Swarm dynamics and equilibria for a nonlocal aggregation model

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Self-organizing animal aggregations

- Animal groups with a high structural order
- The behaviour of individuals is so coordinated, that the group moves as a single coherent entity
- Examples of self-organizing biological groups
 - schooling fish
 - herds of ungulates
 - swarming insects
 - zigzaging flocks of birds

Mathematical models

- The existing models fall into 2 categories: Lagrangian and Eulerian
- Lagrangian models: trajectories of all individuals of a species are tracked according to a set of interaction and decision rules
 - a large set of coupled ODE's
 - a large set of coupled difference equations (discrete time)
- Eulerian models: the problem is cast as an evolution equation for the population density field
 - parabolic
 - hyperbolic

A nonlocal Eulerian PDE swarming model

- ullet We study the PDE aggregation model in \mathbb{R}^n :
 - continuity equation for the density ρ :

$$\rho_t + \nabla \cdot (\rho v) = 0$$

— the velocity \boldsymbol{v} is assumed to have a functional dependence on the density

$$v = -\nabla K * \rho$$

- the potential K incorporates social interactions: attraction and repulsion
- The model was first suggested by Mogilner and Keshet, *J. Math. Biol.* [1999]
- Literature on this model has been very rich in recent years

Lagrangian description

N individuals

 $X_i(t) =$ spatial location of the *i*-th individual at time t

$$\frac{dX_i}{dt} = -\frac{1}{N} \sum_{\substack{j=1...N\\j\neq i}} \nabla_i K(X_i - X_j), \qquad i = 1...N$$

PDE: continuum approximation, as $N \to \infty$

Assumption: social interactions depend only on the relative distance between the individuals

radially symmetric potentials

$$K(x) = K(|x|)$$

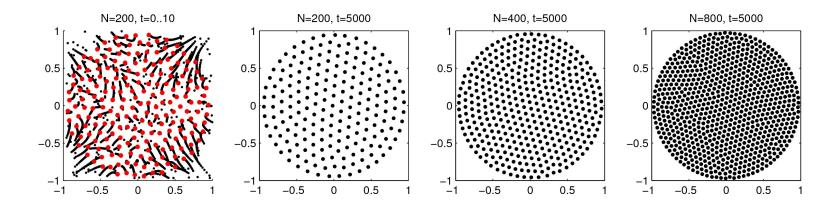
Notation: F(r) = -K'(r)

$$\frac{dX_i}{dt} = \frac{1}{N} \sum_{\substack{j=1...N\\j \neq i}} F(|X_i - X_j|) \frac{X_i - X_j}{|X_i - X_j|}, \qquad i = 1...N$$

 $F(|X_i - X_j|) =$ magnitude of the force that the individual X_j exerts on the individual X_i , along $X_i - X_j$

Repulsion (F(r) > 0) acts at short ranges, attraction (F(r) < 0) at long ranges.

Example: n = 2, F(r) = 1/r - r; random initial conditions inside the unit square. The solution approaches a constant density in the unit disk.



Motivation for this work

- Equilibria of the model should have biologically relevant features:
 - finite densities
 - sharp boundaries
 - relatively constant internal population
- The main motivation for this work is to
 - design interaction potentials K which lead to such equilibria
 - investigate analytically and numerically the well-posedness
 and long time behaviour of solutions

Interaction potential K

$$K(x) = K_r + K_a$$

$$= \phi(x) + \frac{1}{q}|x|^q, \qquad q \ge 2$$

 $\phi(x)$ = the free-space Green's function for $-\Delta$:

$$\phi(x) = \begin{cases} -\frac{1}{2\pi} \ln|x|, & n = 2\\ \frac{1}{n(n-2)\omega_n} \frac{1}{|x|^{n-2}}, & n \ge 3 \end{cases}$$

Continuity equation: $\rho_t + v \cdot \nabla \rho = -\rho \operatorname{div} v$

Calculate div v:

$$\begin{aligned} \operatorname{div} v &= \operatorname{div}(-\nabla K * \rho) \\ &= -\Delta K * \rho \\ &= \rho - \Delta \left(\frac{1}{q}|x|^q\right) * \rho \end{aligned}$$

The repulsion term has become local!

