# Hybrid Data Assimilation without Ensemble Filtering

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Probabilistic Approaches to Data Assimilation for Earth Systems BIRS, Banff, Canada 18-21 February 2013

Contributions from: D. Kleist, D. Parrish, R. Treadon, and J. Whitaker

Similar to presentations given recently at Meteo-France and NCEP

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# Outline



Problem Statement & Experimental Setting



- Illustration from Single-Cycle
- 3 Ensemble Spread Examination



Cycled-Analysis Evaluation





Forecast Verification vs Analysis





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Illustration from Single-Cycle Ensemble Spread Examination Cycled-Analysis Evaluation Forecast Verification vs Observations Forecast Verification vs Analysis Summary Variational Formulation

Filter-Free Ensemble GEOS Data Assimilation System GEOS IAU-based 3dVar GEOS IAU-based Hybrid 3dVar Experimental Setting

# Variational Formulations

FGAT 3dVar-ensemble Hybrid:

$$J(\delta \mathbf{x}) = \frac{1}{2} \, \delta \mathbf{x}^{\mathsf{T}} \mathbf{B}_{h}^{-1} \delta \mathbf{x} + \frac{1}{2} \sum_{k=1}^{\mathsf{K}} [\mathbf{H}_{k} \delta \mathbf{x} - \mathbf{d}_{k}]^{\mathsf{T}} \mathbf{R}_{k}^{-1} [\mathbf{H}_{k} \delta \mathbf{x} - \mathbf{d}_{k}] + J_{x}$$

where

- $\mathbf{B}_h = \beta \mathbf{B} + (1 \beta) \mathbf{B}_e \circ \mathbf{C}$  is a *hybrid* of static and ensemble-based error covariances, **B** and  $\mathbf{B}_e$  respectively;
- C is a localization error covariance of compact support;
- the incremental solution becomes  $\delta \mathbf{x} = \delta \mathbf{x}_0 + \sum_m^M \delta \mathbf{x}_m^e \circ \alpha_m$ , for an ensemble with a total of *M* members,  $\delta \mathbf{x}_m^e$ ;
- NCEP and GMAO get  $\delta x_m^e$  by using the EnKF analyses plus inflation.
- NCEP and GMAO recenter EnKF analyses about hybrid analysis.



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# **Problem Statement**

- Hybrid DA includes: re-centering plus inflation
- Evaluations in GEOS DAS suggest:
  - Hybrid approach provides noticeable improvements only when using additive inflation, i.e., EnKF alone doesn't do it
  - Forecasts from EnKF analyses plus additive inflation result in mild spread within the background time window
  - It seems that much of the initial (analysis) spread can be simulated with additive inflation alone
  - Appreciable background spread is obtained in the latter case

*Question: how does hybrid-DA perform when the ensemble filter is dropped and an ensemble of analyses is created from simply additively inflating the central analysis?* 



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# Reasoning behind the filter-free approach

Hybrid implementations of ensemble-based analysis have a member increment be:

 $\delta \mathbf{x}_i^a = \delta \mathbf{x}_i^o + \delta \mathbf{x}^r + \delta \mathbf{e}_i$ 

where:

- $\delta \mathbf{x}_{i}^{o}$  increment due to observations, e.g., EnKF increment
- $\delta \mathbf{x}^r$  increment due to re-centering

 $\delta e_i$  - random additive perturbation to boost model error Remarks:

- **1**  $\delta \mathbf{e}_i$  does not represent model error and is redundant wrt  $\delta \mathbf{x}_i^o$
- 2 in a dual-resolution context  $\delta \mathbf{x}^r$  might as large as  $\delta \mathbf{x}_i^o$
- Solution when magnitude of δe<sub>i</sub> is comparable to that of δx<sup>o</sup><sub>i</sub> the role of ensemble analyses is downplayed
- (4) if (2) and (3) hold, re-centering and inflation might be all that's needed

The present work evaluates the case when  $\delta x_i^0$  is ignored; that is, the ensemble is generated from randomly-inflated,  $\delta e_i$ , central analysis.



