

FLOWS

Typical theory assumptions

Complete

Compact phase
space

All periodic orbits
non-degenerate

N-body Practice:

Incomplete

(Singularities: $r_{ij} \rightarrow 0$)

Non-compact
phase space

($r_{ij} \rightarrow \infty$)

All periodic
orbits degenerate

(Symmetries)

Goal: Make the N-body flow

(A) Complete: remove collision singularities!
Regularize binaries. Blow up triples (& higher?)

(B) Symmetry-free: remove symmetries by symplectic reduction.

(C) Live on a compact space:
add boundaries at the ends corresponding to escape.

(A) and (B): done! for the planar 3 body problem.
Partial progress: spatial 3 body problem
& planar 4 body problem

(C): open

Joint w Rick Moeckel. U of
Minn.

Partial History

(d, N) = (dim. of ambient space, Number of bodies)

(B): Reduction. Lagrange [1772] d arbitrary, $N = 3$.

(B): Symplectic Reduction. Meyer; Marsden-Weinstein [1974]

(A): Regularization method $d=2$. Levi-Civita [1921]
for binary collisions. Initially: perturbed Kepler

(A) and (B)! Lemaitre [1954]: $d=2$, $N=3$;
& $d=3$, $N=3$ but w/ coord. singularities at collinearity

(A): Regularization method $d=3$. Kuustanheimo-Steifel [1965]

(B): Regularization, N arbitrary (& democratic). Heggie [1970]. $d=2$ & 3

(A): Blow-up Method. McGehee [1974]

for triple and higher collisions.

(C): Partial compactification of infinity: C. Robinson [1984]

Partial Results:

$(d, N) = (\text{dim. of ambient space, Number of bodies})$

$(2, 3)$: planar 3-body problem: (A) and (B) Done. (arXiv: (RM)²)

regularized reduced phase space = $T^*(\mathbb{CP}^1) \times T^*([0, \infty))$

regularized shape sphere

size r

symp. form: 'twisted' when ang. mom. nonzero

$$r^2 = I = \frac{\sum m_i m_j r_{ij}^2}{\sum m_i}$$

$(2, 4)$: planar 4-body problem: (A) and (B) in progress (looks good)

regularized reduced phase space = $T^*(K3) \times T^*([0, \infty))$

regularized shape space

size r

symp. form: 'twisted' when ang. mom. nonzero

$(3, 3)$: spatial 3-body problem: in progress (problematic)

regularized reduced phase space = $T^*(\mathbb{CP}^2) \times T^*([0, \infty)) \times_f \mathcal{O}$

regularized shape space

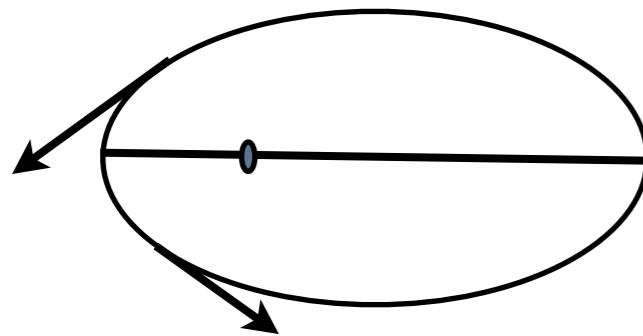
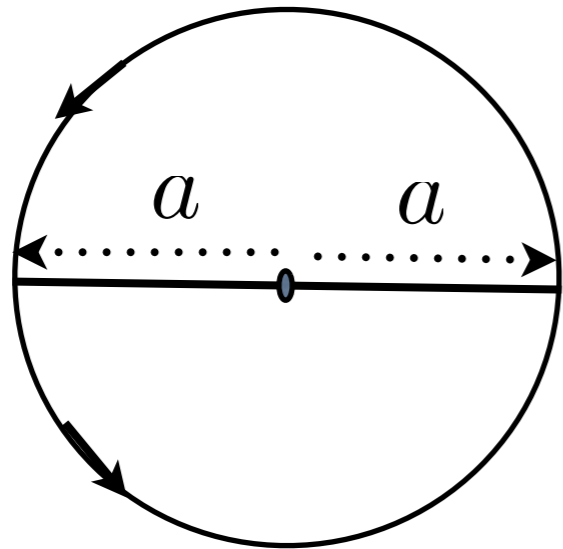
size r

fiber product
over reg. shape
space

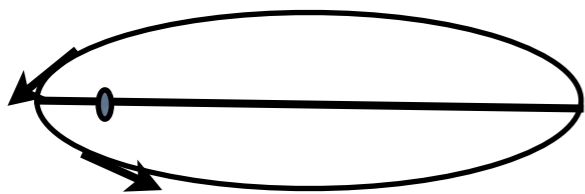
two-sphere bundle over
reg. shape space
fiber: instantaneous
Euler rigid body

(A): Levi-Civita Regularization. $d = 2$

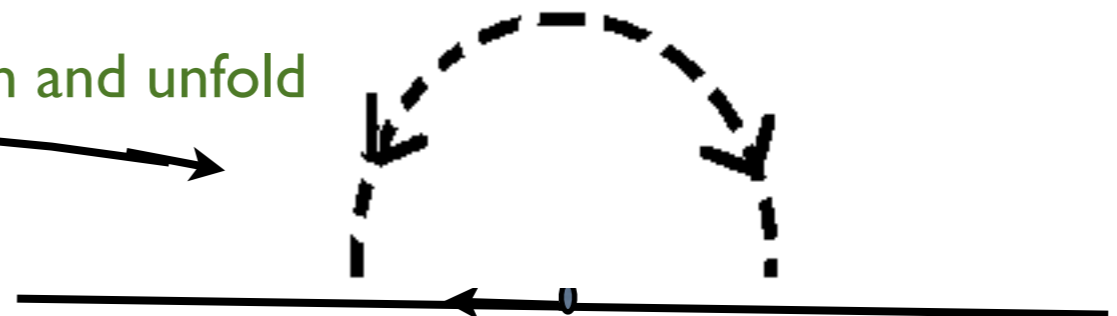
$$H_K = \frac{1}{2}|\dot{q}|^2 - \frac{1}{|q|} = \frac{-1}{2a} \quad ; q \in \mathbb{C} = \mathbb{R}^2$$



