

Amalgamation properties for types in stable theories and beyond

John Goodrick

University of Maryland, College Park

Banff

February 2009

Introduction

We ask: when can certain systems of types be amalgamated, and when is the result unique?

This yields properties such as n -existence (or the n amalgamation property) and n -uniqueness.

Many natural algebraic examples have these properties, and they have nice consequences, such as:

Theorem

(De Piro, Kim, Young) If T is simple and has 5 complete amalgamation over models, then the existence of a hyperdefinable group configuration implies the existence of a hyperdefinable group.

More recently, Hrushovski showed that in stable T , 4-existence is equivalent to the eliminability of “generalized imaginary sorts” as well as the collapsing of certain definable groupoids.



The 3-amalgamation problem

3-amalgamation is about the following question:

Question

Given complete types $p_{12}(x_1, x_2)$, $p_{23}(x_2, x_3)$, and $p_{13}(x_1, x_3)$, when is $p_{12} \cup p_{23} \cup p_{13}$ consistent?

Equivalently: given any realization (a_1, a_2) of p_{12} , is there a common realization of the two types $p_{23}(a_2, x_3)$ and $p_{13}(a_1, x_3)$?

A minimal necessary requirement is coherence: $p_{12} \upharpoonright x_1 = p_{13} \upharpoonright x_1$, $p_{12} \upharpoonright x_2 = p_{23} \upharpoonright x_2$, and $p_{13} \upharpoonright x_3 = p_{23} \upharpoonright x_3$.

Failures of 3-amalgamation

Question

Given complete types $p_{12}(x_1, x_2)$, $p_{23}(x_2, x_3)$, and $p_{13}(x_1, x_3)$, when is $p_{12} \cup p_{23} \cup p_{13}$ consistent?

But many coherent triples of types cannot be amalgamated, e.g.:

If the universe is linearly ordered by “ $<$,” $x_1 < x_2 \in p_{12}$,
 $x_2 < x_3 \in p_{23}$, and $x_3 < x_1 \in p_{13}$;

Or in a theory with an equivalence relation E with exactly two classes, if $\neg E(x_i, x_j) \in p_{ij}$.

3-amalgamation in stable theories

Theorem

Suppose that T is stable, $B = \text{acl}^{\text{eq}}(B)$, $a_1 \downarrow_B a_2$, and the types $p_1(a_1, x_3)$ and $p_2(a_2, x_3)$ are nonforking extensions of a common type $p(x_3) \in S(B)$. Then there is a realization a_3 of $p_1(a_1, x_3) \cup p_2(a_2, x_3)$ such that $a_3 \downarrow_B a_1 a_2$.

Proof.

Pick any a_3 realizing $p_1(a_1, x_3)$ such that $a_3 \downarrow_{Ba_1} a_2$. By stationarity of p , $a_3 \models p_2(a_2, x_3)$. □

3-amalgamation in simple theories

Kim and Pillay generalized this to simple theories:

Theorem

Suppose that T is simple, $B = \text{bdd}^{\text{heq}}(B)$, $a_1 \downarrow_B a_2$, and the types $p_1(a_1, x_3)$ and $p_2(a_2, x_3)$ are nonforking extensions of a common type $p(x_3) \in S(B)$. Then there is a realization a_3 of $p_1(a_1, x_3) \cup p_2(a_2, x_3)$ such that $a_3 \downarrow_B a_1 a_2$.

If T has elimination of hyperimaginaries (e.g. if T is supersimple), then $B = \text{acl}^{\text{eq}}(B)$ is enough.

From 3 to n

In the terminology we are about to define, we have shown that all stable theories have 3-existence (or the 3-amalgamation property).

Now we will generalize this property from 3 to n .

n -amalgamation problems

Notation: $\mathcal{P}^-(n) = \{s : s \subsetneq \{1, \dots, n\}\}$.

Definition

1. An n -amalgamation problem is a functor $A : \mathcal{P}^-(n) \rightarrow \mathcal{P}(\mathcal{C})$, where the maps on the right are elementary.
2. A solution to an n -amalgamation problem A is an extension to a functor $A' : \mathcal{P}(n) \rightarrow \mathcal{P}(\mathcal{C})$ (again with elementary maps on the right).