Lagrangian approach

Characteristic curves: $\frac{d}{dt}X(\alpha,t) = v(X(\alpha,t),t), \qquad X(\alpha,0) = \alpha$

Evolution equation for $\rho(X(\alpha,t),t)$:

$$\frac{D\rho}{Dt} = -\rho^2 + \rho \,\Delta\left(\frac{1}{q}|x|^q\right) * \rho$$

Special case q = 2: explicit calculations

$$\Delta\left(\frac{1}{2}|x|^2\right) = n, \quad \Delta\left(\frac{1}{2}|x|^2\right) * \rho = n\underbrace{\int_{\mathbb{R}^n} \rho(y)dy}_{=M}$$

ODE along characteristics: $\frac{D\rho}{Dt} = -\rho(\rho - nM)$

Exact solution:
$$\rho(X(\alpha,t),t) = \frac{nM}{1 + \left(\frac{nM}{\rho_0(\alpha)} - 1\right)e^{-nMt}}$$

Asymptotic behaviour as $t \to \infty$?

Asymptotic behaviour

Density: $\rho(X,t) \to nM$, as $t \to \infty$, along particle paths with $\rho_0(\alpha) \neq 0$

Asymptotic behaviour of trajectories: $R_{\alpha} = \lim_{t \to \infty} |X(\alpha, t)|$

For radial solutions, it can be proved that trajectories are mapped into the ball of \mathbb{R}^n of radius $R_{\alpha} = \frac{1}{(n\omega_n)^{\frac{1}{n}}}$.

Numerics suggest that *all* solutions have this asymptotic behaviour.

Global attractor: constant, compactly supported density:

$$\bar{\rho}(x) = \begin{cases} nM & \text{if } |x| < \frac{1}{(n\omega_n)^{\frac{1}{n}}} \\ 0 & \text{otherwise} \end{cases}$$

Global existence of particle paths

$$v(x) = \int_{\mathbb{R}^n} k(x - y)\rho(y) \, dy - Mx, \tag{1}$$

where

$$k(x) = \frac{1}{n\omega_n} \frac{x}{|x|^n}$$

The convolution kernel k is singular, homogeneous of degree 1-n.

Equation (1) is analogous to Biot-Savart law, where vorticity ω is now replaced by density ρ .

Existence and uniqueness of particle paths follow similarly to that for incompressible Euler equations.

Extension to global existence: Beale-Kato-Majda criterion

$$\int_0^t \|\rho(\cdot,s)\|_{L^\infty} ds < \infty, \text{ for all finite times } t$$

Case q > 2: Non-constant steady states

Numerics suggests that attractors are radially symmetric.

Assume the model admits a radial steady state supported on a ball B(0,R).

Recall formula for div v: div $v = \rho - \Delta \left(\frac{1}{q}|x|^q\right) * \rho$

Equilibria supported on B(0,R):

$$v = 0$$
, hence div $v = 0$ in $B(0, R)$

A steady state $\bar{\rho}$ satisfies:

$$\bar{\rho} - (n+q-2) \int_{\mathbb{R}^n} |x-y|^{q-2} \bar{\rho}(y) dy = 0$$
 in $B(0,R)$

Use radial symmetry $\bar{\rho}(x) = \bar{\rho}(r)$.

Radial steady states

The density $\bar{\rho}$ satisfies the homogeneous Fredholm integral equation

$$\bar{\rho}(r) = c(q, n) \int_0^R (r')^{n-1} \bar{\rho}(r') I(r, r') dr', \qquad 0 \le r < R,$$

$$I(r,r') = \int_0^{\pi} (r^2 + (r')^2 - 2rr'\cos\theta)^{q/2-1}\sin^{n-2}\theta d\theta.$$

In other words, $\bar{\rho}$ is an eigenfunction of the linear operator T_R :

$$T_R \overline{\rho}(r) = c(q, n) \int_0^R (r')^{n-1} \overline{\rho}(r') I(r, r') dr',$$

that corresponds to eigenvalue one: $T_R \bar{\rho}(r) = \bar{\rho}(r), \quad r < R$

The eigenvalue problem: find $\bar{\rho}$ and the radius R of the support

Krein-Rutman theorem

Consider case R = 1 first.

The kernel $c(q,n)(r')^{n-1}I(r,r')$ is nonnegative, continuous and bounded.

 T_1 is a linear, strongly positive, compact operator that maps the space of continuous functions $C([0,1],\mathbb{R})$ into itself.

Krein-Rutman theorem: there exists a *positive* eigenfunction $\bar{\rho}_1$ such that

$$T_1 \bar{\rho}_1 = \lambda \bar{\rho}_1 \tag{2}$$

 $\lambda(q,n)$ is the spectral radius of T_1 ; it is a simple eigenvalue and there is no other eigenvalue with a positive eigenvector.

Define, by rescaling: $\bar{\rho}(r) = \bar{\rho}_1(r/R)$.