Kepler: $\ddot{q} = \frac{-\beta q}{|q|^3}$



cut open and unfold



$$z^2 = q$$

2:1 branched cover

$$\frac{d}{d\tau} = |q| \frac{d}{dt}$$

slow time down as approach collision $q=0$

$$\implies \frac{d^2 z}{d\tau^2} = H_K z \quad \text{harm. oscillator!}$$

Derivation of L-C using Jacobi-Maupertuis [J-M]

$$ds_{JM}^2 = 2(H - V)ds_{Kin}^2 \iff \text{solutions to Newton's eq. w Energy } H$$

so:

$$ds_{JM,Kepl}^2 = 2\left(\frac{-1}{2a} + \frac{1}{|q|}\right)|dq|^2 \iff \text{Kepler. with Energy } \frac{-1}{2a}$$

$q = z^2 \implies dq = 2zdz$:L.C. var. change

$$= 2\left(\frac{-1}{2a} + \frac{1}{|z|^2}\right)4|z|^2|dz|^2$$

$$= 2\left(\frac{-4|z|^2}{2a} + 4\right)|dz|^2$$

$$= 2\left(E - \frac{\omega^2|z|^2}{2}\right)|dz|^2$$

$$E = 4, \quad \omega = \frac{2}{\sqrt{a}}$$

$$= ds_{JM,Harm}^2$$

(2,3) CASE

three Levi-Civita squaring maps:

$$z_{ij}^2 = Q_{ij}$$

& the time change:

$$\frac{d}{d\tau} = r_{12}r_{23}r_{31} \frac{d}{dt}$$

(A): reg.

regularizes all binary collisions !

$$Q_{12} + Q_{23} + Q_{31} = 0$$

$$\implies z_{12}^2 + z_{23}^2 + z_{31}^2 = 0$$

(B): reduce

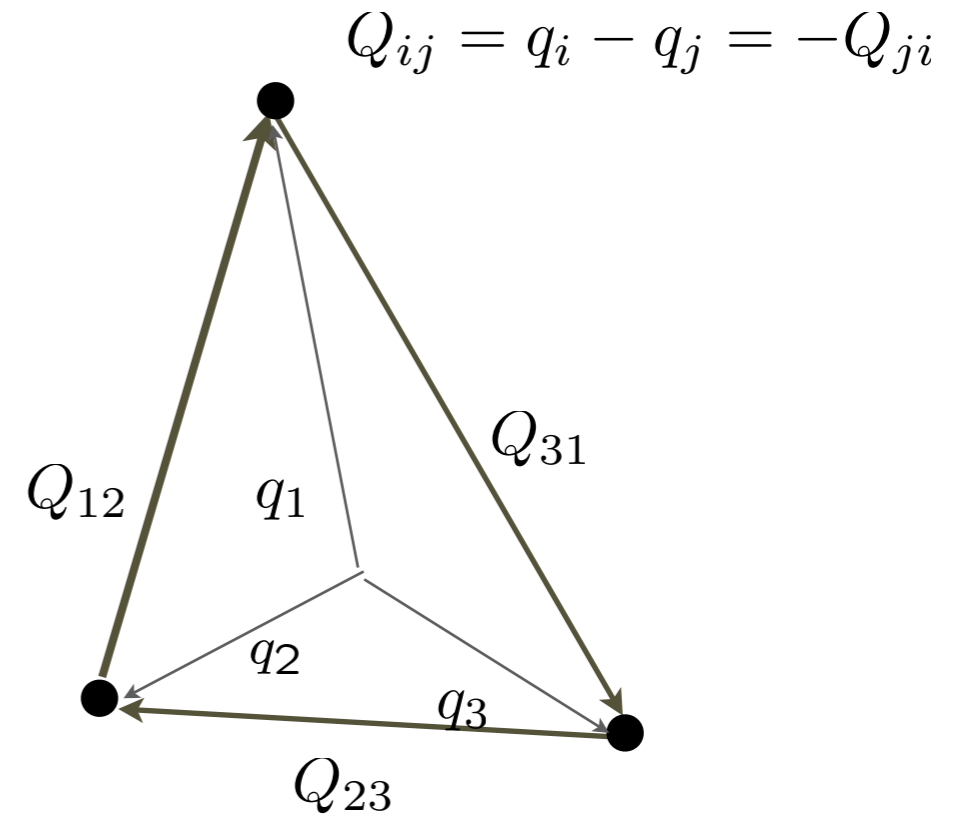
Regularized shape space = $\{[z_{12}, z_{23}, z_{31}] \in \mathbb{C}\mathbb{P}^2 : z_{12}^2 + z_{23}^2 + z_{31}^2 = 0\}$

a conic in the complex projective plane



$S^2 = \mathbb{C}\mathbb{P}^1 =$ standard shape sphere = $\{[Q_{12}, Q_{23}, Q_{31}] \in \mathbb{C}\mathbb{P}^2 : Q_{12} + Q_{23} + Q_{31} = 0\}$

a complex projective line in the complex projective plane



(*) recall: homogeneous coordinates on complex projective n-space

$$[Z_0, Z_1, \dots, Z_n] = [\lambda Z_0, \lambda Z_1, \dots, \lambda Z_n],$$
$$\lambda \in \mathbb{C}, \lambda \neq 0, (Z_0, Z_1, \dots, Z_n) \neq (0, 0, \dots, 0)$$

(*) vector \rightarrow homogeneous coordinates implements reduc. by rotation & scaling

Well-known: conic in $\mathbb{CP}^2 \cong \mathbb{CP}^1$

Explicit map: $\mathbb{CP}^1 = \{[x_1, x_2]\} \rightarrow \text{Our Conic} = \{z_{12}^2 + z_{31}^2 + z_{23}^2 = 0\}$ by:

$$z_{12} = 2ix_1x_2 \quad z_{31} = x_1^2 + x_2^2 \quad z_{23} = i(x_1^2 - x_2^2)$$

So $\mathbb{CP}^1 =$ regularized shape sphere. To visualize...

Combine w/

Affine coordinates: $v = \frac{x_2}{x_1} \in \mathbb{C}\{\infty\}$

or Stereo. projection: $c = \text{stereo}(x_1, x_2) \in S^2 \subset \mathbb{R}^3$

Use binary collisions as landmarks:

$$0 = r_{12} = |Q_{12}| = |z_{12}^2| = |2x_1x_2|^2 \implies [x_1, x_2] = [1, 0] \text{ or } [0, 1]$$

$$0 = r_{31} = |Q_{31}| = |z_{31}^2| = |x_1^2 + x_2^2|^2 \implies [x_1, x_2] = [1, i] \text{ or } [0, -i]$$

$$0 = r_{23} = |Q_{23}| = |z_{23}^2| = |x_1^2 - x_2^2|^2 \implies [x_1, x_2] = [1, 1] \text{ or } [0, -1]$$

Regularized Shape Sphere -- round version after stereographic projection

Coordinates $(c_1, c_2, c_3) \in \mathbb{R}^3$.