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Illustration from Single-Cycle Ensemble Spread Examination Cycled-Analysis Evaluation Forecast Verification vs Observations Forecast Verification vs Analysis Summary Variational Formulation Filter-Free Ensemble **GEOS Data Assimilation System** GEOS IAU-based 3dVar GEOS IAU-based Hybrid 3dVar Experimental Setting

#### Atmospheric GCM

- Fully ESMF-based
- Cubed-sphere hydrostatic dynamical core
- RAS-Bacmeister convective physics
- Chou-Suarez radiation scheme
- Koster et al. catchment land-surface model
- Lock et al. turbulence physics
- Interactive ozone
- Interactive GOCART aerosols
- OSTIA-prescribed SST

#### Analysis: GSI

- FGAT 3D-Var
- IAU-based assimilation
- TLNMC balance
- JCSDA CRTM
- Double-PCG minimization

#### Ensemble filter

- ESRL-NCEP EnKF
- Full obs but ozone and precip

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Illustration from Single-Cycle Ensemble Spread Examination Cycled-Analysis Evaluation Forecast Verification vs Observations Forecast Verification vs Analysis Summary Variational Formulation Filter-Free Ensemble GEOS Data Assimilation System GEOS IAU-based 3dVar GEOS IAU-based Hybrid 3dVar Experimental Setting

# Schematic of GEOS IAU-based 3dVar

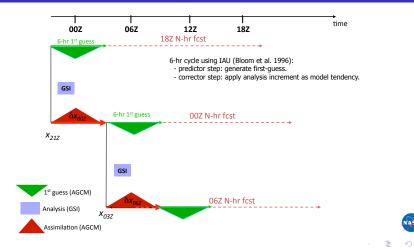
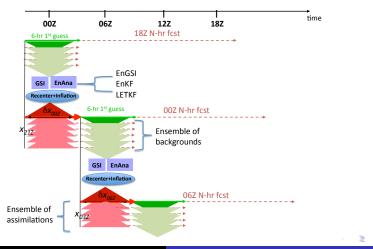


Illustration from Single-Cycle Ensemble Spread Examination Cycled-Analysis Evaluation Forecast Verification vs Observations Forecast Verification vs Analysis Summary Variational Formulation Filter-Free Ensemble GEOS Data Assimilation System GEOS IAU-based 3dVar GEOS IAU-based Hybrid 3dVar Experimental Setting

## Schematic of IAU-based Hybrid 3dVar



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#### Hybrid Experimental Setting

- Central DAS: 0.5° outer and inner loops; 72-levels
- 32 Ensemble Forecasts: 1.0°; 72-levels
- GSI Hybrid/Static B: 50% / 50%
- TLNMC applied to both static & hybrid covariances
- Vertical & horizontal localizations applied to ensemble B
- Add/ve perturbations scaled from NMC-like 48-24hr forecasts
- Experiment period (after spin up): April 2012



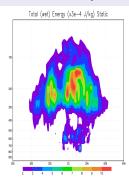
Instantaneous Increment Effect of inflation

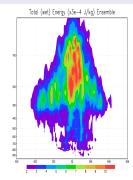
### Analysis Increment as Total Energy for 00 UTC on 1 Jun 2012

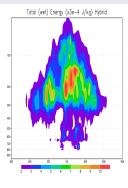
Static-Only

32-mem Ens-Only

Hybrid (50%/50%)

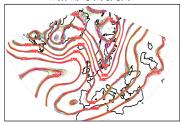








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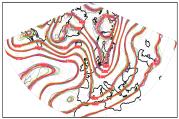
Instantaneous Increment Effect of inflation

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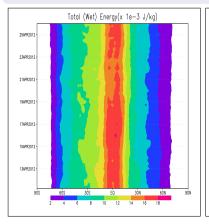
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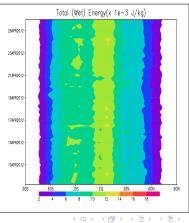
Time Series of Spread Global Spread

