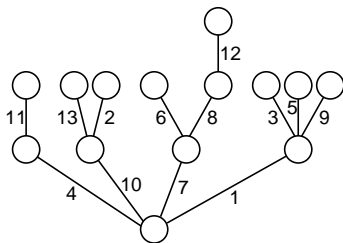
Probabilistic treatments of cutting trees

- Janson (2006):
 - **Description of cutting procedure via records** in edge-labelled trees
 - Record:** edge-label smaller than labels of all ancestor-edges



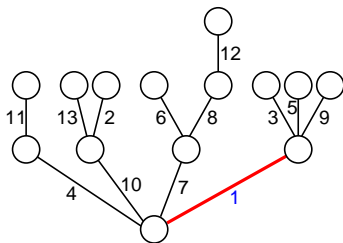
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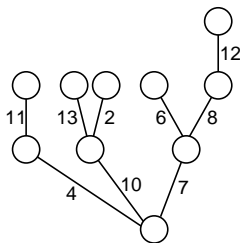
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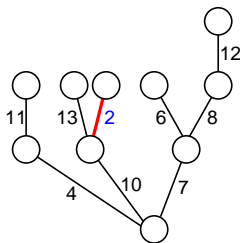
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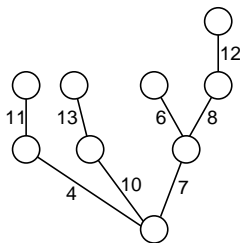
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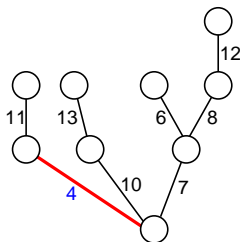
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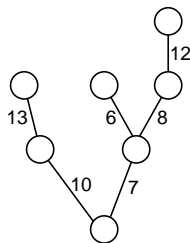
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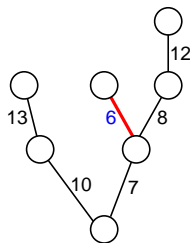
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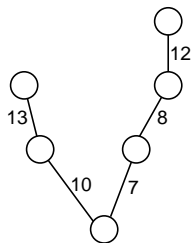
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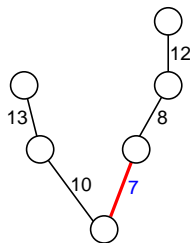
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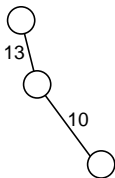
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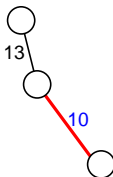
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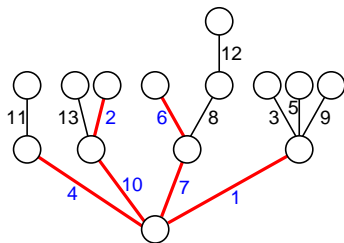
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Cut \leftrightarrow Edge-record

Probabilistic treatments of cutting trees

- Janson (2006):
 - **Rayleigh limit law for all conditioned GW-trees**
(simply generated trees):

$$\frac{X_n}{\sqrt{n}} \xrightarrow{(d)} \text{Rayleigh}(\sigma), \quad \sigma \text{ dependent on offspring-distr.}$$

- Limiting distribution results for **deterministic trees**
- Edge-cutting procedure behaves asympt. as **vertex-cutting procedure**
- Holmgren (2008, 2010, 2011):
 - **Stable limit laws for large class of log n -trees: split trees**
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→ Many further probabilistic treatments related to cutting trees

- Further tree/graph families, extensions and refinements
- Relations to coalescence models

Question: Might recursive approach also be useful to contribute to study of some of such extensions?

- k -cutting trees
- Isolating multiple nodes in trees
- Separating nodes in trees

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k -cut model for rooted trees

- Cai, Devroye, Holmgren & Skerman (2019)
Berzunza, Cai & Holmgren (2020, 2021):

Adapting cutting down procedure:

A vertex has to be cut k -times
before this vertex and its subtrees are discarded.

