

General-order observation-driven models

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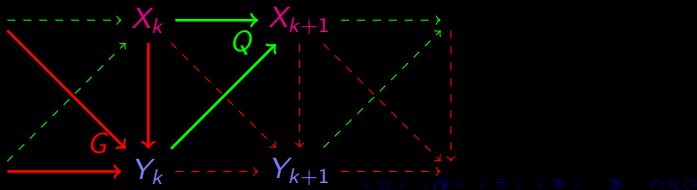
Partially observed Markov models

Definition (Partially observed Markov model (POMM))

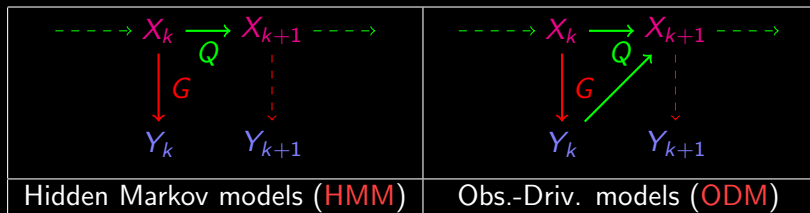
A **partially observed Markov** model with **latent space** $(\mathcal{X}, \mathcal{X})$ and **observation space** $(\mathcal{Y}, \mathcal{Y})$ is a pairwise homogeneous Markov chain $((Y_n, X_n), \mathcal{F}_n)_{n \geq 0}$ with kernel \mathbf{K}^θ , $\theta \in \Theta$, generally described as

$$\begin{aligned} Y_k | \mathcal{F}_{k-1}, X_k &\sim G^\theta(X_{k-1}, Y_{k-1}, X_k; \cdot), \\ X_{k+1} | \mathcal{F}_k &\sim Q^\theta(X_k, Y_k; \cdot), \end{aligned} \quad (1)$$

and such that only the $\{Y_k\}$'s are observed.



Two important examples



- ▷ In both cases, $\{X_k\}$ is a **Markov chain**.
- ▷ An **ODM** moreover requires that

$$Q^\theta(X_k, Y_k; \cdot) = \delta_{\psi_{Y_k}^\theta(X_k)},$$

where δ_x denotes the Dirac mass at point x and, for all $y \in Y$,

$$\begin{aligned} \psi^\theta : Y \times X &\rightarrow X \\ (y, x) &\mapsto \psi_y^\theta(x). \end{aligned}$$

General-order ODM

For $m \leq n$, denote $Z_{m:n} := (Z_m, Z_{m+1}, \dots, Z_n)$.

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Definition (ODM(p, q))

Let $p, q \geq 1$ and, for all $\theta \in \Theta$,

$$\begin{aligned} \psi^\theta &: Y^p \times X^q \rightarrow X \\ (\mathbf{y}, \mathbf{x}) &\mapsto \psi_{\mathbf{y}}^\theta(\mathbf{x}). \end{aligned}$$

An ODM of order (p, q) with link function ψ^θ and observation kernel G^θ satisfies, for all $k \in \mathbb{N}$,

$$\begin{aligned} X_{k+1} &= \psi_{Y_{(-p+1+k):k}}^\theta (X_{(-q+1+k):k}), \\ Y_{k+1} | \mathcal{F}_k, X_{k+1} &\sim G^\theta(X_{k+1}; \cdot). \end{aligned} \tag{2}$$

where $\mathcal{F}_k = \sigma(Y_{-p+1}, \dots, Y_k, X_{-q+1}, \dots, X_k)$.

Definition (Linear ODM (LODM))

A **linear ODM** (LODM) is an ODM

- ▷ with parameters $\theta = (\vartheta, \varphi)$ with $\vartheta = (\omega, \mathbf{a}_{1:p}, \mathbf{b}_{1:q}) \in \mathbb{R}^{1+p+q}$,
- ▷ with $X \subseteq \mathbb{R}$ and link functions of the form

$$\psi^\theta : Y^p \times X^q \rightarrow X$$

$$(y_{1:p}, x_{1:q}) \mapsto \psi_y^\theta(\mathbf{x}) = \omega + \sum_{k=1}^p a_k v(y_k) + \sum_{k=1}^q b_k x_k, \quad (3)$$

where $v : Y \rightarrow \mathbb{R}$.

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If $X = \mathbb{R}_+$, set $(\omega, a_{1:p}, b_{1:q}) \in \mathbb{R}_+^{1+p+q}$ and $v : Y \rightarrow \mathbb{R}_+$.