Can choose projection so

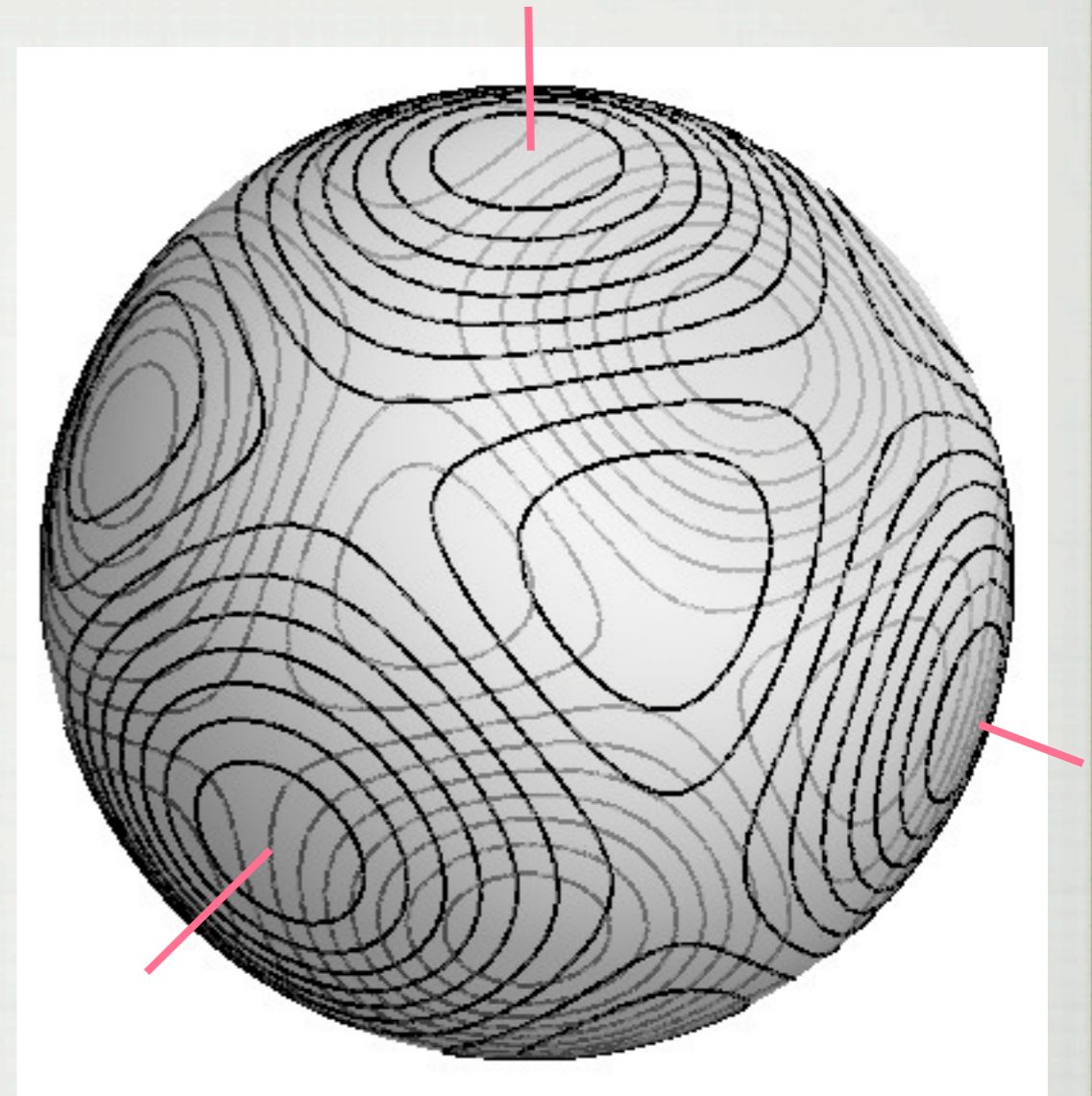
$$\begin{aligned} \rho_{12} &= c_1^2 + c_2^2 & \rho_{ij} &= r_{ij} / \sqrt{I} \\ \rho_{31} &= c_3^2 + c_1^2 \\ \rho_{23} &= c_2^2 + c_3^2 \end{aligned}$$

Binary collisions are on coordinate axes.

$$\rho_{12} = 0 \implies c_1 = c_2 = 0.$$

Collinear shapes on coordinate planes.

$$\rho_{12} = \rho_{31} + \rho_{23} \implies c_3 = 0.$$



Octahedral symmetry -- imagine an octahedron inflated to become round.

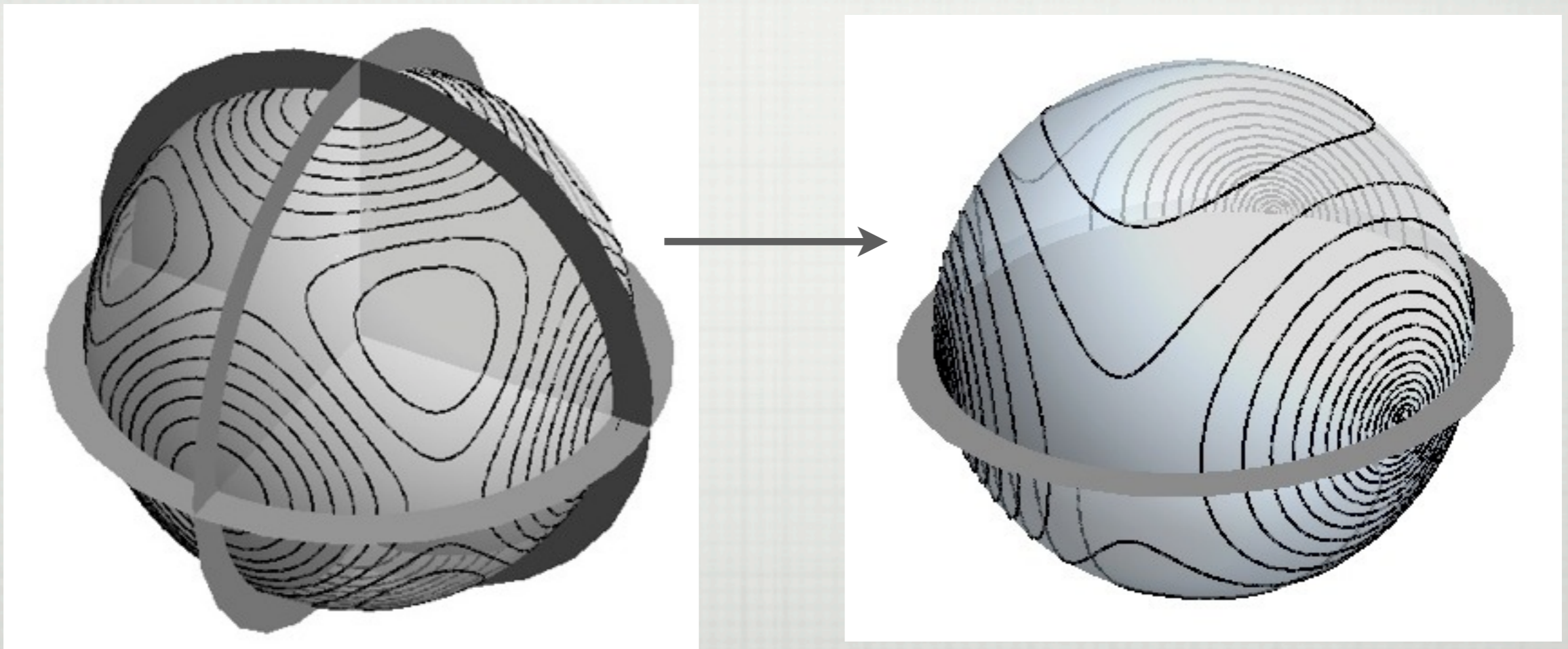
Lemaitre's Conformal Map: $\phi : \mathbb{C}^3 \rightarrow \mathbb{C}^3$ $X_{ij} = z_{ij}^2$