Considered tree models:

- paths and “path-like trees”
 - conditioned Galton-Watson trees
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k-cuts in paths

k = 1: Cutting down path:

$X_n \stackrel{(d)}{=} \text{number of records}$ in sequence of n i.i.d. $\text{Unif}[0, 1]$ r.v.
 $\stackrel{(d)}{=} \text{number of left-to-right maxima/minima}$ in random permutation
 $\stackrel{(d)}{=} \text{number of cycles}$ in random permutation

Limiting behaviour of X_n :

Goncharov (1942); Shepp-Lloyd (1966):

$$\frac{X_n - \log n}{\sqrt{\log n}} \stackrel{(d)}{\longrightarrow} \mathcal{N}(0, 1)$$

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$k \geq 2$: number of cuts $X_n^{[k]}$ have complicated behaviour,
Cai, Devroye, Holmgren and Skerman (2019):

First two moments:

$$\mathbb{E}(X_n) \sim \eta_k n^{1-\frac{1}{k}}, \quad \mathbb{E}(X_n^2) \sim \gamma_k n^{2-\frac{2}{k}},$$

$$\eta_k = \frac{(k!)^{\frac{1}{k}} \Gamma(\frac{1}{k})}{k-1}, \quad \gamma_k = \frac{\Gamma(\frac{2}{k})(k!)^{\frac{2}{k}}}{k-1} + 2 \cdot \begin{cases} \frac{\pi \cot(\frac{\pi}{k}) \Gamma(\frac{2}{k})(k!)^{\frac{2}{k}}}{2(k-2)(k-1)}, & k > 2, \\ \frac{\pi^2}{4}, & k = 2. \end{cases}$$

Limiting distribution: $\mathcal{L}\left(\frac{X_n^{[k]}}{n^{1-\frac{1}{k}}}\right) \xrightarrow{(d)} \mathcal{L}(\mathcal{B}_k),$

$$\mathcal{B}_k := \sum_{p \geq 1} \mathcal{B}_p, \quad \mathcal{B}_p := (1 - U_p) \left(\prod_{1 \leq j < p} U_j \right)^{1-\frac{1}{k}} S_p, \quad S_p := \left(k! \sum_{1 \leq s \leq p} \left(\prod_{s \leq j < p} U_j \right) E_s \right)^{\frac{1}{k}},$$

$E_j \stackrel{(d)}{=} \text{Exp}(1), \quad U_j \stackrel{(d)}{=} \text{Unif}[0, 1], \quad j \geq 1, \quad \text{mutually independent}$

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Recursive approach

Consider $k = 2$: 2-Cutting a path



For recursive approach **have to take care of auxiliary quantity**:
 number of nodes already cut once

→ “Urn model” with non-deterministic ball replacement scheme:



↦

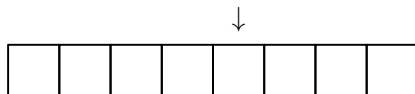


↦

remove random number of bricks (= cutting off)

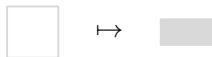
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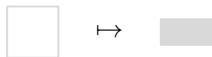
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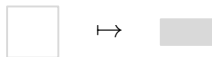
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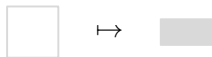
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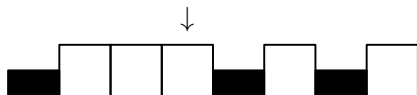
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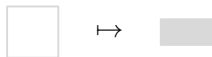
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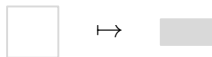
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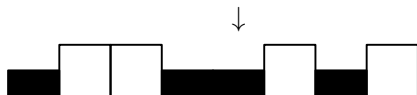
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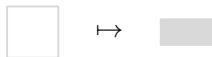
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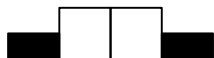
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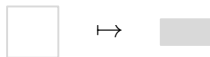
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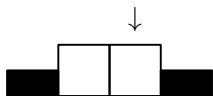
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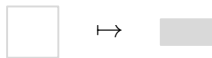
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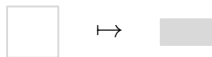
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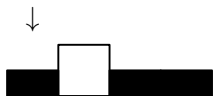
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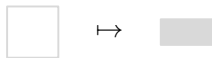
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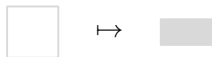
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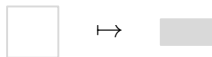
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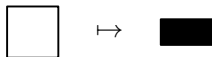
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Stochastic recurrence