Examples of LODM

- ▷ GARCH(p, q), Bollerslev [1986]:

$$X = \mathbb{R}_+, \quad G^\theta(x; \cdot) = \mathcal{N}(0, x) \quad \text{and} \quad v(y) = y^2.$$

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Note that, transforming the observations, we can take $v(y) = y$, but it modifies the definition of G^θ .

Domination

- ▷ In contrast to HMMs, ODMs are **not fully dominated**: $\mathbf{K}^\theta(x, \cdot)$ is not dominated by $(\mu \otimes \nu)$ for σ -finite measures μ and ν on X and Y , resp.
- ▷ We always assume that the ODM is **partially dominated**: there is a σ -finite measure ν on Y such that, for all $\theta \in \Theta$ and $x \in X$, $G^\theta(x, \cdot)$ is dominated by ν , and, moreover, the density $g^\theta(x; \cdot) = dG^\theta(x, \cdot)/d\nu$ satisfies, for all $y \in Y$,

$$g^\theta(x; y) > 0,$$

- ▷ To avoid a trivial case, ν is supposed to be **non-degenerate**, that is, its support contains at least two points.
- ▷ For LODMs, we assume the push measure $\nu \circ \nu^{-1}$ to be non-degenerate.

Embedding in an ODM(1,1)

Define $Z = Y^{p-1} \times X^q$ and for all $k \in \mathbb{N}$,

$$Z_k = (Y_{(k-p+1):(k-1)}, X_{(k-q+1):k}) \in Z .$$

▷ Then $(Y_k, Z_k)_{k \geq 0}$ is an ODM(1,1) with link function

$$\Psi^\theta : Y \times Z \rightarrow Z$$

$$(y, z) \mapsto \Psi_y^\theta(z) = \psi_{(y,y)}^\theta(x) \quad \text{where } z = (y, x) .$$

▷ Given an initial distribution η on Z , we denote by \mathbb{P}_η^θ the distribution of $\{X_k, k > -q, Y_\ell, \ell > -p\}$ when

$$(Y_{(-p+1):-1}, X_{(-q+1):0}) \sim \eta .$$

Likelihood

▷ For any $m \in \mathbb{N}$ and $y_{0:m-1} \in Y^m$, define

$$\Psi^\theta \langle y_{0:m-1} \rangle = \Psi_{y_{m-1}}^\theta \circ \dots \circ \Psi_{y_0}^\theta : Z \rightarrow Z, \quad (4)$$

$$\psi^\theta \langle y_{0:m-1} \rangle = \Pi_{p+q-1} \circ \Psi^\theta \langle y_{0:m-1} \rangle : Z \rightarrow X, \quad (5)$$

where $\Pi_j : Z \rightarrow Y$ or X denotes the projection over the j -th coordinate.

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- ▷ Then, for any arbitrary $z^{(i)} \in Z$ and observations $Y_{0:n}$, the (conditional) **log-likelihood** (given $Z_0 = z^{(i)}$) reads

$$L_{z^{(i)},n}^\theta := \sum_{k=0}^n \ln g^\theta \left(\psi^\theta \langle Y_{0:(k-1)} \rangle (z^{(i)}); Y_k \right). \quad (6)$$

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- ▷ Hence the log-likelihood, as well as its **derivatives**, can easily be computed using $O(n)$ operations.

Stationary distribution

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- ▷ A similar coupling argument yields β mixing properties for (Y_k) , see Doukhan and Neumann [2017].

Notation

Recall that, for all $\theta \in \Theta$ and initial distribution η on (Z, \mathcal{Z}) , \mathbb{P}_η^θ denotes the distribution of $\{Y_k, X_\ell : k > -p, \ell > -q\}$ for $Z_0 \sim \eta$.

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If the model is **ergodic**, i.e. there exists a unique probability measure η such that \mathbb{P}_η^θ is **shift-invariant**, we denote

- ▷ the stationary distribution extended on $((Y \times X)^{\mathbb{Z}}, (\mathcal{X} \otimes \mathcal{Y})^{\otimes \mathbb{Z}})$ by \mathbb{P}^θ ,
- ▷ the marginalization of \mathbb{P}^θ on $(Y^{\mathbb{Z}}, \mathcal{Y}^{\otimes \mathbb{Z}})$ by $\tilde{\mathbb{P}}^\theta$.

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Remark: when establishing ergodicity through a drift condition, we obtain some minimal finite moment condition, referred to as **(M)** in the following, for X_0 (and Y_0) under the stationary distribution.

- ▷ The Maximum Likelihood Estimator (MLE) $\hat{\theta}_{z^{(i)},n}$ is defined as

$$\hat{\theta}_{z^{(i)},n} \in \operatorname{argmax} \left\{ L_{z^{(i)},n}^{\theta} : \theta \in \Theta \right\} \quad (7)$$

for some arbitrary initial point $z^{(i)} \in Z$.