With A as above and $s \subseteq t \subsetneq n$, let $\tau_t^s : A(s) \rightarrow A(t)$ be the image of the inclusion $s \subseteq t$.

Factoriality says: $\tau_u^t \circ \tau_t^s = \tau_u^s$ whenever this makes sense.

[Draw picture of 3-amalgamation problem]

Bases of amalgamation

Definition

If A is an n -amalgamation problem, then A is over B if $B = A(\emptyset)$ and for every $s \subsetneq n$, τ_s^\emptyset fixes B pointwise.

If we are looking at the solutions of A , clearly we may assume that A is over $A(\emptyset)$ (just shift the $A(s)$'s by appropriate automorphisms).

From now on we always assume A is over $A(\emptyset)$.

Independent amalgamation problems

We write “ i ” for $\{i\}$ to simplify notation.

Definition

An n -amalgamation problem A is independent if for every s s.t. $\emptyset \neq s \subsetneq n$,

- 1 $\{\tau_s^i(A(i)) : i \in s\}$ is an $A(\emptyset)$ -independent set;
- 2 If $t \subseteq s$, then $\tau_s^t(A(t)) = \text{bdd}^{\text{heq}}(A(\emptyset) \cup \{\tau_s^i(A(i)) : i \in t\})$.

(If T is stable, replace “ bdd^{heq} ” by “ acl^{eq} .”)

So if the τ -maps are all inclusions, then $A(t) \downarrow_{A(t \cap u)} A(u)$.

Independent solutions to A are defined in a similar way.

Independent amalgamation problems

We write “ i ” for $\{i\}$ to simplify notation.

Definition

An n -amalgamation problem A is independent if for every s s.t. $\emptyset \neq s \subsetneq n$,

- 1 $\{\tau_s^i(A(i)) : i \in s\}$ is an $A(\emptyset)$ -independent set;
- 2 If $t \subseteq s$, then $\tau_s^t(A(t)) = \text{bdd}^{\text{heq}}(A(\emptyset) \cup \{\tau_s^i(A(i)) : i \in t\})$.

(If T is stable, replace “ bdd^{heq} ” by “ acl^{eq} .”)

So if the τ -maps are all inclusions, then $A(t) \downarrow_{A(t \cap u)} A(u)$.

Independent solutions to A are defined in a similar way.

n -existence, n -uniqueness

Assume T is simple.

Definition

1. T has n -existence if every independent n -amalgamation problem has an **independent** solution.
2. T has n -uniqueness if every independent n -amalgamation problem A has at most one **independent** solution up to isomorphism over A .
3. T has n -complete amalgamation if for every k with $3 \leq k \leq n$, T has k -existence.

n -existence and n -uniqueness continued

So n -existence and n -uniqueness give two different ways to classify simple theories:

2-existence is true in any simple theory, by the existence of nonforking extensions;

3-existence is true in any stable theory, and all known examples of simple theories;

4-existence can fail even in stable theories (we'll see an example).

2-uniqueness is true in any stable theory (by stationarity of strong types), but fails for unstable simple T ;

3-uniqueness can fail even for stable T .

Example: the random graph

The theory of a random graph is simple and has n -existence for all $n \geq 2$.

But if $A(i) = a_i$ (for $i = 1, 2$), then there are two solutions to the 2-amalgamation problem A : one with an edge between the points and one with no edge. So the random graph does not have 2-uniqueness.

Example: random hypergraphs

A hypergraph is a set with a symmetric ternary relation R .

The theory of a random “tetrahedron-free hypergraph” (where R cannot hold of every 3-element subset of a 4-element set) turns out to be simple.

However, it fails 4-existence: consider a 4-amalgamation problem where $A(\{i, j, k\})$ is a triple of points on which R holds.

Similarly, the n -simplex-free hyper $^{n-3}$ graph is simple and has $(n - 1)$ -complete amalgamation but not n -existence.

“Q-example”

We now give an example of a stable T which fails 3-uniqueness.

Let I be some infinite set,

$[I]^2$ is all 2-element subsets of I ,

$E \subseteq I \times [I]^2$ is set membership,

$P = \{0, 1\} \times [I]^2$, with projection map $\pi : P \rightarrow [I]^2$,

And $Q \subseteq P \times P \times P$ be the set of all $((i, s), (j, t), (k, u))$ such that:

- 1 s, t, u are all distinct sets,
- 2 $|s \cup t \cup u| = 3$, and
- 3 $i + j + k$ is even.