$\tilde{X}_{n,j}$: number of cuts to destroy path of length n
starting with j random nodes already cut once

Distributional recurrence:

$$\tilde{X}_{n,j} \stackrel{(d)}{=} V_{n,j} \cdot \tilde{X}_{n,j+1} + (1 - V_{n,j}) \cdot \tilde{X}_{S_1, S_2}, \quad 0 \leq j \leq n, n \geq 1, \quad \tilde{X}_{0,0} = 0,$$

where $V_{n,j} \stackrel{(d)}{=} \text{Bernoulli}(1 - \frac{j}{n})$,

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Generating functions approach

probability generating function $\mathbb{E}(v^{\tilde{X}_{n,j}}) \rightarrow$ **recurrence**

suitable g.f. $\tilde{F} := \tilde{F}(z, x, v) := \sum_{n,j \geq 0} \binom{n}{j} \cdot \mathbb{E}(v^{\tilde{X}_{n,j}}) z^n x^j$

\rightarrow **Linear first-order PDE:**

$$z\tilde{F}_z = v \left(\tilde{F}_x + \frac{zx}{1-z(1+x)} \tilde{F} \right)$$

Explicit solution:

$$\tilde{F}(z, x, v) = e^{\int_x^\infty \frac{z t e^{-\frac{x-t}{v}}}{1-z(1+t)e^{-\frac{x-t}{v}}} dt}$$

Solution of original problem: vanish auxiliary quantity $x = 0$:

$$F(z, v) := \tilde{F}(z, 0, v) = \sum_{n \geq 1} \mathbb{E}(v^{X_n}) z^n$$

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Generating functions approach

probability generating function $\mathbb{E}(v^{\tilde{X}_{n,j}}) \rightarrow$ **recurrence**

suitable g.f. $\tilde{F} := \tilde{F}(z, x, v) := \sum_{n,j \geq 0} \binom{n}{j} \cdot \mathbb{E}(v^{\tilde{X}_{n,j}}) z^n x^j$

\rightarrow **Linear first-order PDE:**

$$z\tilde{F}_z = v \left(\tilde{F}_x + \frac{zx}{1-z(1+x)} \tilde{F} \right)$$

Explicit solution:

$$\tilde{F}(z, x, v) = e^{\int_x^\infty \frac{zte^{\frac{x-t}{v}}}{1-z(1+t)e^{\frac{x-t}{v}}} dt}$$

Solution of original problem: **vanish auxiliary quantity $x = 0$:**

$$F(z, v) := \tilde{F}(z, 0, v) = \sum_{n \geq 1} \mathbb{E}(v^{X_n}) z^n$$

$$\Rightarrow F(z, v) = e^{\int_0^\infty \frac{zte^{-\frac{t}{v}}}{1-z(1+t)e^{-\frac{t}{v}}} dt}$$

Moments

Expectation: $\mathbb{E}(X_n) = H_n + \sum_{\ell=1}^n \frac{Q(\ell)}{\ell},$

with $Q(n) = \sum_{\ell=0}^{n-1} \frac{(n-1)^\ell}{n^\ell} = \int_0^\infty \left(1 + \frac{x}{n}\right)^{n-1} e^{-x} dx,$ Ramanujan's Q-function