induces

$$\phi_{pr} : P(\mathcal{C}) \rightarrow P(\mathcal{W})$$

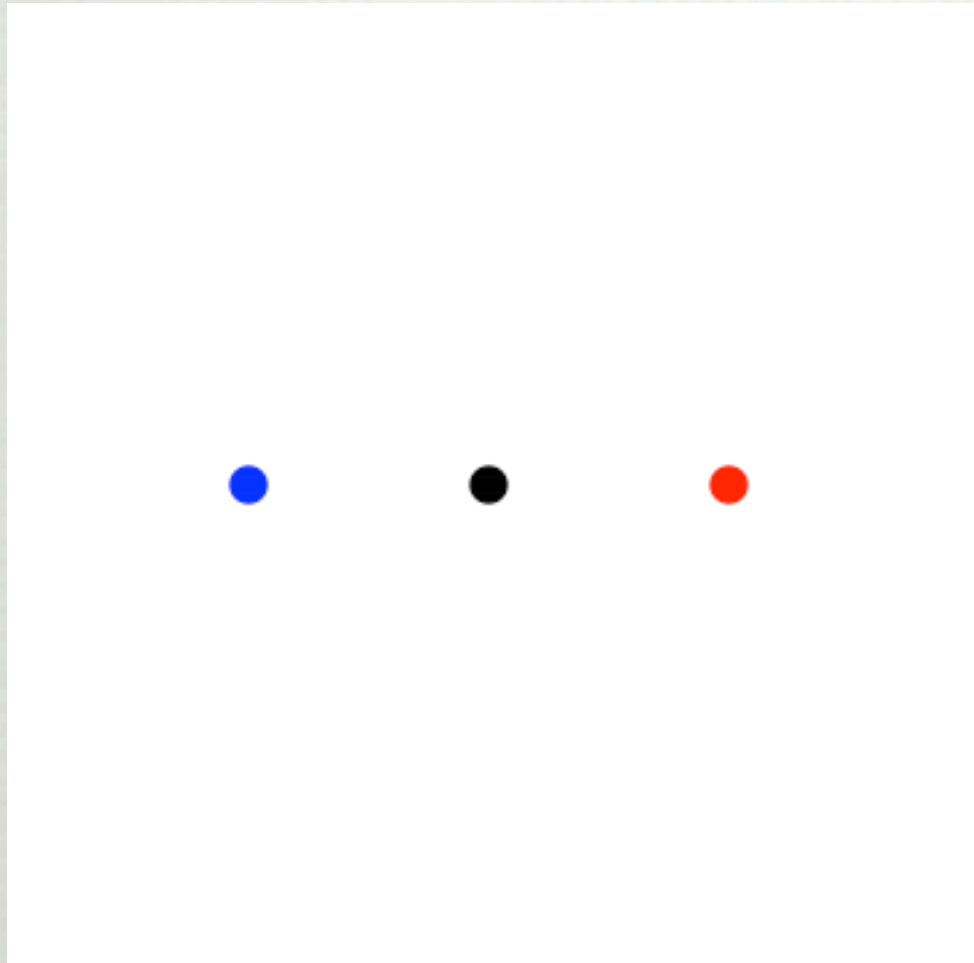
between regularized to unregularized shape spheres.

- four-to-one cover branched over the binary collisions
- each octant of regularized sphere maps to a hemisphere
- behaves like the squaring map near the six regularized binary collision points