- ▷ In **well-specified** models, a standard **consistency** result consists in showing that

$$\lim_{n \rightarrow \infty} \hat{\theta}_{\eta,n} = \theta_{\star}, \quad \mathbb{P}^{\theta_{\star}}\text{-a.s.} \quad (8)$$

- ▷ and **asymptotic normality** consists in showing that

$$\sqrt{n}(\hat{\theta}_{z^{(i)},n} - \theta_{\star}) \xrightarrow{\mathbb{P}^{\theta_{\star}}} \mathcal{N}(0, \mathcal{J}^{-1}(\theta_{\star})) \quad (9)$$

where $\mathcal{J}(\theta_{\star})$ is a nonsingular $d \times d$ -matrix.

Asymptotic behavior of the likelihood

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This is done by approximating $Y_{0:(k-1)}$ by $Y_{-\infty:(k-1)}$, defined, in the case $k = 1$ by the **backward** limit

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Let (X, δ_X) and (Z, δ_Z) be **complete metric spaces** in such a way that $\Pi_{p+q+1} : Z \rightarrow X$ is 1-Lipschitz.

Uniform Lipschitz condition

By (4) and (5), $\delta_X(\psi^\theta \langle Y_{i:0} \rangle(z^{(i)}), \psi^\theta \langle Y_{i+1:0} \rangle(z^{(i)}))$ is bounded from above by

$$\left(\sup_{y \in Y^i, z, z'} \frac{\delta_Z(\Psi^\theta \langle y \rangle(z), \Psi^\theta \langle y \rangle(z'))}{\delta_Z(z, z')} \right) \delta_Z(\Psi^\theta \langle Y_{i+1} \rangle(z^{(i)}), z^{(i)}) .$$

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Define for all $i \in \mathbb{N}^*$,

$$\text{Lip}_i^\theta = \sup \left\{ \frac{\delta_Z(\psi^\theta \langle y \rangle(z), \psi^\theta \langle y \rangle(z'))}{\delta_Z(z, z')} : y \in Y^i, z, z' \in Z \right\} .$$

We use the following condition:

(A-1) For all $\theta \in \Theta$, we have $\text{Lip}_0^\theta < \infty$ and $\text{Lip}_n^\theta \rightarrow 0$ as $n \rightarrow \infty$,

Asymptotic behavior of the likelihood (cont.)

Under (A-1)+ (M), for all $\theta \in \Theta$, there exists a measurable function $\psi^\theta \langle \cdot \rangle : Y^{\mathbb{Z}^-} \rightarrow X$ such that for all $\theta, \theta_* \in \Theta$,

$$\begin{aligned} X_1 &= \psi^\theta \langle Y_{-\infty:0} \rangle && \mathbb{P}^\theta\text{-a.s.} \\ \psi^\theta \langle Y_{-\infty:0} \rangle &= \lim_{n \rightarrow \infty} \psi^\theta \langle Y_{-n:0} \rangle(z^{(i)}) && \tilde{\mathbb{P}}^{\theta_*}\text{-a.s.} \end{aligned}$$

Note that, under $\tilde{\mathbb{P}}^{\theta_*}$, we have that

- ▷ $y \mapsto p^\theta(y \mid Y_{-\infty:0}) := g^\theta(\psi^\theta \langle Y_{-\infty:0} \rangle; y)$ is a density w.r.t. ν
- ▷ $y \mapsto p^{\theta_*}(y \mid Y_{-\infty:0})$ is **the conditional density** of Y_1 given $Y_{-\infty:0}$.

Moreover, with some continuity conditions, for n large,

$$L_{z^{(i)},n}^\theta \approx \sum_{k=0}^n \ln p^\theta(Y_k \mid Y_{-\infty:(k-1)}) \quad \tilde{\mathbb{P}}^{\theta_*}\text{-a.s.} \quad (10)$$

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All these steps can be carried out for the previously mentioned models, with some restrictions on the parameter set Θ , sometimes appearing in technical conditions.

Consistency: missing steps

From the approximation in (10), we **only** get that

$$\lim_{n \rightarrow \infty} \Delta \left(\hat{\theta}_{z^{(i)}, n}, \Theta^* \right) = 0 \quad \tilde{\mathbb{P}}^{\theta_*} \text{-a.s.}, \quad (11)$$

where Δ is the metric on Θ and the **limit maximizing set** Θ^* is defined for all θ_* by

$$\Theta^* = \operatorname{argmax} \left\{ \tilde{\mathbb{E}}^{\theta_*} [\ln p^\theta(Y_1 | Y_{-\infty:0})] : \theta \in \Theta \right\}$$

To prove consistency, it remains to go through **two additional steps**:

- ▷ we need to show that (see Douc, Roueff, and Sim [2016] for any POMM)

$$\Theta^* = [\theta_*] := \left\{ \theta \in \Theta : \tilde{\mathbb{P}}^\theta = \tilde{\mathbb{P}}^{\theta_*} \right\}.$$

Then, with (11), we get **equivalence class consistency** (as introduced by Leroux [1992]).