Asymptotics of m -th integer moments:

$$\mathbb{E}\left(\left(\frac{X_n}{\sqrt{n}}\right)^m\right) \sim \frac{m!}{\Gamma(1 + \frac{m}{2})} \cdot [w^m] e^{\frac{\sqrt{2}w \arccos\left(-\frac{w}{\sqrt{2}}\right)}{\sqrt{1-\frac{w^2}{2}}}}, \quad m \geq 0$$

Exponent $\varphi(w) := \frac{\sqrt{2}w \arccos\left(-\frac{w}{\sqrt{2}}\right)}{\sqrt{1-\frac{w^2}{2}}} = \sum_{m \geq 1} \frac{2^{\frac{m}{2}} \Gamma(\frac{m}{2}) \Gamma(\frac{m}{2}+1)}{m!} w^m$

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Moment generating function

Fréchet and Shohat moment conv. thm. $\Rightarrow \frac{X_n}{\sqrt{n}} \xrightarrow{(d)} X$,

with X characterized via moments: $\mathbb{E}(X^m) = \frac{m!}{\Gamma(1+\frac{m}{2})} [w^m] e^{\varphi(w)}$

Moment generating function $M(s) = \mathbb{E}(e^{sX}) = \sum_{m \geq 0} \frac{s^m}{\Gamma(1+\frac{m}{2})} \cdot [w^m] e^{\varphi(w)}$

Use Mittag-Leffler-transform:

$$f(z) = \sum_{n \geq 0} f_n z^n \xrightarrow{B_\alpha} \hat{f}(z) = \sum_{n \geq 0} f_n \frac{z^n}{\Gamma(1 + \alpha n)}$$

$$B_\alpha(f(z)) = \frac{1}{2\pi i} \int_{C-i\infty}^{C+i\infty} \frac{E_\alpha(zt)}{t} f\left(\frac{1}{t}\right) dt, \quad \text{Mittag-Leffler-fct. } E_\alpha(z) = \sum_{n \geq 0} \frac{z^n}{\Gamma(1 + \alpha n)}$$

Representation of m.g.f.:

$$M(s) = \frac{1}{2\pi i} \int_{C-\infty}^{C+i\infty} \left(1 + \frac{2}{\sqrt{\pi}} \int_0^{s^2 t^2} e^{-\tau^2} d\tau \right) e^{s^2 t^2 + \frac{\sqrt{2}}{t} \arccos\left(-\frac{1}{\sqrt{2t}}\right)} dt, \quad \Re C > \frac{1}{\sqrt{2}}$$

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Recursive approach for general k

General k : adaptations for recursive approach

- Require $k - 1$ auxiliary quantities:
 j_1 nodes cut once, \dots , j_{k-1} nodes cut $(k - 1)$ -times
- "Urn model"-description with k types of balls
- Generating functions approach \rightarrow linear first-order PDE:

$$z\tilde{F}_z = v \left(\tilde{F}_{x_1} + x_1\tilde{F}_{x_2} + x_2\tilde{F}_{x_3} + \dots + x_{k-2}\tilde{F}_{x_{k-1}} + \frac{x_{k-1}z\tilde{F}}{1 - z(1 + x_1 + x_2 + \dots + x_{k-1})} \right)$$

- PDE is explicitly solvable
- Vanishing all auxiliary variables $x_1, \dots, x_{k-1} = 0$
 \rightarrow explicit solution for g.f. $F_k(z, v) = \sum_{n \geq 1} \mathbb{E}(v^{X_n^{[k]}}) z^n$:

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Limiting behaviour

Asymptotic behaviour of m -th integer moment:

$$\mathbb{E} \left(\left(\frac{X_n}{n^{1-\frac{1}{k}}} \right)^m \right) \sim \frac{m!}{\Gamma(1 + \frac{(k-1)m}{k})} \cdot [w^m] e^{\varphi(w)},$$

with **exponent**:

$$\begin{aligned} \varphi(w) &= \sum_{m=1}^{\infty} \frac{(k!)^{\frac{m}{k}} \Gamma(\frac{m}{k} + 1) \Gamma(\frac{(k-1)m}{k})}{m!} w^m \\ &= k! w \int_0^{\infty} \frac{dx}{x^k - k!wx + k!} \\ &= \sum_{j=1}^k \frac{x_j w}{k - (k-1)x_j w} \ln(-x_j), \quad x_j \text{ roots of } p(x) = x^k - k!wx + k! \end{aligned}$$