Some Three-Body Orbits in the Regularized Reduced Configuration

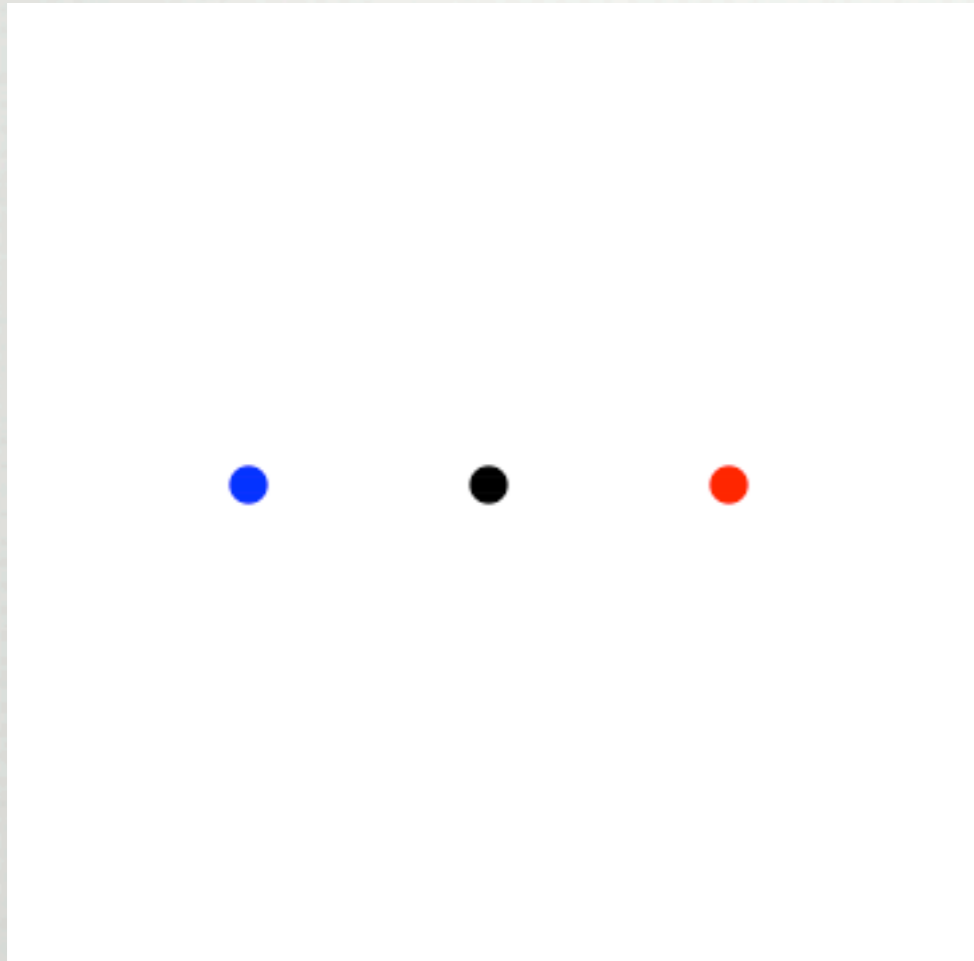
Figure-eight orbit



The orbit in regularized shape space is remarkably simple!

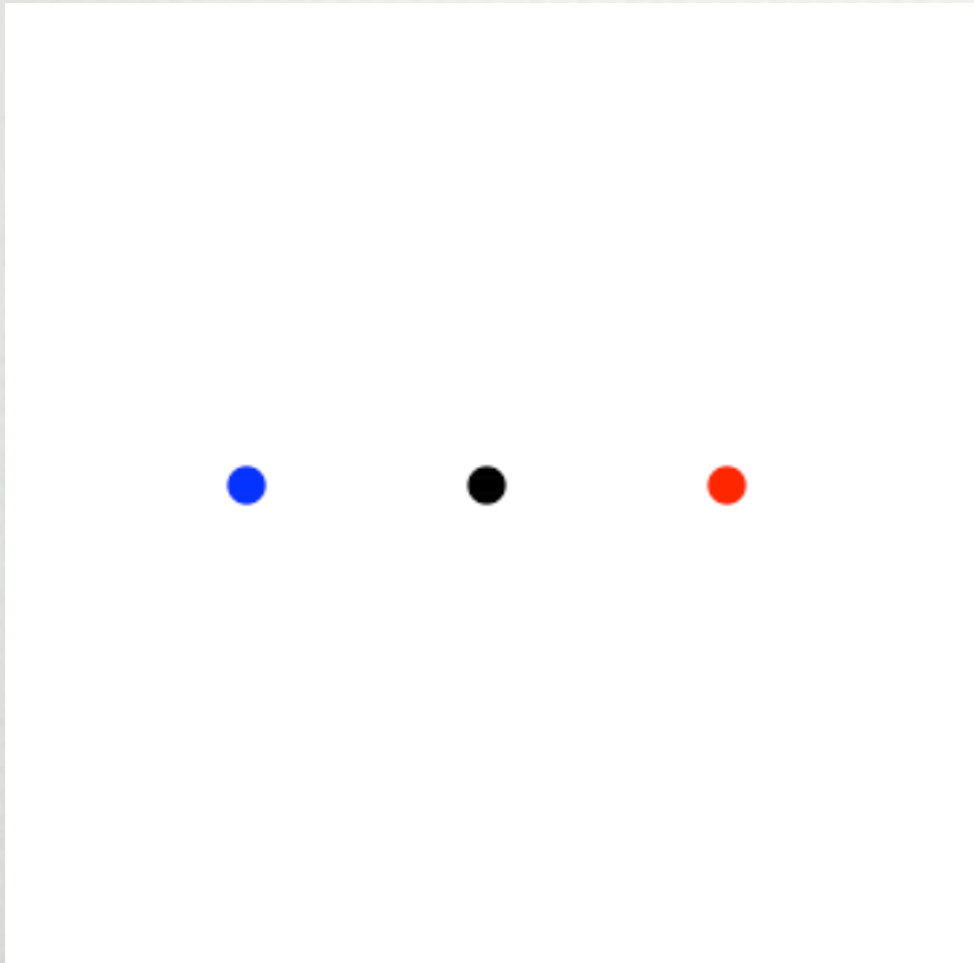
Some Three-Body Orbits in the Regularized Reduced Configuration