- ▷ To conclude, find conditions to have that $[\theta_*] = \{\theta_*\}$. (So that the model restricted to these θ_* s is **identifiable**).

Identifiability: basic assumption on the observation kernel

We suppose that the **observation kernel** satisfies:

(A-2) We can write $\theta_\star = (\vartheta_\star, \varphi_\star)$ and, for all $\theta = (\vartheta, \varphi)$ in Θ and $x, x' \in X$,

$$G^\theta(x; \cdot) = G^{\theta_\star}(x'; \cdot) \quad \text{if and only if} \quad \varphi = \varphi_\star \quad \text{and} \quad x = x' .$$

(i.e. φ is the part of the parameter θ that can be identified directly from the conditional distribution of one observation)

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We suppose that the **observation kernel** satisfies:

(A-3) We can write $\theta_\star = (\vartheta_\star, \varphi_\star)$ and, for all $\theta = (\vartheta, \varphi)$ in Θ and $x, x' \in X$,

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Denote by $[\theta_\star]$ the **equivalence class**:

$$[\theta_\star] = \left\{ \theta \in \Theta : \tilde{\mathbb{P}}^\theta = \tilde{\mathbb{P}}^{\theta_\star} \right\}$$

Identifiability: a general result

We have the following result.

Theorem

Consider an **ergodic** ODM(p, q) satisfying (A-2). Suppose that, for all $\theta \in \Theta$, there exists $\psi^\theta \langle \cdot \rangle : Y^{\mathbb{Z}^-} \rightarrow X$ such that

$$X_1 = \psi^\theta \langle Y_{-\infty:0} \rangle \quad \mathbb{P}^\theta\text{-a.s.} \quad (12)$$

Then $[\theta_\star]$ coincides with the set of all $\theta = (\vartheta, \varphi_\star) \in \Theta$ such that

$$\psi^\theta \langle Y_{-\infty:0} \rangle = \psi^{\theta_\star} \langle Y_{-\infty:0} \rangle \quad \tilde{\mathbb{P}}^{\theta_\star}\text{-a.s.},$$

$$\psi^\theta \langle Y_{-\infty:0} \rangle = \psi_{Y_{(-p+1):0}}^\theta \left(\left(\psi^\theta \langle Y_{-\infty:j} \rangle \right)_{-q \leq j \leq -1} \right) \quad \tilde{\mathbb{P}}^{\theta_\star}\text{-a.s.}$$

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Recall that (12) follows from (A-1)+(M), see [likelihood approx.](#)

Uniform Lipschitz assumption: the linear case.

For a **linear** link function (3) with $v(y) = y$,
Ass. (A-1) is equivalent to

(L-1) For all $\theta = (\vartheta, \varphi) \in \Theta$ with $\vartheta = (\omega, \mathbf{a}_{1:p}, \mathbf{b}_{1:q})$, we have
 $\mathbf{b}_{1:q} \in \mathcal{S}_q$,

where

$$\mathcal{S}_q := \left\{ \mathbf{c}_{1:q} \in \mathbb{R}^q : \forall z \in \mathbb{C}, |z| \leq 1 \text{ implies } 1 - \sum_{k=1}^q c_k z^k \neq 0 \right\} .$$

Identifiability: the linear case.

We have the following result.

Theorem

Consider an **ergodic** ODM(p, q) satisfying (L-1) and (A-2)+(M).
Then, for any $\theta_\star = (\omega^\star, a^\star_{1:p}, b^\star_{1:q}, \varphi^\star)$ in the interior of Θ ,

$$[\theta_\star] = \{\theta_\star\} \quad \text{if and only if}$$

(L-2) The polynomials $P_p(\cdot; a^\star_{1:p})$ and $Q_q(\cdot; b^\star_{1:q})$ have no common complex roots,

where we defined

$$P_p(z; a_{1:p}) = \sum_{k=0}^{p-1} a_{k+1} z^{p-1-k}$$
$$Q_q(z; b_{1:q}) = z^q - \sum_{k=1}^q b_k z^{q-k}.$$

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- ▷ The same **identifiability** condition is valid in the general case of LODMs.
- ▷ **Open question**: GARCH(p, q) processes are known to be **regularly varying**. How can this be extended to **integer valued** cases ?

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