Limiting behaviour

Convergence in distribution $\frac{X_n}{n^{1-\frac{1}{k}}} \xrightarrow{(d)} X,$

X characterized via moments:

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k -cutting trees

Berzunza, Cai & Holmgren (2020, 2021); Wang (2021):
Limiting distribution result for conditioned GW-trees:

$$\frac{X_n}{\sigma^{\frac{1}{k}} n^{1-\frac{1}{2k}}} \xrightarrow{(d)} X,$$

with X characterized via moments or via functional of Brownian continuum random tree

Recursive approach:

- only applicable for “very simple trees”
- yields first-order linear PDE (for Cayley-trees)
- PDE does not seem to be explicitly solvable
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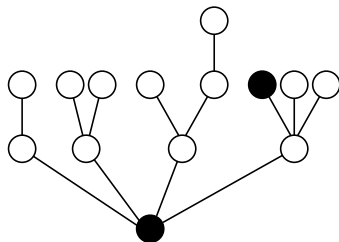
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Isolating a set of nodes in trees

Cutting algorithm for isolating multiple nodes:

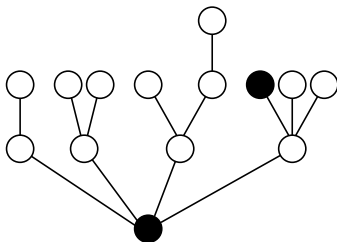
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- Select a vertex/edge at random
- Remove vertex/edge and discard all subtrees not containing any vertex of S
- Iterate procedure and terminate when all nodes of S are isolated/removed



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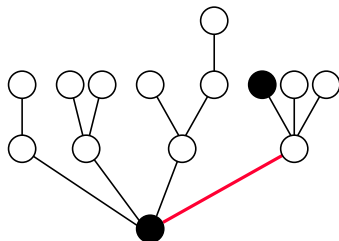
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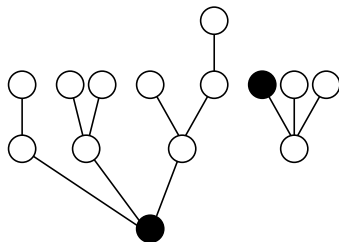
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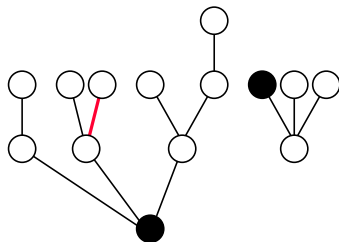
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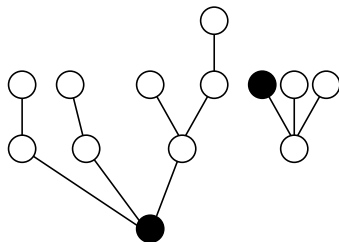
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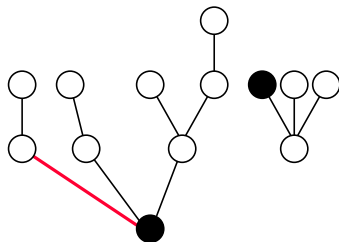
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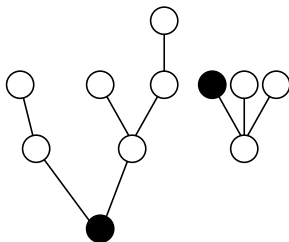
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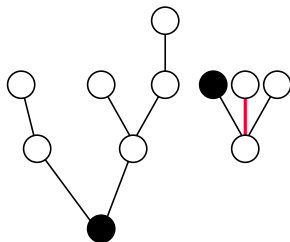
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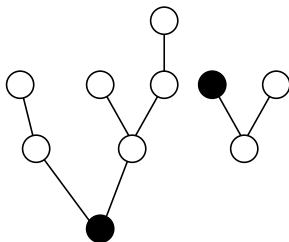
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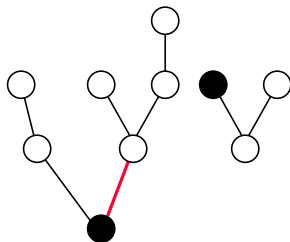
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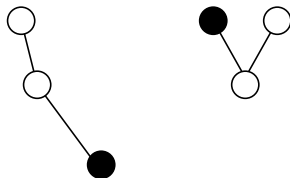
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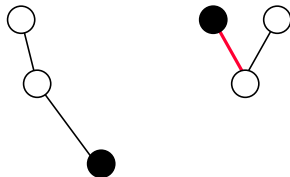
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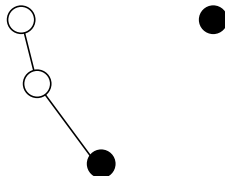
- Take a tree T with a distinguished set $S \subseteq V(T)$ of nodes
- Select a vertex/edge at random
- Remove vertex/edge and discard all subtrees not containing any vertex of S
- Iterate procedure and terminate when all nodes of S are isolated/removed