Figure-eight orbit

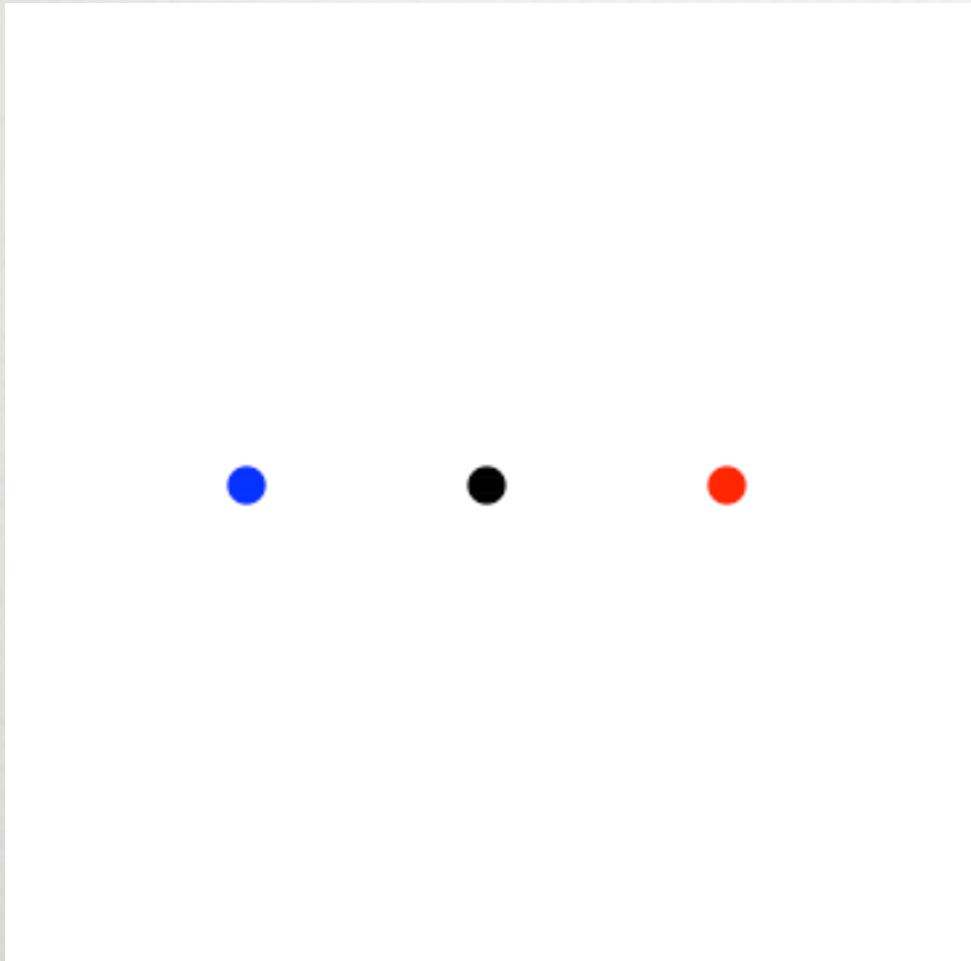


The orbit in regularized shape space is remarkably simple!

vs orbits plotted in usual reduced (shape) space



vs orbits plotted in usual reduced (shape) space



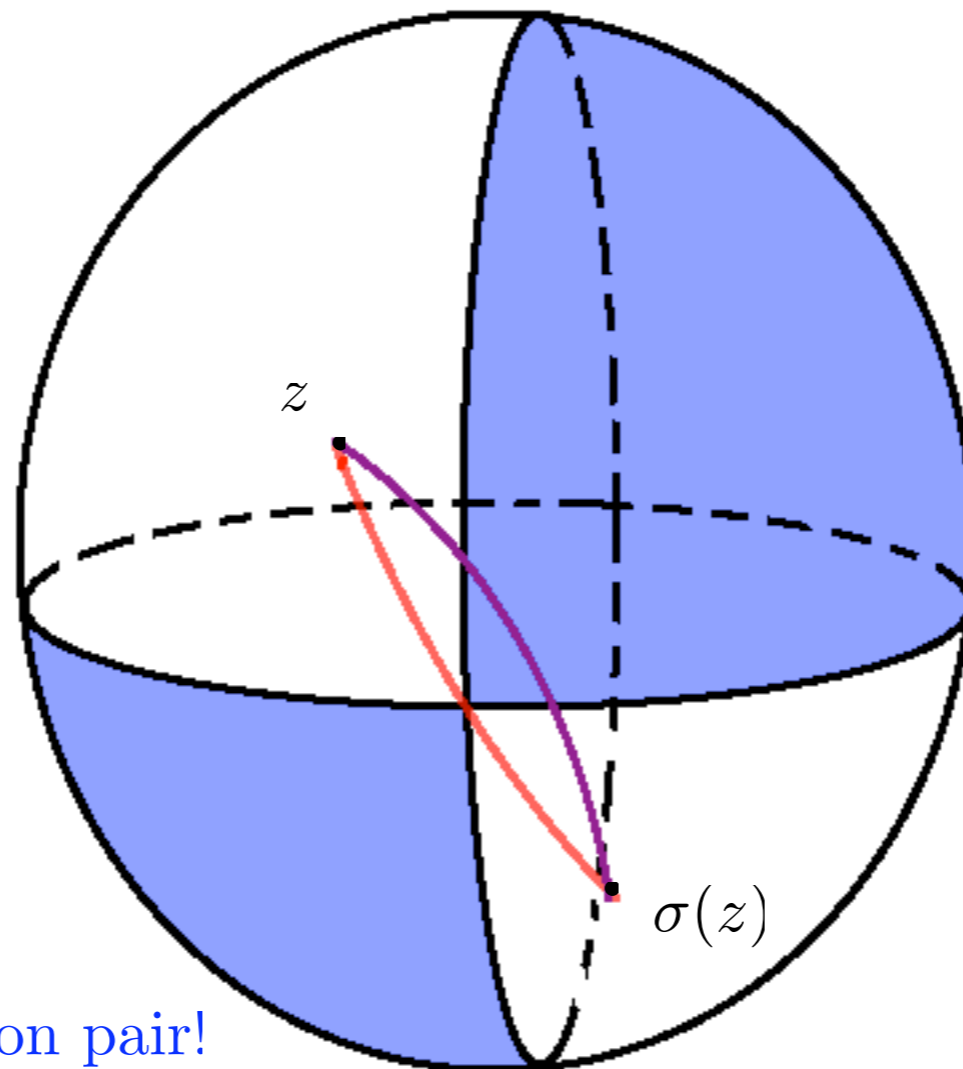
Regularizing map induces $4 = 2^2$ new symmetries

$$\sigma : z_{ij} \mapsto \pm z_{ij}$$

which all cover the identity on original space, since $z_{ij}^2 = q_{ij}$

\implies variants of brake or italian symmetry: $\sigma(z(-t)) = z(t)$

Interior binary collisions
no longer excluded
for (J-M) minimizers !



fixed points of σ : binary collision pair!

Guide to computing the reduced, regularize, blown-up dynamical equations

(* (1) Reduce by translation

(* (2) Separate size and shape

(3) Reduce by rotation : symp. reduction + homogeneous coordinates
requires fixing of the total angular momentum

(4) Compute the (co)metric [kinetic energy] in new coordinates

***** hardest work here*****

(* (5) L-C regularize (squaring map) these homogeneous coordinates
requires fixing of the the total energy

(6) McGehee blow-up

(1) Reduce by translation

[d = 2]

Relative position coordinates

$$Q_{ij} = q_i - q_j = -Q_{ji} :$$

components of linear map $L : \mathbb{C}^N \rightarrow \mathbb{C}^{\binom{N}{2}}$, $L(q) = Q$.

with $\text{image}(L) \cong (\text{config. space}) / (\text{translations}) \cong \mathbb{C}^{N-1}$

dual map L^* : components $p_i = \sum_j P_{ij}$

$$\begin{aligned} H(q, p) &= K(p) - U(q) = \left(\frac{|p_1|^2}{2m_1} + \dots \right) - \left(\frac{m_1 m_2}{|q_1 - q_2|} + \dots \right) \\ &= K(P) - U(Q) = \left(\frac{|\sum P_{1j}|^2}{2m_1} + \dots \right) - \left(\frac{m_1 m_2}{|Q_{12}|} + \dots \right) \end{aligned}$$