#### Evolution of 6-hr Background Spread

EnKF-based hybrid

Filter-Free hybrid





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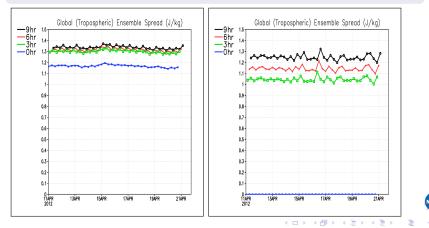
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Time Series of Spread Global Spread

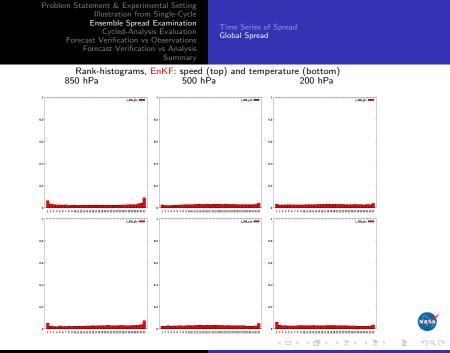
#### Spread within 9-hr Background Period

#### EnKF-based hybrid

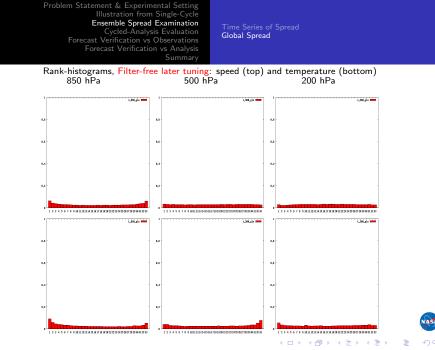
Filter-Free hybrid



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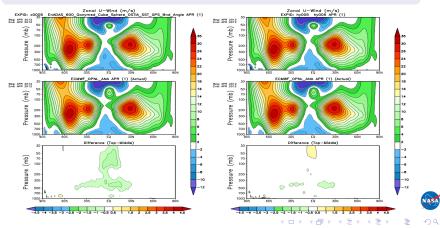
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Comparison with Other Analyses Observations Contributions

#### Comparison w/ ECMWF: Zonally-Averaged Monthly Mean U-Wind

Control 3d-Var

EnKF-based hybrid



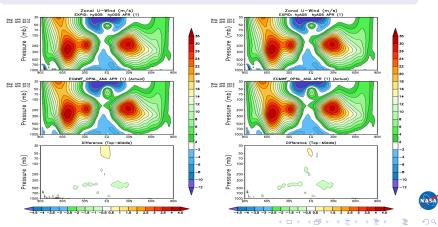
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Comparison with Other Analyses Observations Contributions

#### Comparison w/ ECMWF: Zonally-Averaged Monthly Mean U-Wind

EnKF-based hybrid

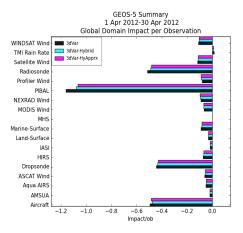
#### Filter-Free hybrid



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Comparison with Other Analyses Observations Contributions

#### Observation Impact on Analysis: April 2012 (Imp/ob)

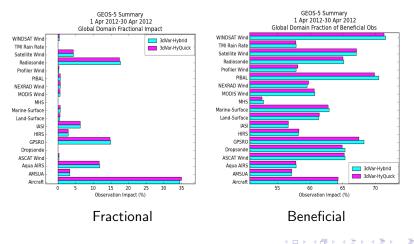




Note: GPS removed on purpose since data identifier (KX) is messed in diagnostic file for control

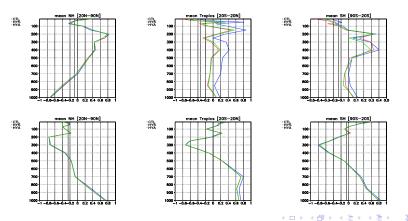
Comparison with Other Analyses Observations Contributions