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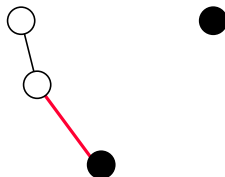
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Previous studies for number of cuts

- Addario-Berry, Broutin & Holmgren (2014):
isolating ℓ random nodes in Cayley-trees:

$$\frac{X_n^{[\ell]}}{\sqrt{n}} \xrightarrow{(d)} \chi_{2\ell},$$

$\chi_{2\ell}$: chi-distributed r.v. with 2ℓ degrees of freedom,

$$\text{density } f_{\ell}(x) = \frac{x^{2\ell-1}}{2^{\ell-1}(\ell-1)!} e^{-\frac{x^2}{2}}, \quad x > 0$$

- Kuba & Panholzer (2014):
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$$\frac{\log n}{n} X_n^{[\ell]} \xrightarrow{(d)} \text{Beta}(\ell, 1)$$

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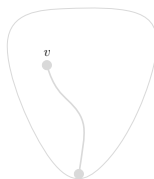
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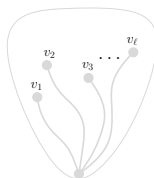
Isolation of multiple nodes

Consider multiple isolation in Cayley-trees:

- “random path”: all nodes on path from root to random node



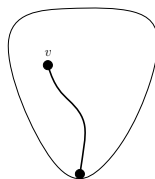
- “random ancestor-tree”: all nodes on each path from root to ℓ random nodes



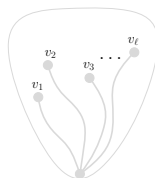
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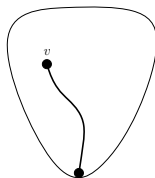
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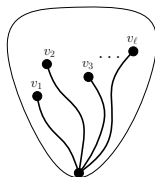
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Recursive approach

$X_{n,\ell}$: **number of cuts** to isolate all nodes in ancestor-tree of ℓ random nodes

- Suitable g.f. $F(z, u, v) := \sum_{n,\ell} \frac{n^{\ell-1}}{\ell!} \binom{n}{\ell} \cdot \mathbb{E}(\sqrt{X_{n,\ell}}) z^n u^\ell$
- \rightarrow quasi-linear first-order PDE
- **Explicit solution:** ($T(x) = xe^{T(x)}$ tree function)

$$F(z, u, v) = \frac{1-v}{v} \log\left(\frac{1}{1-vT(z)}\right) + T\left((1+u) \cdot \frac{T(z) - \frac{1-v}{v} \log\left(\frac{1}{1-vT(z)}\right)}{e^{T(z) - \frac{1-v}{v} \log\left(\frac{1}{1-vT(z)}\right)}}\right)$$