(2): Separate size and shape:

$$\text{size } r = |Q| \text{ with } r^2 = I = \langle Q, Q \rangle = \frac{\sum m_i m_j |Q_{ij}|^2}{\sum m_i}$$

$$\text{Shape: } [Q] = [Q_{12}, \dots, Q_{N-1, N}] \in \mathbb{CP}^{N-2} \subset \mathbb{CP}^{\binom{N}{2}}$$

$$Q_{ij} + Q_{jk} + Q_{ki} = 0$$

(3): Reduce by rotation

[d = 2]

scaling and rotation:

$$Q_{ij} \mapsto kQ_{ij}, P_{ij} \mapsto \frac{1}{\bar{k}}P_{ij}, \quad k \in \mathbb{C} \setminus 0.$$

has momentum map:

$$\sum \bar{P}_{ij}Q_{ij} = p_r + i\mu = \Phi(Q, P)$$

SIZE MOMENTUM

ANGULAR MOMENTUM

Momentum shift trick:

Take particular solution $P_{ij} = \Gamma_{ij}(Q)$ to $\Phi(Q, P) = 1$

Substitute

$$P_{ij} = (p_r - i\mu)\Gamma_{ij} + Y_{ij}, \quad \Phi(Q, Y) = 0$$

CONNECTION

Yields general solution P to

$$\Phi(Q, P) = p_r + i\mu$$

Reduce by rotation... ct'd..

[d = 2]

Defines map $(Q, Y) \rightarrow (Q, (p_r - i\mu)\Gamma(Q) + Y)$
 from 0-level of momentum map to level $p_r + i\mu$

inducing isomorphism

$$(\mathcal{P} \setminus \{0\})/S^1 \cong \mathbb{R}^+ \times \mathbb{R} \times T^*\mathbb{C}P^{N-2} \times \mathbb{R}$$

r p_r $[Q; Y]$ μ

where $\mathcal{P} = (Q, P)$ phase space $(\cong T^*\mathbb{C}^{N-1})$

ANG. MOMENTUM

(4): Compute kinetic energy in new coord (hard work)

& so the total energy

$$K_\mu = \frac{1}{2}(p_r^2 + \frac{1}{r^2}K_{shape}([Q, Y]) + \frac{\mu^2}{r^2})$$

$$U = \frac{1}{r} \sum \frac{m_i m_j}{\rho_{ij}}$$

FUBINI-STUDY

$\rho_{ij} = \frac{|Q_{ij}|}{r} =$ normalized distance

$$H_\mu = K_\mu - U$$

WARNING: Eqns NOT canonical. Curvature term: $\Omega = d\Gamma$

)

(5): Apply Levi-Civita squaring transformation: [d = 2]

$$z_{ij}^2 = Q_{ij} \quad , \quad \frac{d}{d\tau} = f \frac{d}{dt} \quad , \quad f = \prod_{i < j} \rho_{ij}$$

$$, \text{ OR } f = \prod_{i < j} \rho_{ij} / \left(\sum \rho_{ij} \right)^{\binom{N}{2}} = \prod_{i < j} r_{ij} / \left(\sum r_{ij} \right)^{\binom{N}{2}} , \text{ OR...}$$

Use Poincaré trick for time reparam. by factor f at const. energy $H = E$

$$\tilde{H}_\mu = f(H_\mu - E)$$

Key to non-singularity at binary collisions:

$$fU = \frac{1}{r} \sum_{ij} m_i m_j \prod_{kl \neq ij} \rho_{kl}$$

not singular at simple binary collisions: $\rho_{ij} = 0$

$$(r, p_r, [Z, \eta]) \mapsto (r, p_r, [Q, P]) \quad \text{induced by } [Z] \mapsto [Q]; Q_{ij} = Z_{ij}^2$$

$$K \subset \mathbb{CP}^{\binom{N}{2}} \rightarrow \mathbb{CP}^{N-2} \subset \mathbb{CP}^{\binom{N}{2}}$$

pulled back triangle constraints

triangle constraints

(6): McGehee blow-up: planar 3 body; eg

McGehee time τ . $\frac{d}{d\tau} = ' = r^{\frac{3}{2}} \frac{d}{dt}$ (*)

Rescaled size momenta $v = \frac{p_r}{r^{1/2}}$.

Rescaled reg. shape momenta $\alpha = r^{1/2} Y$.

Reg. shape variables $[Z]$ unchanged. $z = x_2/x_1$ affine shape coord.

$$r' = \lambda(z)vr$$

$$v' = -\frac{1}{2}\lambda(z)v^2 + 2\tilde{K} - W(z)$$

$$\tilde{\mu}' = -\frac{1}{2}\lambda(z)v\tilde{\mu} \leftarrow \text{Normalized ang. mom. } \tilde{\mu} := \frac{f(r)}{r^2}\mu \quad (1)$$

$$z' = (1 + |z|^2)^2\alpha$$

$$\alpha' = \lambda(z)v\alpha - \tilde{K}_z + W_z + rh\lambda_z(z) - 2i\tilde{\mu}\lambda(z)\alpha \quad \text{MAG. TERM}$$

$$\lambda = \frac{4Mm_1m_2m_3r_{12}r_{31}r_{23}(r_{12}+r_{31}+r_{23})}{I^2}: \text{conformal factor}$$

$$\text{kinetic : } 2\tilde{K} = \lambda v^2 + \lambda\tilde{\mu}^2 + \frac{1}{2}(1 + |z|^2)^2|\alpha|^2.$$

$$\text{potential } W(z) = \frac{\tilde{r}}{(1+|z|^2)^6} (m_1m_2\tilde{\rho}_{31}\tilde{\rho}_{23} + m_1m_3\tilde{\rho}_{12}\tilde{\rho}_{23} + m_2m_3\tilde{\rho}_{12}\tilde{\rho}_{31})$$

$$\text{normalized distances: } \rho_{ij} = r_{ij}/r = \tilde{\rho}_{ij}/\tilde{r},$$

$$\tilde{\rho}_{12} = 4|z|^2, \quad \tilde{\rho}_{31} = |1 + z^2|^2, \quad \tilde{\rho}_{23} = |1 - z^2|^2$$

$$\tilde{r}^2 = \tilde{I} = \frac{m_1m_2\tilde{\rho}_{12}^2 + m_1m_3\tilde{\rho}_{31}^2 + m_2m_3\tilde{\rho}_{23}^2}{m_1 + m_2 + m_3}$$