[Draw picture on blackboard]

$T = \text{Th}(I, [I]^2, E, P, \pi, Q)$.

Q-example continued

$$T = \text{Th}(I, [I]^2, E, P, \pi, Q)$$

Note that if $a, b \in I$, then $|\pi^{-1}(\{a, b\})| = 2$, so $\pi^{-1}(\{a, b\}) \subseteq \text{acl}(a, b)$.

It turns out that T is totally categorical, hence stable.

Note that if $Q(x, y, z)$ holds, then $z \in \text{dcl}(x, y)$.

Therefore, for any three distinct elements $a_1, a_2, a_3 \in I$, note that

$$\pi^{-1}(\{a_1, a_2\}) \subseteq \text{dcl}(\pi^{-1}(\{a_1, a_3\}) \cup \pi^{-1}(\{a_2, a_3\})).$$

Q-example continued

Given three distinct elements $a_1, a_2, a_3 \in I$, let A be the 3-amalgamation problem given by $A(\{i\}) = a_i$ and $A(\{i, j\}) = \text{acl}(a_i, a_j)$.

There are two solutions A_1, A_2 to A , defined by:

$$A_1(\{1, 2, 3\}) = A_2(\{1, 2, 3\}) = \text{acl}(\{a_1, a_2, a_3\});$$

All transition maps in A_1 are inclusion maps.

In A_2 , the transition maps $A(\{1, 3\}) \rightarrow A_2(\{1, 2, 3\})$ and $A(\{2, 3\}) \rightarrow A_2(\{1, 2, 3\})$ are inclusions, but the transition map $A(\{1, 2\}) \rightarrow A_2(\{1, 2, 3\})$ fixes a_1 and a_2 but switches the two elements of $\pi^{-1}(\{a_1, a_2\})$.

$A_1 \not\cong A_2$ because of the relation Q on the fibers.

$(n + 1)$ -existence from $\leq n$ -uniqueness

Theorem

Suppose T is stable and T has k -uniqueness for all $2 \leq k \leq n$ (where $n \geq 2$). Then T has $(n + 1)$ -existence.

Proof.

Suppose A is an independent $(n + 1)$ -amalgamation problem. Let $A'(\{1, \dots, n + 1\})$ be the algebraic closure of independent copies of $A(\{1, \dots, n\})$ and $A(\{n + 1\})$.

Define maps $\tau_{1, \dots, n+1}^i : A(\{i\}) \rightarrow A'(\{1, \dots, n + 1\})$ in the natural way.

For any $i \leq n$, there is only one way to define the transition map $\tau_{1, \dots, n+1}^{i, n+1} : A(\{i, n + 1\}) \rightarrow A'(\{1, \dots, n + 1\})$ (by 2-uniqueness). If $n > 3$, 3-uniqueness implies there is a unique way to extend these transition maps to “faces.” Repeat using induction.



Characterizing 3-uniqueness in stable T

Theorem

(Hrushovski) If T is stable, then TFAE:

- 1 T has 3-uniqueness;
- 2 T has 4-existence;
- 3 Every connected definable groupoid in T with finite automorphism groups is “equivalent” to a group.

Retractable groupoids

Definition

1. A groupoid is a category \mathcal{G} in which every morphism has a (unique, 2-sided) inverse.
2. A groupoid is connected if there is a morphism between any two objects.

In a connected groupoid, any two automorphism groups $\text{Mor}_{\mathcal{G}}(a, a)$ and $\text{Mor}_{\mathcal{G}}(b, b)$ are isomorphic. (Conjugate by $f \in \text{Mor}_{\mathcal{G}}(a, b)$.)

Definition

A connected definable groupoid \mathcal{G} is retractable if there is a definable family of commuting morphisms $\{f_{ab} \in \text{Mor}_{\mathcal{G}}(a, b) : a, b \in \text{Ob}_{\mathcal{G}}\}$.