Existence and uniqueness of equilibria

Introduce $\bar{\rho}(r) = \bar{\rho}_1(r/R)$ in (2):

$$T_R \bar{\rho}(r) = R^{n+q-2} \lambda \, \bar{\rho}(r)$$

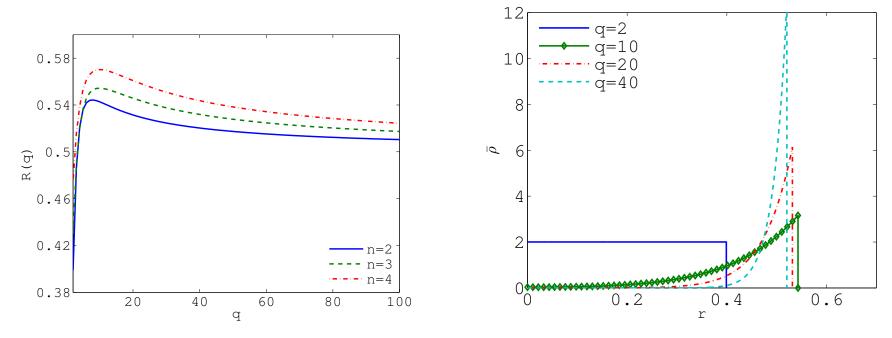
Ask that $\bar{\rho}$ is an eigenfunction of T_R corresponding to e-value 1:

$$R = \lambda^{-\frac{1}{n+q-2}}$$

This gives the radius of the support as a function of q and n.

Once a mass M for $\bar{\rho}$ is set, uniqueness can be inferred from the uniqueness properties of the spectral radius of T_1 and its associated eigenfunction $\bar{\rho}_1$.

Equilibria: numerical results



Left: Plot of the radius of the support R of the steady states as a function of the exponent q, for various space dimensions n.

The plot suggests that the radius R approaches a constant, as $q \to \infty$.

Right: Normalized radially symmetric steady states $\bar{\rho}(r)$ in two dimensions for various values of the exponent q.

For q=2 the steady state is the constant solution in a disk. As q increases, mass aggregates toward the edge of the swarm, creating an increasingly void region in the centre.

Even q: polynomial steady states

Kernel $I(r,r') = \int_0^{\pi} (r^2 + (r')^2 - 2rr'\cos\theta)^{q/2-1}\sin^{n-2}\theta d\theta$ is separable when q is even.

Define the *i*-th order moments of the density $(m_0 = M)$:

$$m_i = n\omega_n \int_0^R r^{n+i-1} \bar{\rho}(r) dr. \tag{3}$$

Example: q = 4

$$I(r,r') = (r^2 + (r')^2) \int_0^{\pi} \sin^{n-2}\theta d\theta$$

and

$$\bar{\rho}(r) = n(n+2)\omega_n \int_0^R (r')^{n-1} (r^2 + (r')^2) \bar{\rho}(r') dr'$$

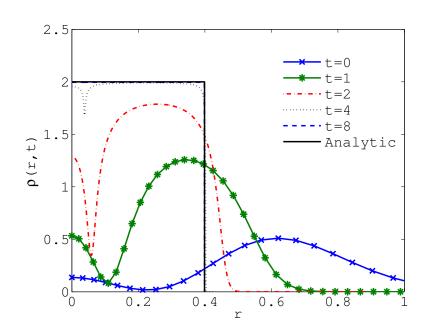
$$= (n+2)m_0 r^2 + (n+2)m_2 \tag{4}$$

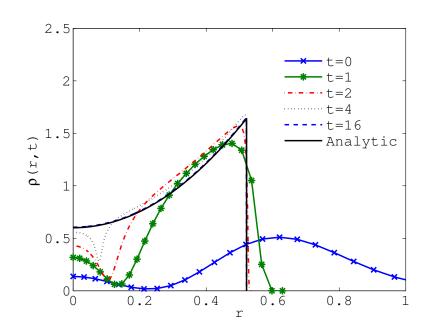
Plug (4) into (3): linear system to find R and m_2

$$\begin{pmatrix} m_0 \\ m_2 \end{pmatrix} = \begin{pmatrix} n\omega_n R^{n+2} & (n+2)\omega_n R^n \\ \frac{n(n+2)}{n+4}\omega_n R^{n+4} & n\omega_n R^{n+2} \end{pmatrix} \begin{pmatrix} m_0 \\ m_2 \end{pmatrix}$$
 (5)

General q even: $\bar{\rho}(r)$ is a polynomial of even powers of r, of degree q-2.

Dynamic evolution: numerical results





Time evolution of a radially symmetric solution to the aggregation model with q=2 (left) and q=4 (right) in two dimensions

Left: As predicted by the analytical results, the solution approaches asymptotically a constant, compactly supported steady state.