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Suitable to gain further results on multiple isolation
in **Cayley-trees** (very simple trees):

- isolating **all descendants** of random node or ℓ random nodes
- isolating all leaves in tree
- behaviour if **number ℓ of nodes grows** with size n

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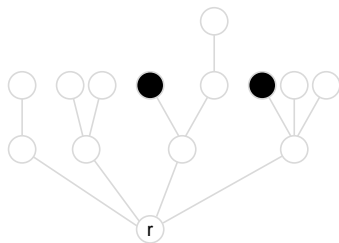
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Separating nodes in trees

Burghart (2022): far-reaching generalization of cutting procedure
to **separating nodes in graphs**

Specific case: separating a set $P \subseteq V(T)$ of nodes from root r in
tree T

→ Stop cutting procedure to isolate root
if remaining subtree does not contain any node from P

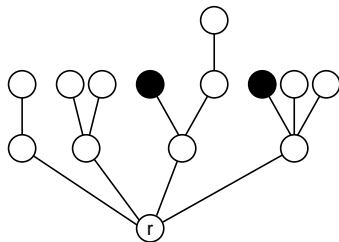


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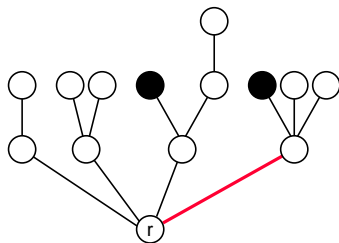


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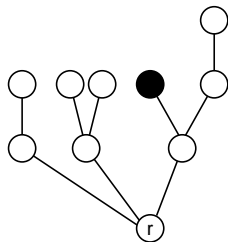


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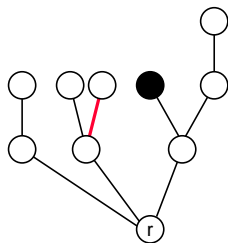


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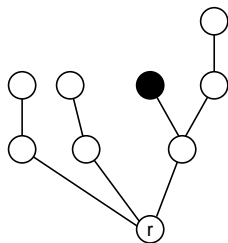


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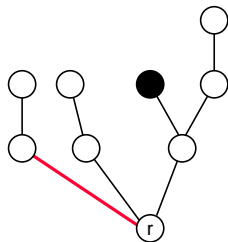


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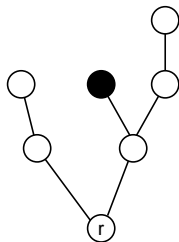


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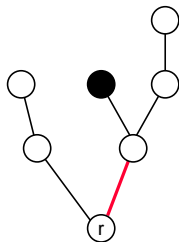


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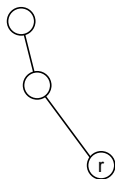


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Analysis of separation procedure

Interesting quantities:

Y_n : number of cuts until all nodes from P are separated

R_n : size of the remainder tree when all nodes are separated

Apply recursive approach to separation procedures
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Recursive approach → easily gives **explicit solution for g.f.**

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Separating all leaves

Recursive approach more involved:

→ requires **auxiliary parameters**

- # leaves that are “active” during cutting procedure
(leaf has not been separated)
- # leaves that are “inactive” during cutting procedure
(internal node in original tree)

→ **linear first-order PDE** involving evaluations of tree function

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Results for separating leaves

Size R_n of remainder tree: $R_n \xrightarrow{(d)} R$, R discrete law

Probability g.f. $\rho(v) = \mathbb{E}(v^R)$:

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Probabilities for small remainder tree size/expectation:

$$\mathbb{P}\{R = 0\} = 1 - \frac{1}{e} \int_0^1 \frac{1}{1 - K(t)} dt \approx 0.462117, \quad (\text{separating} = \text{isolating})$$

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End of talk