(*) alternative time scaling: $f(r) = \left(\frac{r}{r+1}\right)^2$, better behavior for large r

planar 4-body

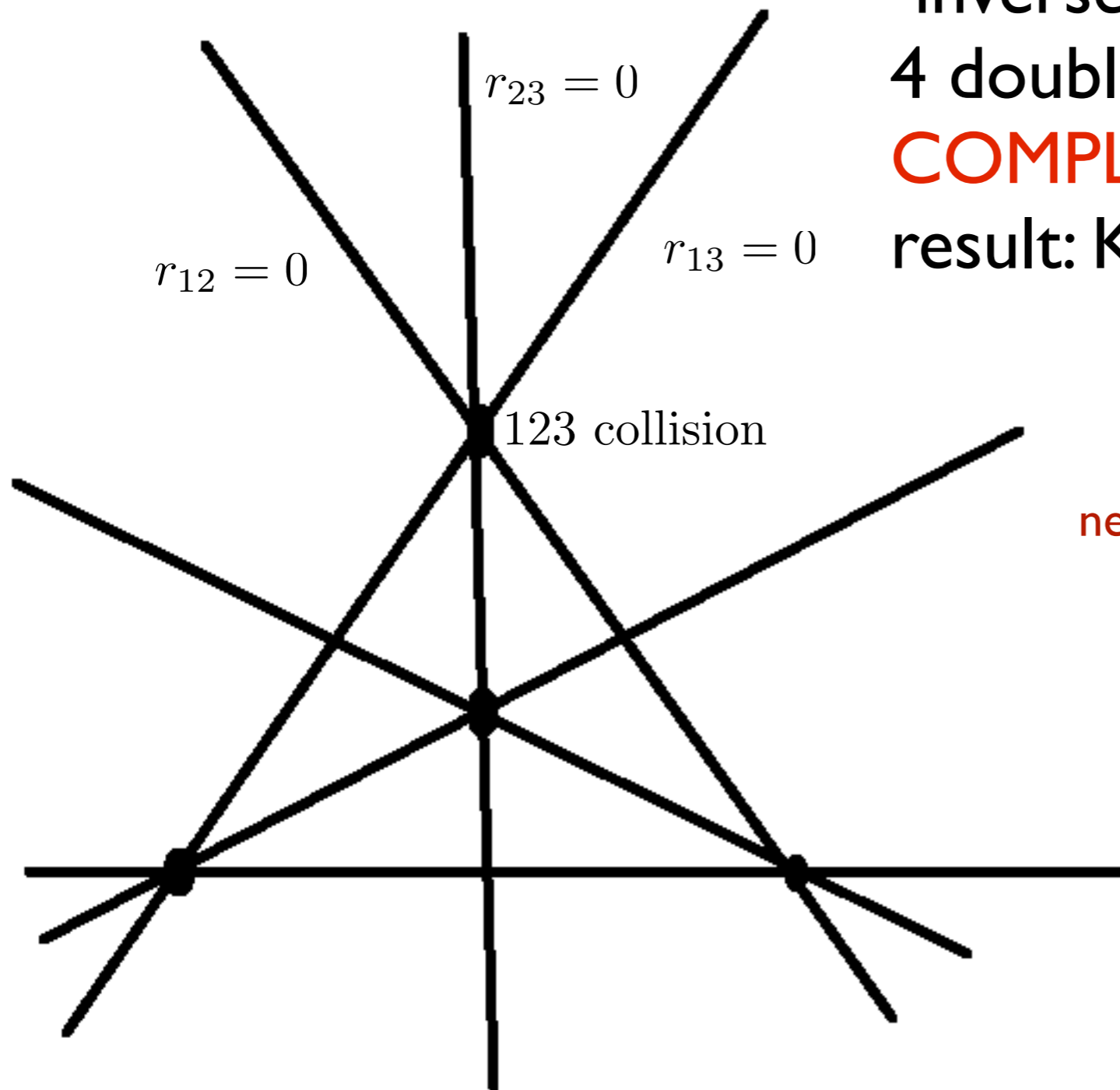
6 double collision lines.

2:1 branched cover each.

result: 32:1 branched cover of $\mathbb{C}P^2$
-inverse image of each of the

4 double collision points: a cone point
COMPLEX blow up (a la alg. geom).

result: K3 = reg. reduced shape space



next talk: complex blowup for triple collisions

J-M remarks.

A. $d = 2, N = 3, J = 0, H = -h < 0, m_1 = m_2 = m_3 :$

\implies J-M formulation takes form (roughly):

$$ds_{JM,reg}^2 = 2(-h(\hat{z}_{12}^2|\hat{z}_{23}|^2|\hat{z}_{31}|^2) + \frac{1}{Mr^2}(|\hat{z}_{23}|^2|\hat{z}_{13}|^2 + |\hat{z}_{12}|^2|\hat{z}_{32}|^2 + |\hat{z}_{21}|^2|\hat{z}_{31}|^2 \dots))ds^2$$

$$\text{with } \hat{z}_{ij} = z_{ij} / \sqrt{|z_{12}|^2 + |z_{23}|^2 + |z_{13}|^2}$$

B. Amusing toy case to see how a regularized J-M solution can minimize while its unregularized projection does not

Kepler: 0-energy: i.e PARABOLIC

$$ds_{JM}^2 = \frac{1}{r}|dq|^2 \quad , q = z^2 \implies dq = 2zdz, r = |q|^2$$

$$ds_{JM,reg}^2 = 4|dz|^2 : \text{EUCLIDEAN!}$$

Polar coordinates: $q = re^{i\theta}$

$$ds_{JM}^2 = \frac{1}{r}(dr^2 + r^2 d\theta^2) = \left(\frac{dr}{\sqrt{r}}\right)^2 + r d\theta^2$$

Change Variables: $u = \frac{1}{2}r^{1/2}$

$$\implies ds_{JM}^2 = du^2 + 4u^2 d\theta^2$$

Again locally Euclidean, but origin a cone point!

Opening cone angle : 4π

Partial
Results:

$(d, N) = (\text{dim. of ambient space, Number of bodies})$

$$\mathcal{P}(d, n) = \text{regularized, reduced, blown-up phase space}$$
$$= T^*(X(d, n)) \times T^*([0, \infty)) \times_f \mathcal{O}$$

OVERFLOW

$X(d, n) =$ regularized shape space; maybe blown up

$$; I = \frac{\sum m_i m_j r_{ij}^2}{\sum m_i}$$

$[0, \infty) =$ size space parameter \sqrt{I} where

$$d = 2 \implies \mathcal{O} = \emptyset$$

$$X(2, 3) = \mathbb{C}P^1$$

$$X(2, 4) = K3$$

$(d, N) = (3, 3)$: partial progress

$$\mathcal{P}(3, 3) = T^*(\mathbb{C}P^2) \times T^*([0, \infty)) \times_f \mathcal{O}$$

with $\mathcal{O} \rightarrow_{\mathbb{C}P^1} \mathbb{C}P^2$