Symmetric witnesses to non-3-uniqueness

Lemma

Suppose that T is stable. T does not have 3-uniqueness if and only if there is a set A , elements a_1, a_2 , and a_3 , and elements f_{12}, f_{23} , and f_{31} such that:

- 1 a_1, a_2, a_3 is a Morley sequence over A ;
- 2 $f_{ij} \in \text{acl}(Aa_i a_j) \setminus \text{dcl}(Aa_i a_j)$;
- 3 $a_1 a_2 f_{12} \equiv_A a_2 a_3 f_{23} \equiv_A a_3 a_1 f_{31}$;
- 4 If (i, j, k) is a cyclic permutation of $(1, 2, 3)$, then $f_{ij} \in \text{dcl}(A f_{jk} f_{ki})$.

$\{a_1, a_2, a_3, f_{12}, f_{23}, f_{31}\}$ as above is called a symmetric witness to non-3-uniqueness.

Non-retractable groupoids from failure of 3-uniqueness

Theorem

(G.-Kolesnikov) Suppose T is stable and $\{a_1, a_2, a_3, f_{12}, f_{23}, f_{31}\}$ is a symmetric witness to non-3-uniqueness over A .

Then $\text{tp}(\text{acl}(Aa_i)/\text{acl}(A))$ defines the object class of a connected \star -definable non-retractable groupoid \mathcal{G} , with

$$\text{Mor}_{\mathcal{G}}(a_1, a_2) = \{f' : f' \equiv_{Aa_1a_2} f_{12}\}.$$

Corollary

If T is stable, then T does not have 3-uniqueness if and only if there is a connected \star -definable groupoid with algebraically closed objects which is not retractable.

Generalizations?

Question

Does failure of n -uniqueness in stable T correspond to the definability of a certain kind of “higher-dimensional groupoid” for $n \geq 4$?

There are various different notions of “ n -category” and “ n -groupoid” in the literature, and it is not clear which one is appropriate here.

Question

In stable T , is $(n + 1)$ -existence equivalent to n -uniqueness (for $n \geq 4$)?

Generalized imaginaries

For stable T , Hrushovski proves there is an expansion \mathcal{C}^* of the monster model \mathcal{C} such that:

1. \mathcal{C}^* is \mathcal{C} plus a bounded collection of new sorts;
2. \mathcal{C} is stably embedded in \mathcal{C}^* ;
3. Each sort $S \in \mathcal{C}^*$ admits a definable map into \mathcal{C} with finite fibers;
4. \mathcal{C}^* has n -uniqueness and n -existence for all n .

However, we lack an “explicit” description of the new sorts in \mathcal{C}^* – presumably they are related to higher groupoids definable in \mathcal{C} .

Forcing amalgamation for simple theories?

Question

If T is simple, is there an expansion $\mathfrak{C}^ \supseteq \mathfrak{C}$ with n -existence into which \mathfrak{C} is stably embedded?*

Consistent amalgamation in rosy theories

What kinds of amalgamation can we expect in rosy theories?

O-minimal structures can't have 3-existence (we can't amalgamate $x_1 < x_2$, $x_2 < x_3$, and $x_3 < x_1$). But they do have the following property:

Definition

(T rosy) T has consistent n -amalgamation if any thorn-independent n -amalgamation problem with a solution has a **thorn-independent** solution.

Consistent amalgamation continued

Theorem

(Onshuus) There is a rosy theory which does not have consistent 3-amalgamation.

The example he constructs is a variation of Hrushovski's *ab initio* construction, and has U -thorn-rank 1, but it is not dependent.






Conjecture

If T is rosy and NIP, then T has consistent 3-amalgamation.

Question

What about consistent n -amalgamation?

Works cited

-  Tristram De Piro, Byunghan Kim, and Jessica Millar, “Constructing the hyperdefinable group from the group configuration,” preprint.
-  Clifton Ealy and Alf Onshuus, “Consistent amalgamation for thorn-forking,” in preparation.
-  John Goodrick and Alexei Kolesnikov, “Groupoids, covers, and 3-uniqueness,” preprint.
-  Ehud Hrushovski, “Groupoids, imaginaries, and finite covers,” preprint.
-  Byunghan Kim and Anand Pillay, “Simple theories,” *Ann. of Pure and Appl. Logic*, **88** (1997), 149-164.