Right: The solution approaches asymptotically the steady state computed analytically

Regularized potentials

$$F(r) = \frac{1}{r} - r \qquad \text{regularize} \qquad F(r) = \begin{cases} C_1, & 0 \le r < r_0 \\ \frac{1}{r} - r, & r_0 \le r \le 2 \\ -C_2 \exp(-r), & 2 < r \end{cases}$$

$$(6)$$

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Equilibrium states for the regularized interaction force (6). Initial conditions were chosen at random in the unit square. For $r_0 < 0.09$, the steady state is the same as for $r_0 = 0$ (uniform density in the unit circle).

Inverse problem: custom designed potentials

Inverse problem: given a density $\bar{\rho}(x)$, can we find a potential K for which $\bar{\rho}(x)$ is a steady state of the model?

Answer: Yes, provided $\bar{\rho}(x)$ is radial and is a polynomial in |x|.

Theorem: In one dimension, consider an even density $\bar{\rho}$ of the form

$$\bar{\rho}(x) = \begin{cases} b_0 + b_2 x^2 + b_4 x^4 + \dots + b_{2d} x^{2d} & |x| < R \\ 0 & \text{otherwise.} \end{cases}$$

Define the moments m_i as in (3). Then $\bar{\rho}(x)$ is the steady state corresponding to the force F:

$$F(x) = \frac{1}{2} - \sum_{i=0}^{d} \frac{a_{2i}}{2i+1} x^{2i+1}$$

where the constants a_0, a_2, \ldots, a_{2d} , are computed from b_0, b_2, \ldots, b_{2d} by solving the following linear system:

$$b_{2k} = \sum_{j=k}^{d} a_{2j} \begin{pmatrix} 2j \\ 2k \end{pmatrix} m_{2(j-k)}, \qquad k = 0 \dots d.$$
 (7)

Moreover, system (7) has a unique solution.

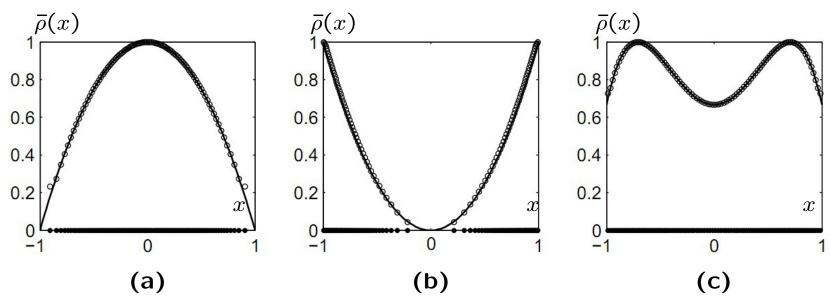
Inverse problem: numerical results

Examples: R = 1 and:

(a)
$$\bar{\rho}(x) = 1 - x^2$$
; (b) $\bar{\rho}(x) = x^2$; (c) $\bar{\rho}(x) = \frac{1}{2} + x^2 - x^4$

The corresponding forces given by the Theorem are:

(a)
$$F(x) = \frac{1}{2} - \frac{9}{10}x + \frac{1}{4}x^3$$
; (b) $F(x) = \frac{1}{2} + \frac{9}{10}x - \frac{1}{2}x^3$;
(c) $F(x) = \frac{1}{2} + \frac{209425}{672182}x - \frac{2075}{2527}x^3 + \frac{3}{19}x^5$.



Filled circles along the x-axis: the steady states reached by numerical time evolution. Empty circles: density function as computed from the filled circles. Solid line: analytical expression for $\bar{\rho}$.

Bibliography

1. R.C. Fetecau, Y. Huang and T. Kolokolnikov [2011]. Swarm dynamics and equilibria for a nonlocal aggregation model, *Nonlinearity*, Vol. 24, No. 10, pp. 2681-2716 (featured article)

Other recent work / Future Directions

- Studied q < 2, in particular the case $q \to 2 n$, when attraction becomes as singular as repulsion (Newtonian potential)
- Investigated properties of the steady states: monotonicity, asymptotic behaviour $(q \to \infty, q \to 2-n)$
- Energy considerations: local/ global minima

$$E[\rho] = \frac{1}{2} \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} K(x - y) \rho(x) \rho(y) dy dx$$

The model is a gradient flow with respect to this energy:

$$\frac{d}{dt}E[\rho] = -\int_{\mathbb{R}^n} \rho(x) |\nabla K * \rho(x)|^2 dx \le 0$$