#### Observation Impact on Analysis: April 2012



Observations fit to background Observations fit to forecast

# RAOB fits to background: BiasZonal Winds (top); Temperature (bottom)NHTropicsSH

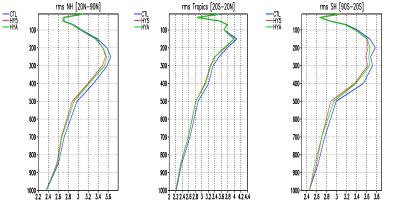




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Observations fit to background Observations fit to forecast

# Zonal wind RAOB fits to background: RMS NH Tropics SH



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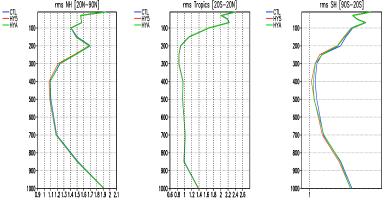
Observations fit to background Observations fit to forecast

#### Zonal wind RAOB fits to 24-hour forecast: RMS NH Tropics SH rms NH [20N-90N] rms Tropics [20S-20N] rms SH [90S-20S] -CTL HY5 HYA -CTL HY5 HYA -CTL HY5 HYA 100 100 100 200 200 200 300 300 300 400 400 400 500 500· 500· 600 600· 600 · 700 700· 700· 800 800· 800· 900 -900 900 · 1000 1000 1000 22242628 3 32343638 4 4244 21 24 27 3 33 36 39 42 45 ťι 36 39 24 27 12



Observations fit to background Observations fit to forecast

# Temperature RAOB fits to 24-hour forecast: RMS NH Tropics SH Image: Tropics [205-201] Image: Tropics [205-201]



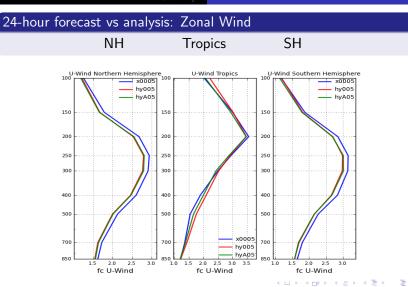
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Hybrid Data Assimilation without Ensemble Filtering

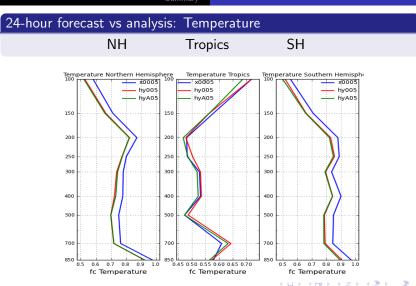
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Forecast RMS Error Forecast Anomaly Correlation



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Forecast RMS Error Forecast Anomaly Correlation



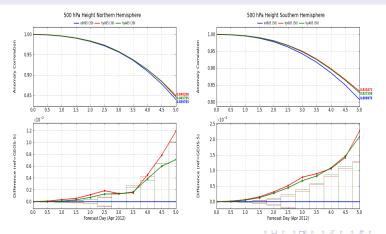
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Forecast RMS Error Forecast Anomaly Correlation

#### Anomaly Correlations: H500

#### Northern Hemisphere

#### Southern Hemisphere





# Summary

#### Main Points

- Overall 3d-hybrid approach gives positive results in GEOS DAS with noticeable reduction of model biases and improved skill scores
- Filter-free scheme works just as well as EnKF in sustaining ensemble
- Would be nice to study skill of NMC-like perturbations in an EPS

#### Advantages of Filter-Free Hybrid

- Really inexpensive way of generating ensemble
- Avoids need to maintain two analysis systems
- Avoids contradictions when calculating adjoint-based obs impact

#### Still, could it be the EnKF is not properly tuned? See Amal's presentation



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